

## A NOVEL APPROACH TO DISCOVER UNMODELLED FEATURES IN GRAVITATIONAL WAVE SIGNALS

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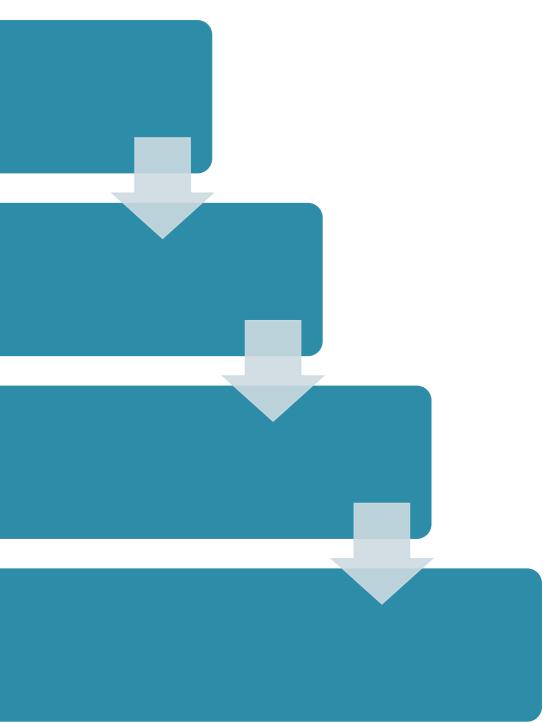
#### Gravitational signals from CBC

#### Parameter estimations

#### Residual analyses

#### Machine learning





## **GRAVITATIONAL WAVE** SIGNALS





#### Different sources: focus on CBC

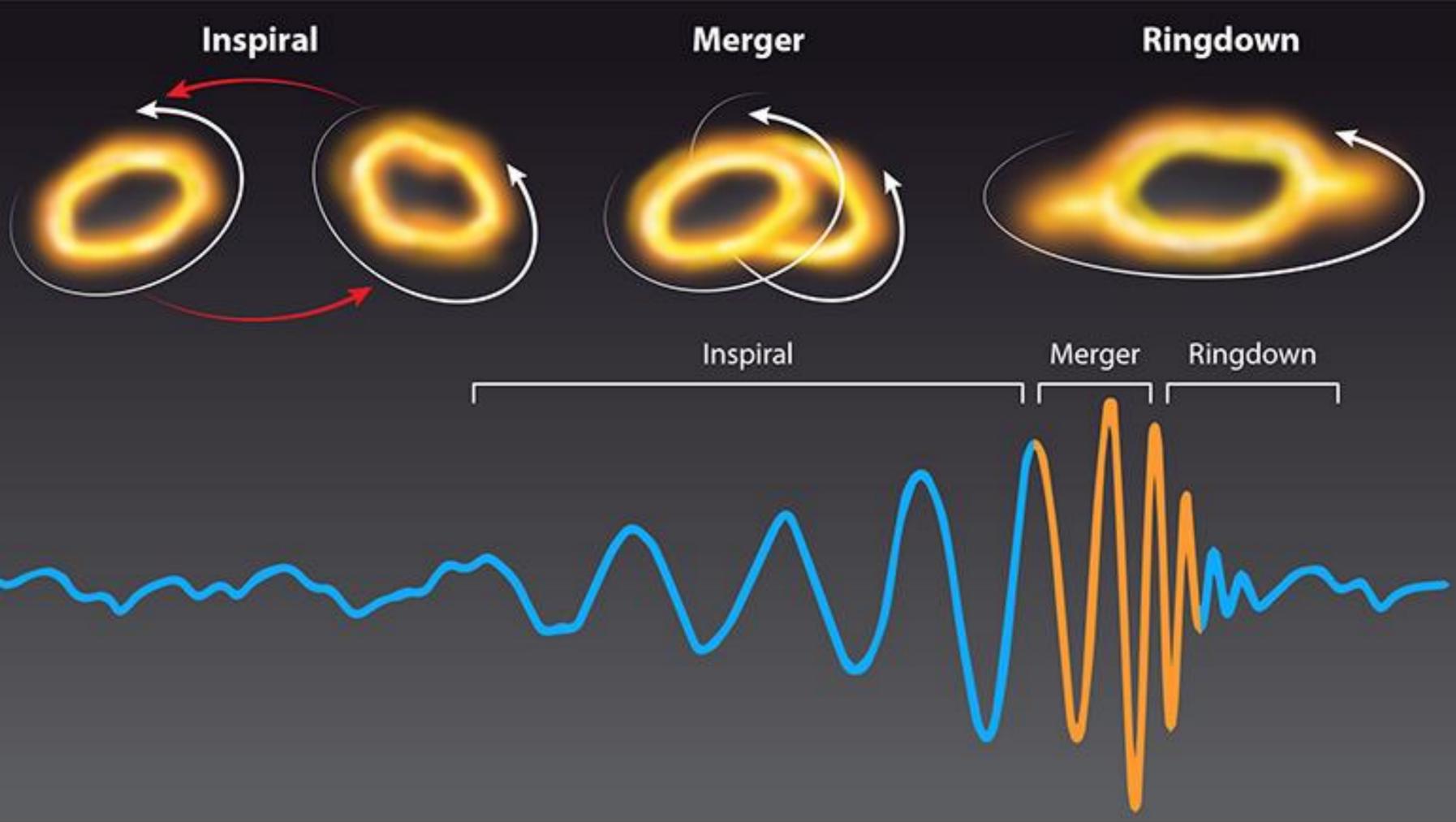
## Goal: find parameters of the objects

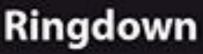
For example: masses, spin, position in the sky

Start with simulated signals

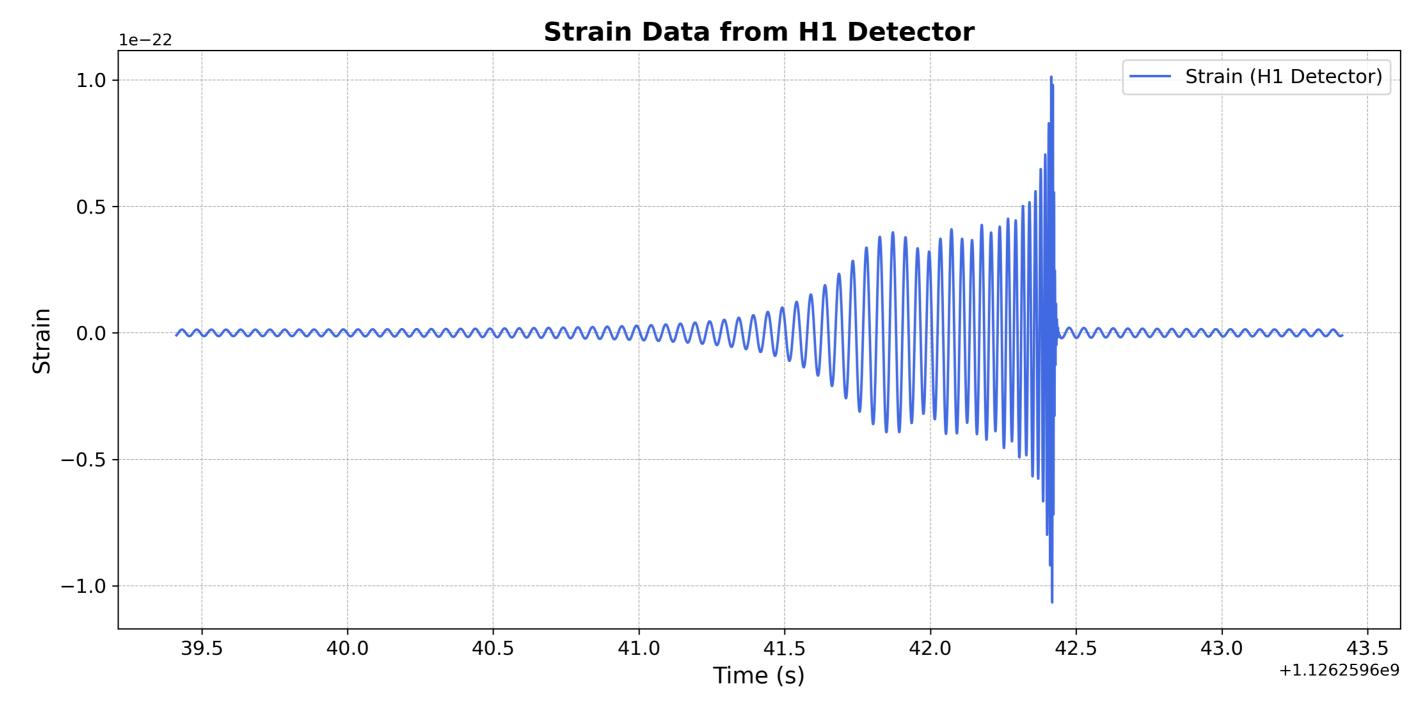






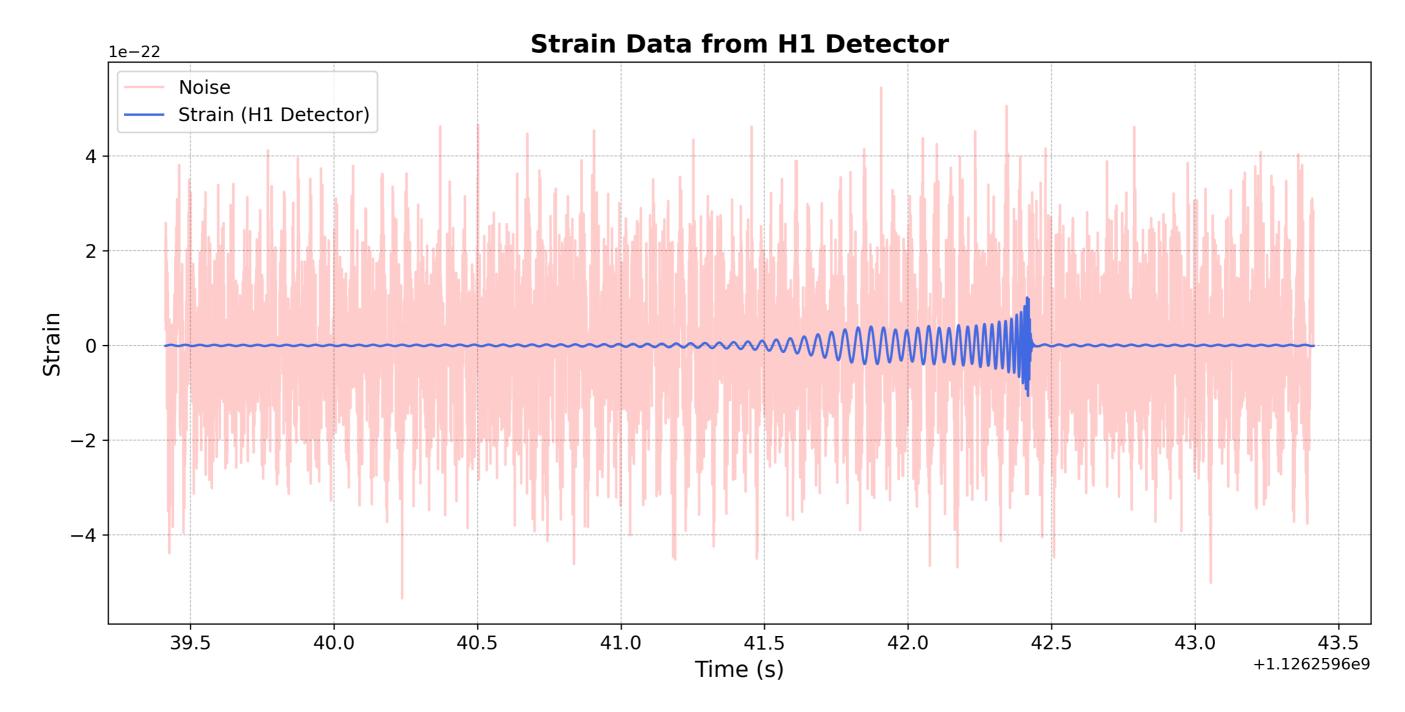


#### **SIMULATED SIGNAL**





#### ADDING THE NOISE





## PARAMETER ESTIMATION



#### **BAYESIAN PARAMETER ESTIMATION**

# Bilby

#### Result: posterior distribution





## $P(A | B) = \frac{P(B | A) P(A)}{P(B)}$

#### **BILBY WORKFLOW**

## • Inference: figuring out the model parameters $\theta$ given some model M

Injecting signal and noise into bilby Choose model with parameters

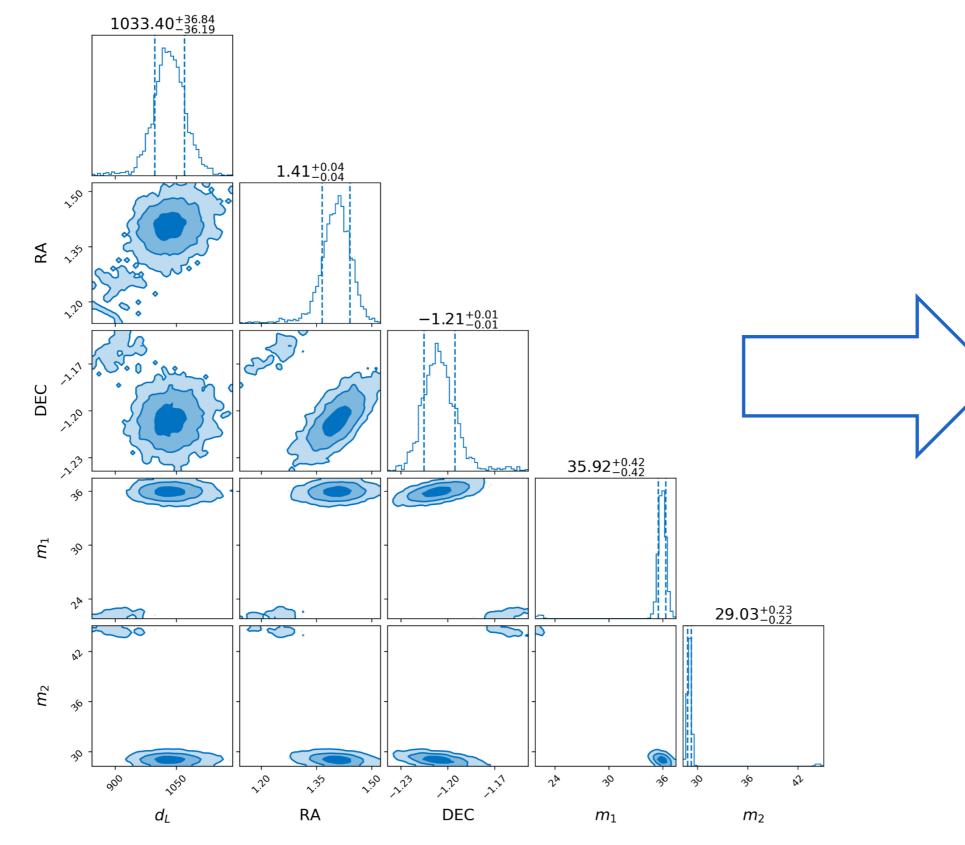
Monte Carlo Markov chain





Returns Posterior distribution

#### **POSTERIOR DISTRIBUTION**



GHENT UNIVERSITY

$$m_1 = \cdots$$
$$m_2 = \cdots$$
$$DEC = \cdots$$
$$RA = \cdots$$

#### **PROBLEMS WITH PARAMETER ESTIMATIONS**

- Advancing detectors 

   More data
- Curse of dimensionality 
   → long runtimes
- Less advanced waveforms 

   less parameters
- Sounds nice but is it still good enough?
- To check this, create ML algorithm





## **RESIDUAL ANALYSES**





#### <u>GOING TO THE RESIDUAL</u>

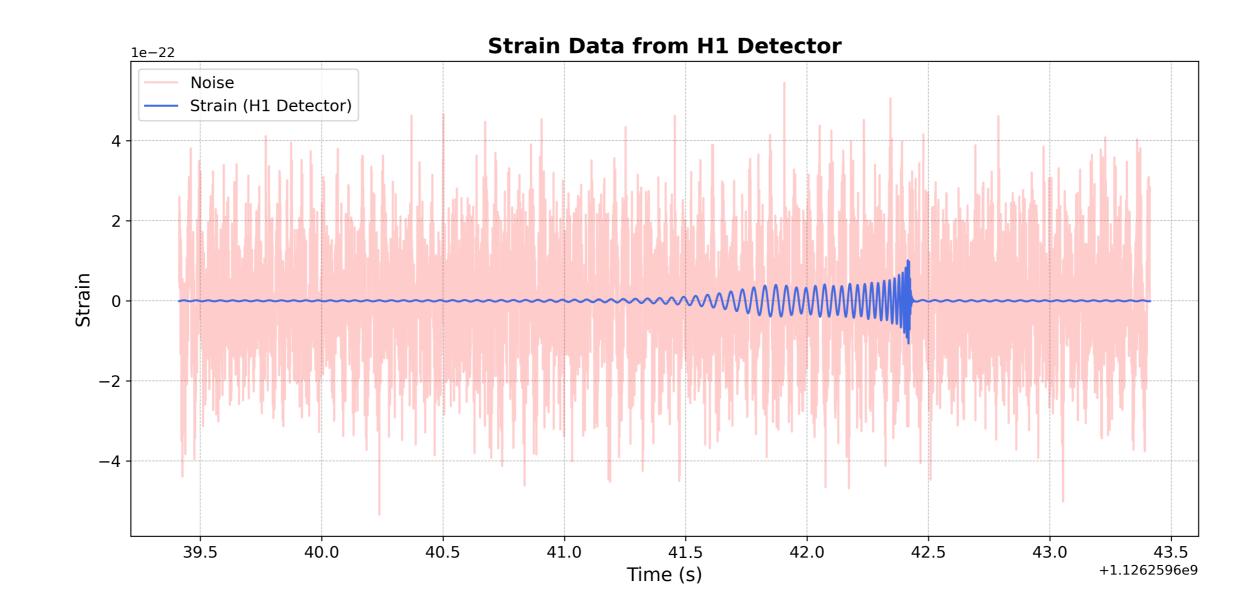
#### Extract best parameters

### Residual = Observed Data-Best-fit Signal

#### Depends on waveform

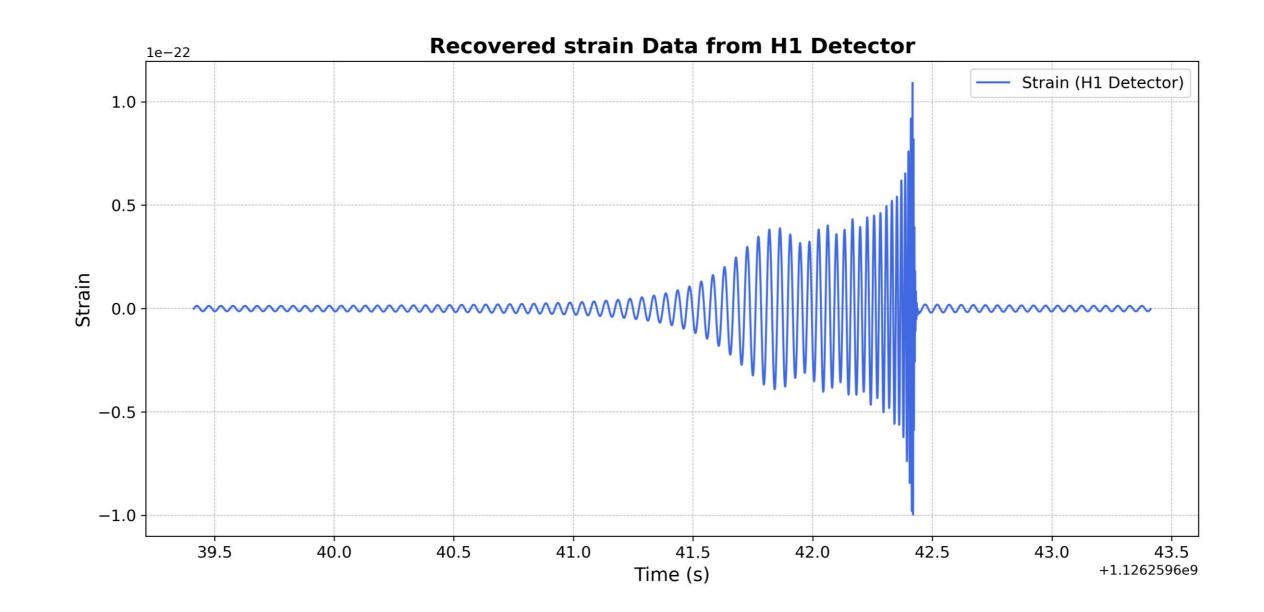


#### **ORIGINAL SIGNAL**



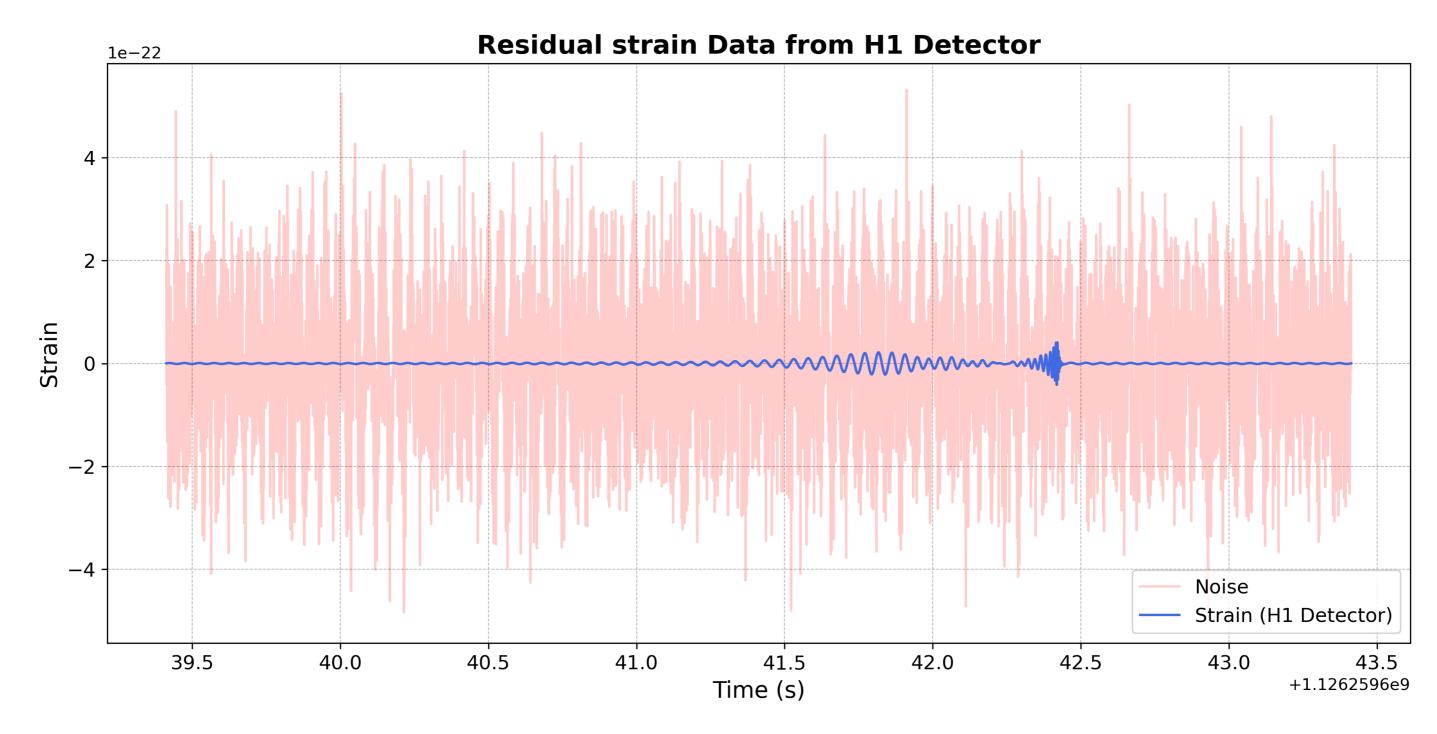


#### **RECOVERED SIGNAL**





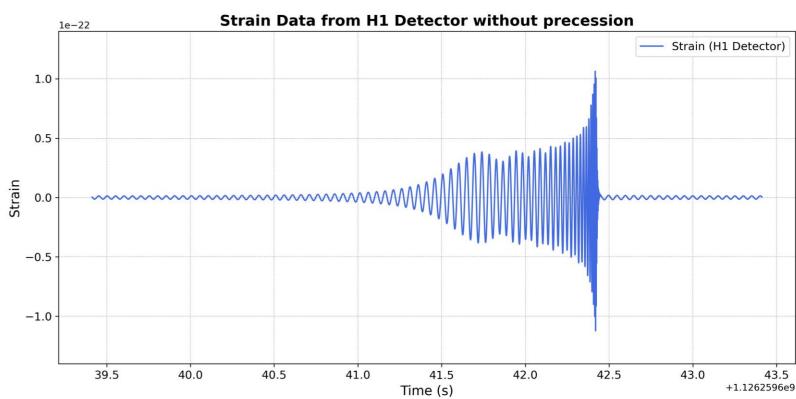
#### **RESIDUAL**

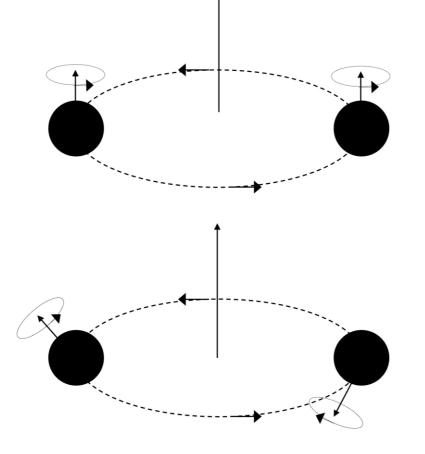


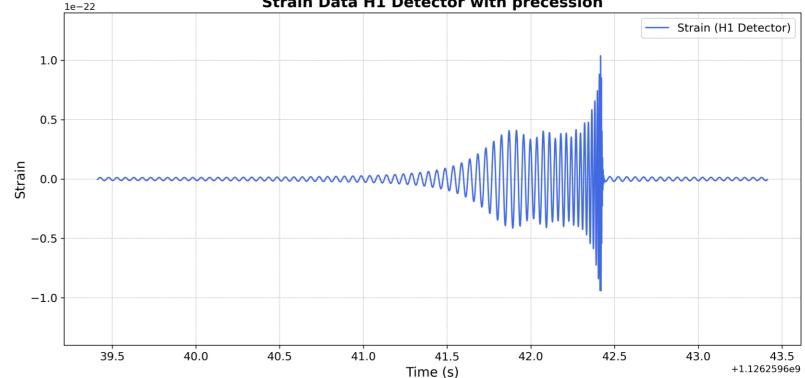


#### **DIFFERENT WAVEFORMS**

- Gravitational wave features:
  - Precession
  - Higher-Order Modes
  - Other exotic features



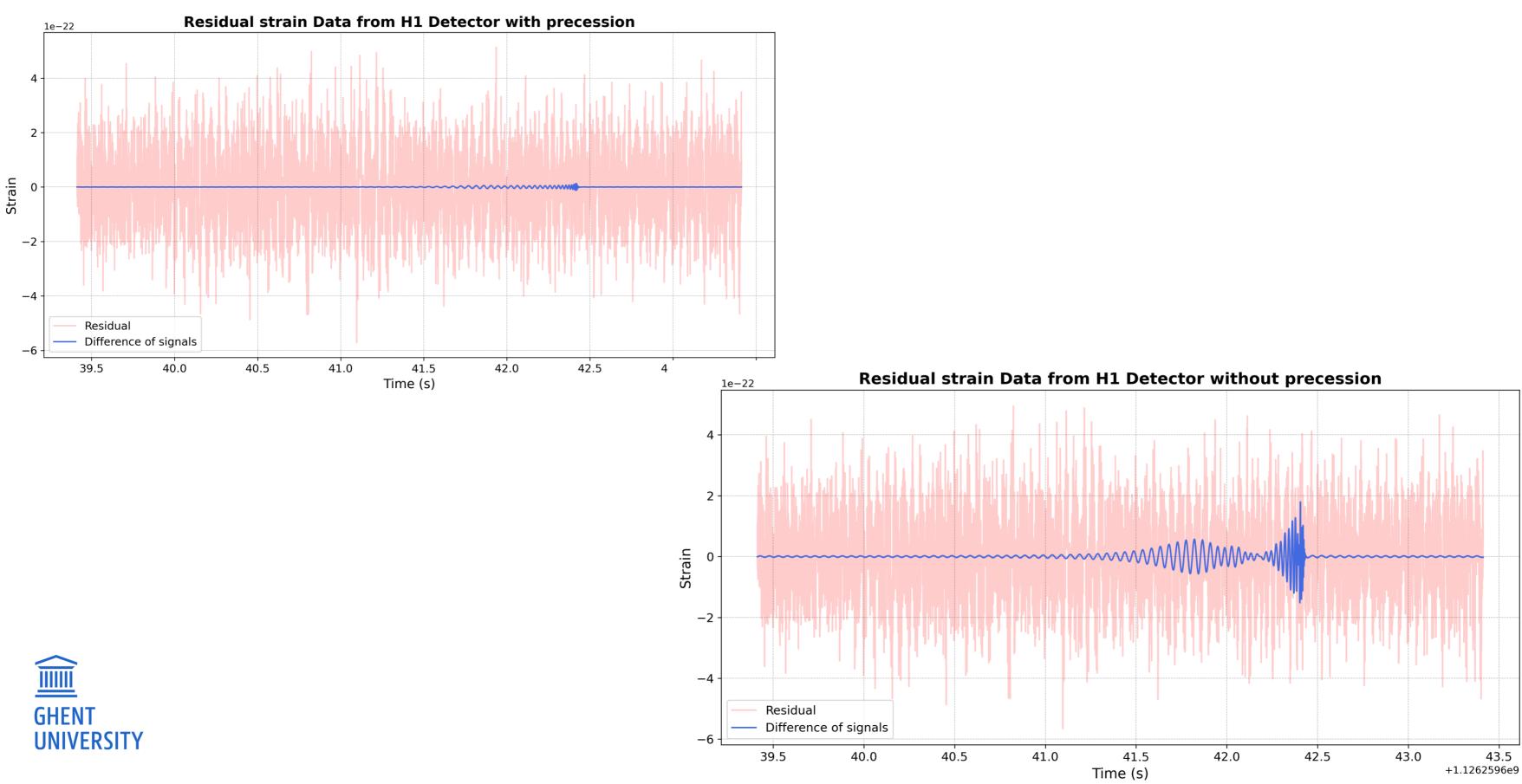




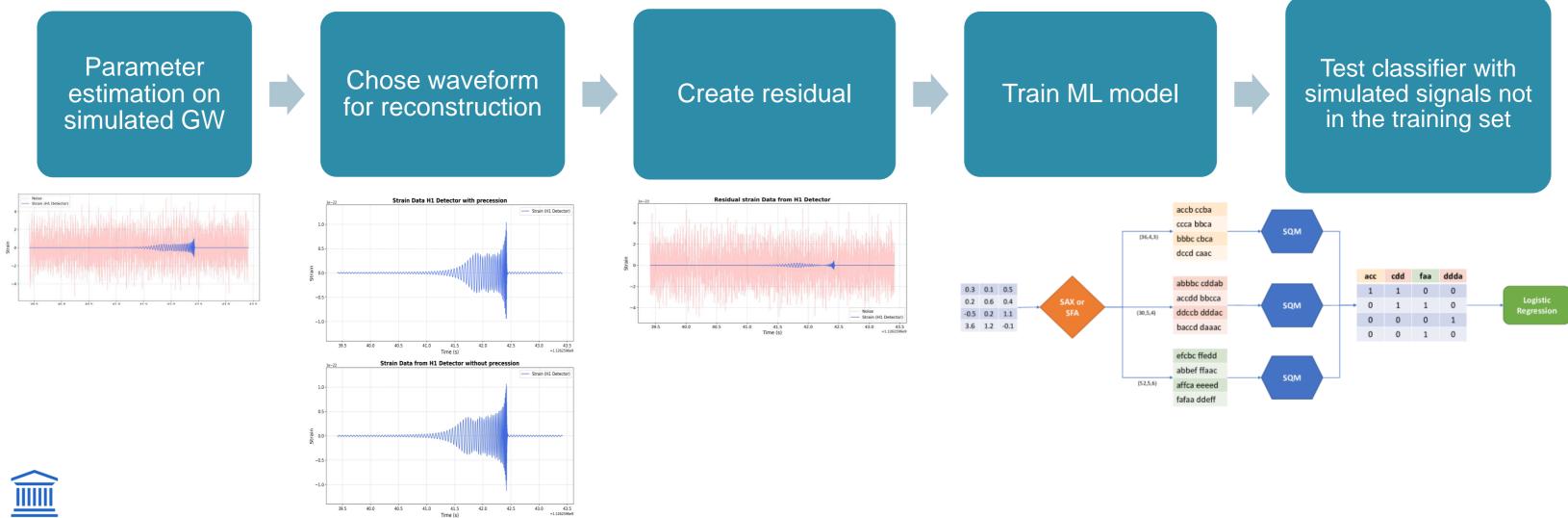


Strain Data H1 Detector with precession

#### **DIFFERENCE IN RESIDUAL**



#### FIRST STEP





40.0

40.5



### Experimenting with different ML algorithms

#### Extending to more features

#### Unmodelled features

