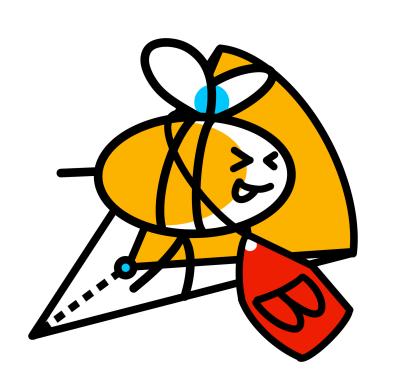






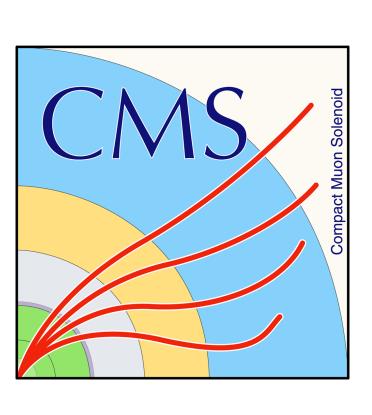
# Deep Learning for jets: towards a unified jet algorithm

Alexandre De Moor







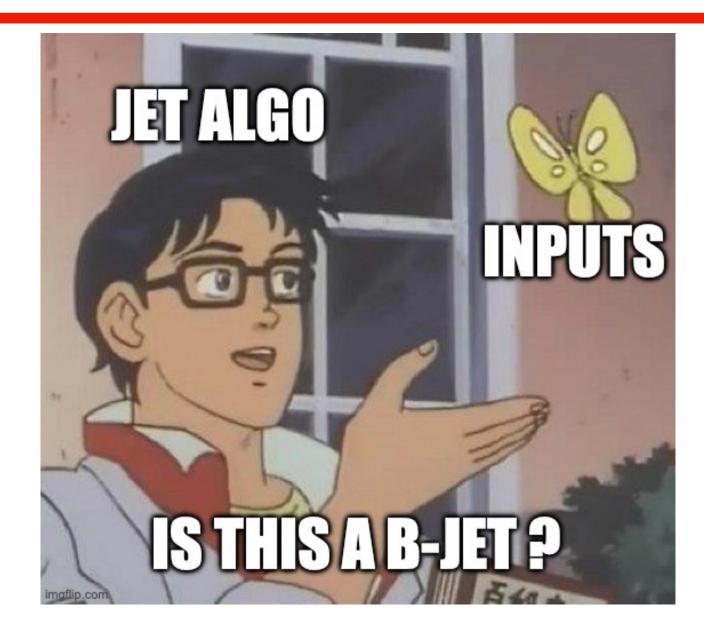




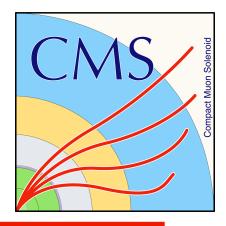




1. Jet tagging 101: what is a jet and Deep Learning?





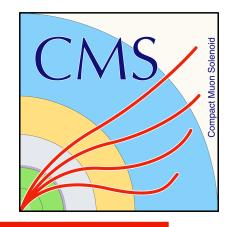


1. Jet tagging 101: what is a jet and Deep Learning?

2. Jet algorithm evolution: from likelihood ratio to Transformer models



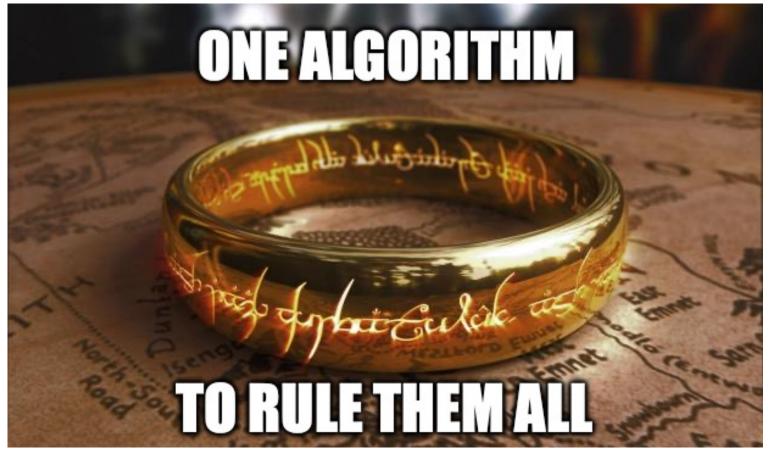




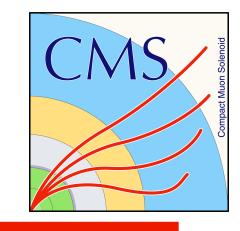
1. Jet tagging 101: what is a jet and Deep Learning?

2. Jet algorithm evolution: from likelihood ratio to Transformer models

3. Unified Jet approach: everyone joins the tagging battle!





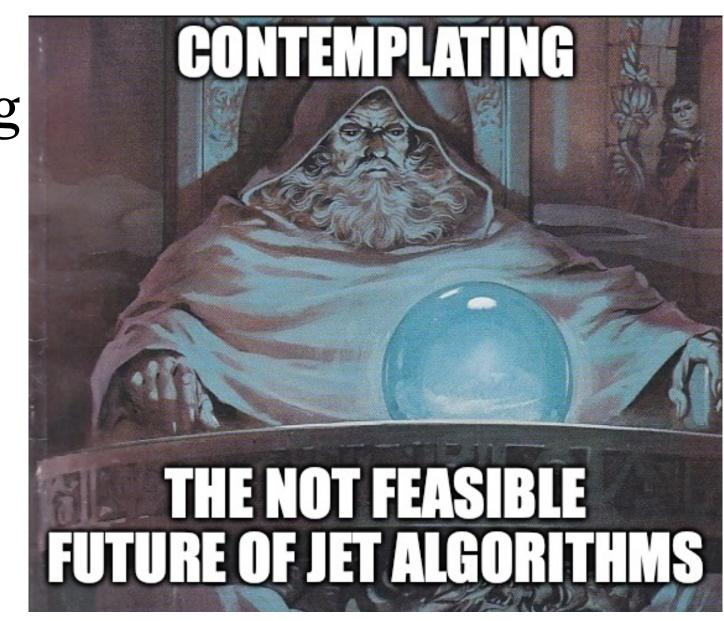


1. Jet tagging 101: what is a jet and Deep Learning?

2. Jet algorithm evolution: from likelihood ratio to Transformer models

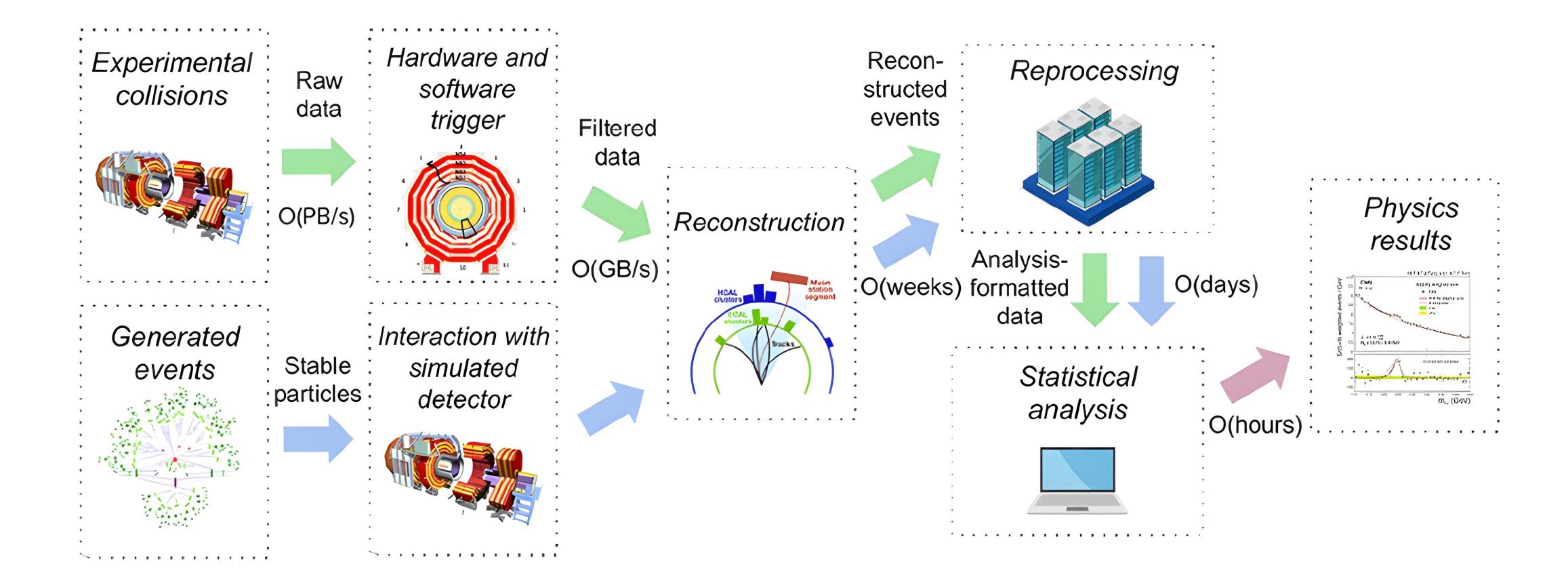
3. Unified Jet approach: everyone joins the tagging

4. What's next: towards fully unified world models







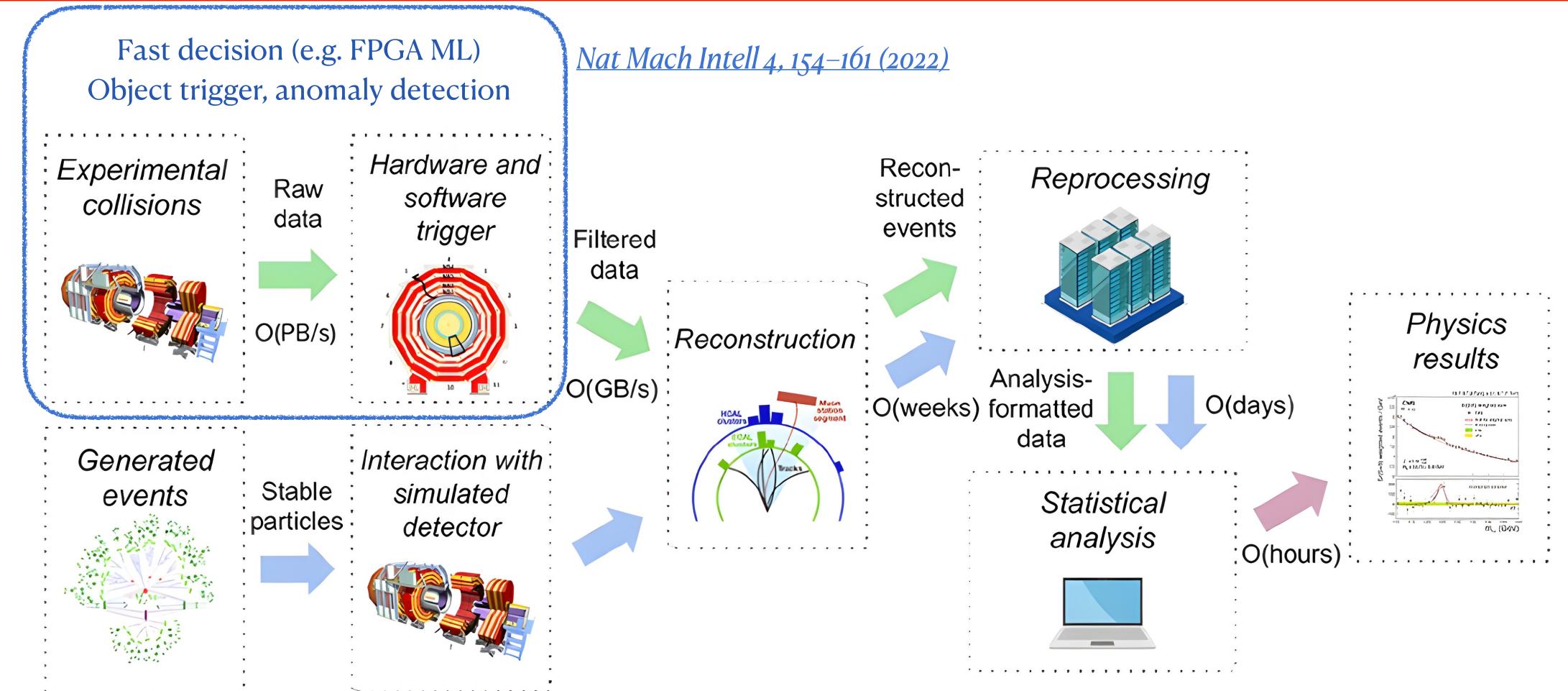


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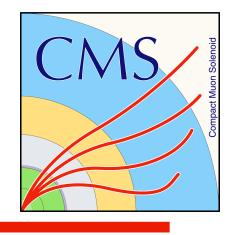






Front.Big Data 4 (2021) 661501

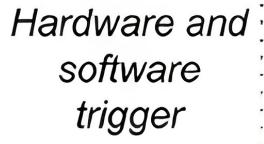




Fast decision (e.g. FPGA ML) Object trigger, anomaly detection

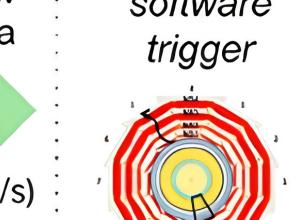
Experimental: collisions

Raw data

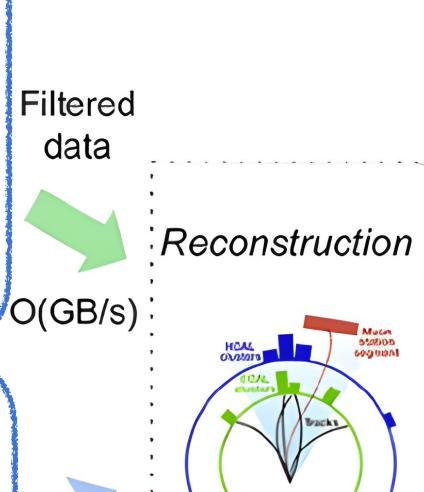




Stable

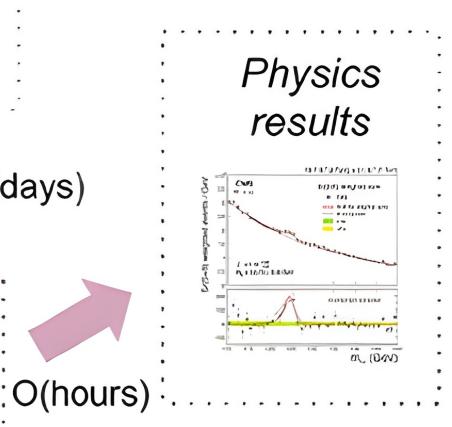




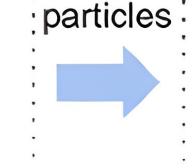


Recon-Reprocessing structed events Analysis-O(days) :O(weeks) formatted data Statistical

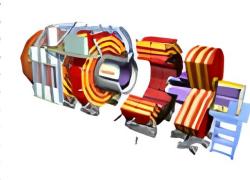
analysis



Generated events



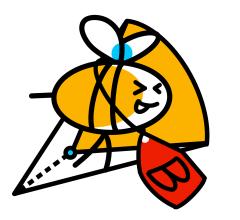
Interaction with: simulated detector

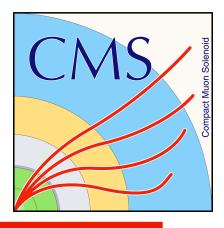


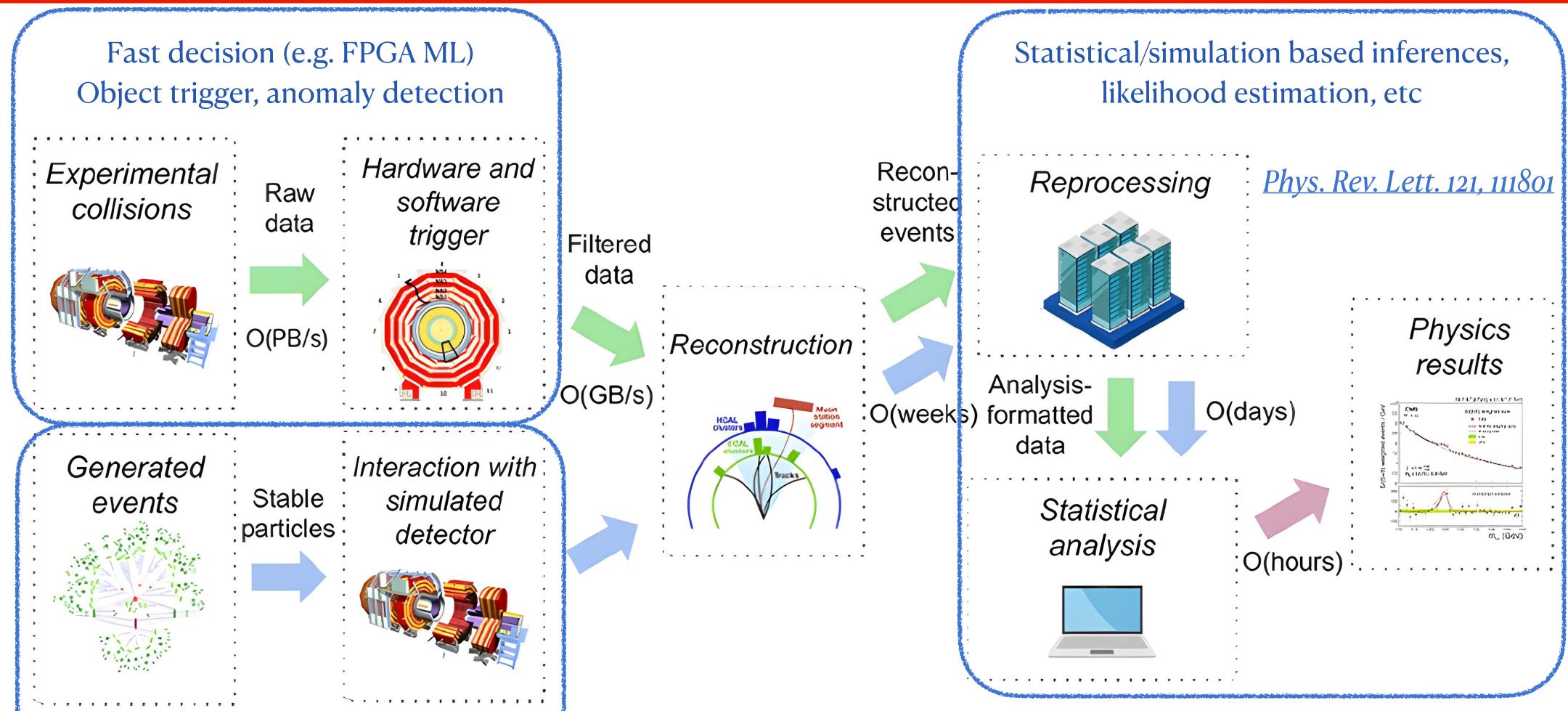
Generative models (GAN/VAE, Diffusion, Norm. Flows)

SciPost Phys. 18, 195 (2025)

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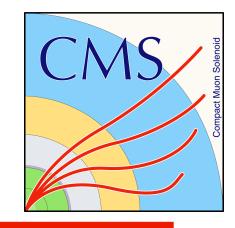
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25/11/2025

Generative models (GAN/VAE,

Diffusion, Norm. Flows)

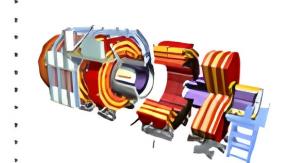




Fast decision (e.g. FPGA ML)
Object trigger, anomaly detection

Experimental : collisions

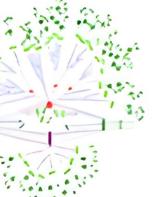
Raw data Hardware and software trigger



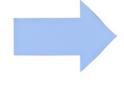


3/s)

Generated events



Stable particles



Interaction with simulated detector



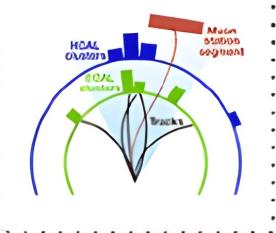
Generative models (GAN/VAE, Diffusion, Norm. Flows)

Today's discussion

Reconstructed events



Reconstruction

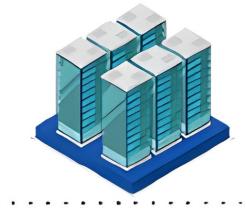


Jet algorithms, tau
reconstruction, tracking,
vertexing, lepton id.,
Particle-Flow, etc

Statistical/simulation based inferences, likelihood estimation, etc

O(days)

Reprocessing



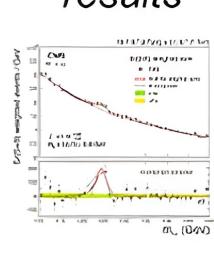
AnalysisO(weeks) formatted
data



Statistical analysis



Physics results

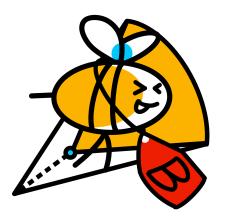


O(hours)

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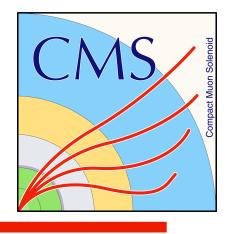
بخ

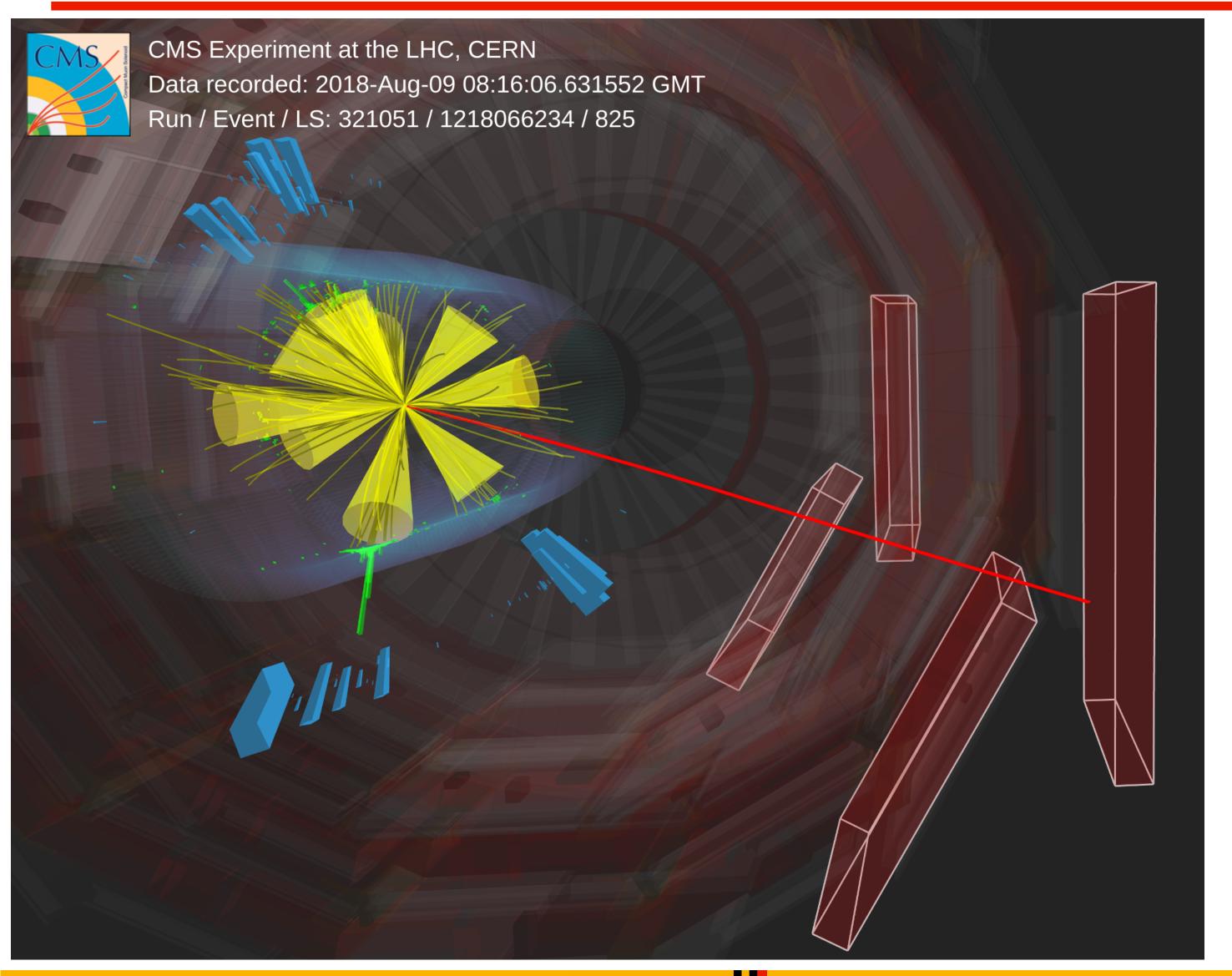
25/11/2025



25/11/2025

# Jet tagging 101: definitions





- Jet: a narrow cone of collimated stable particles
- Jet clustering: agglomeration law associating the stable particles into a jet (e.g. anti-kT)
- Jet's origin: Jet tagging
- Jet's properties : jet (energy) regression

Disclaimer: focus on small jet radius, but the discussion generalizes to large radius one too

CMS-PHO-EVENTS-2024-025

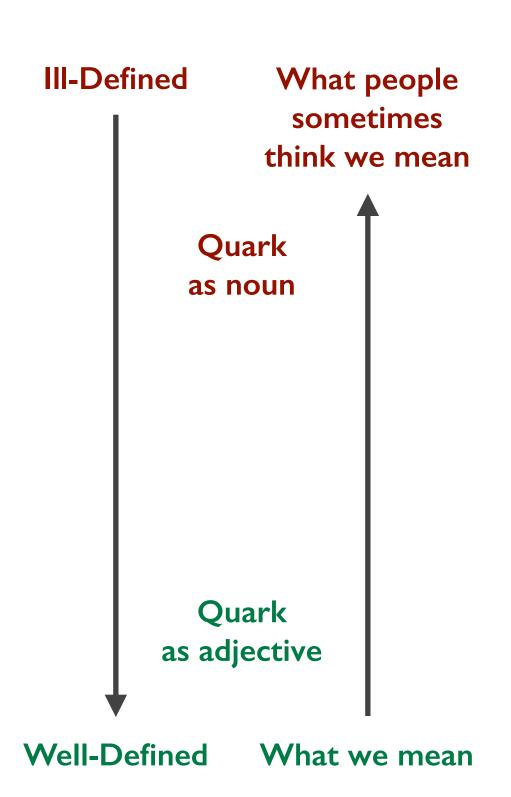


## Jet tagging 101: definitions



#### What is a Quark Jet?

From lunch/dinner discussions



A quark parton

A Born-level quark parton

The initiating quark parton in a final state shower

An eikonal line with baryon number 1/3 and carrying triplet color charge

A quark operator appearing in a hard matrix element in the context of a factorization theorem

A parton-level jet object that has been quark-tagged using a soft-safe flavored jet algorithm (automatically collinear safe if you sum constituent flavors)

A phase space region (as defined by an unambiguous hadronic fiducial cross section measurement) that yields an enriched sample of quarks (as interpreted by some suitable, though fundamentally ambiguous, criterion)

For quark jet: necessary to define the flavor of the originating quark or gluon

Jet flavor: A long and complex discussion (with still no consensus)

In CMS: defined via ghost hadron/ parton association

Jet Energy Correction (JEC): correct for detector response, pileup effects, and other biases.

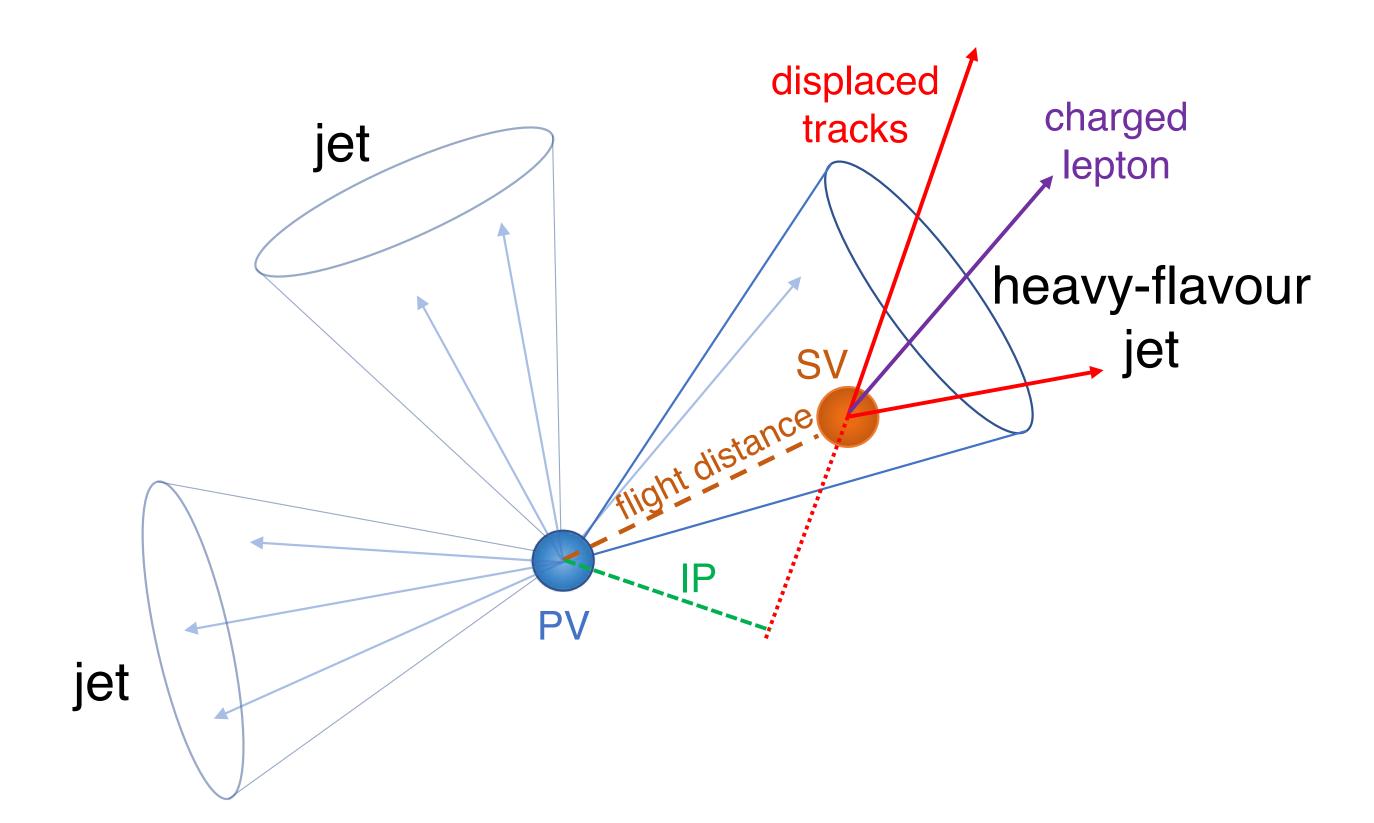
> Les Houches 1-19 June 2015 JINST 13 (2018) P05011

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# Jet tagging 101: signatures





Heavy flavor (b-c) jets: b (c) hadron with a sufficient lifetime, 1.5 (1.0) ps

- Creation of a secondary vertex (SV)
- Displaced tracks
- 20% (10%) of the b (c) jets containing a soft lepton from the heavy hadron decay

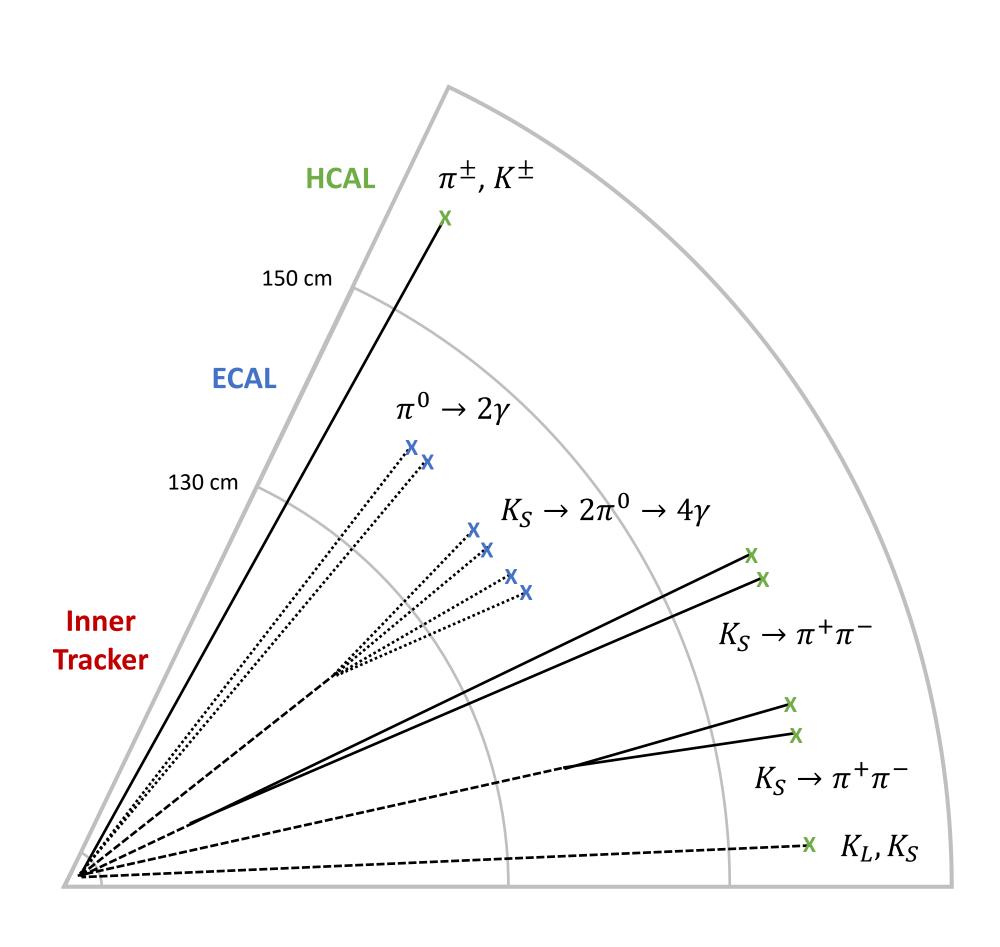
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# Jet tagging 101: signatures

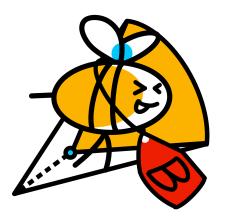




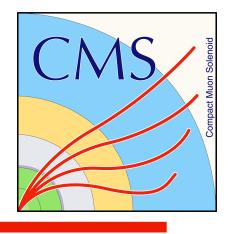
Strange jet: weaker signatures vs u-d jets

- Neutral composition of the jet and its energy
- Charged kaon identification not possible at our energy scale for CMS





## Deep Learning 101: ML



#### What is Machine Learning?

"Machine Learning is the science of getting computers to act without being explicitly programmed."

- Arthur Samuel, 1959

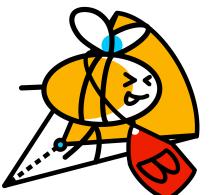
#### Key ingredients:

- Data and an objective: what and in which conditions?
- Objective (loss) function: mapping the prediction and the ground truth
- Learning strategies: how to adjust the prediction
- Structure: how to modelize the prediction from the inputs

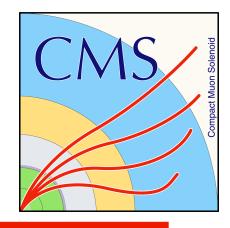
Only focus on ML with artificial neural networks (Deep Learning)

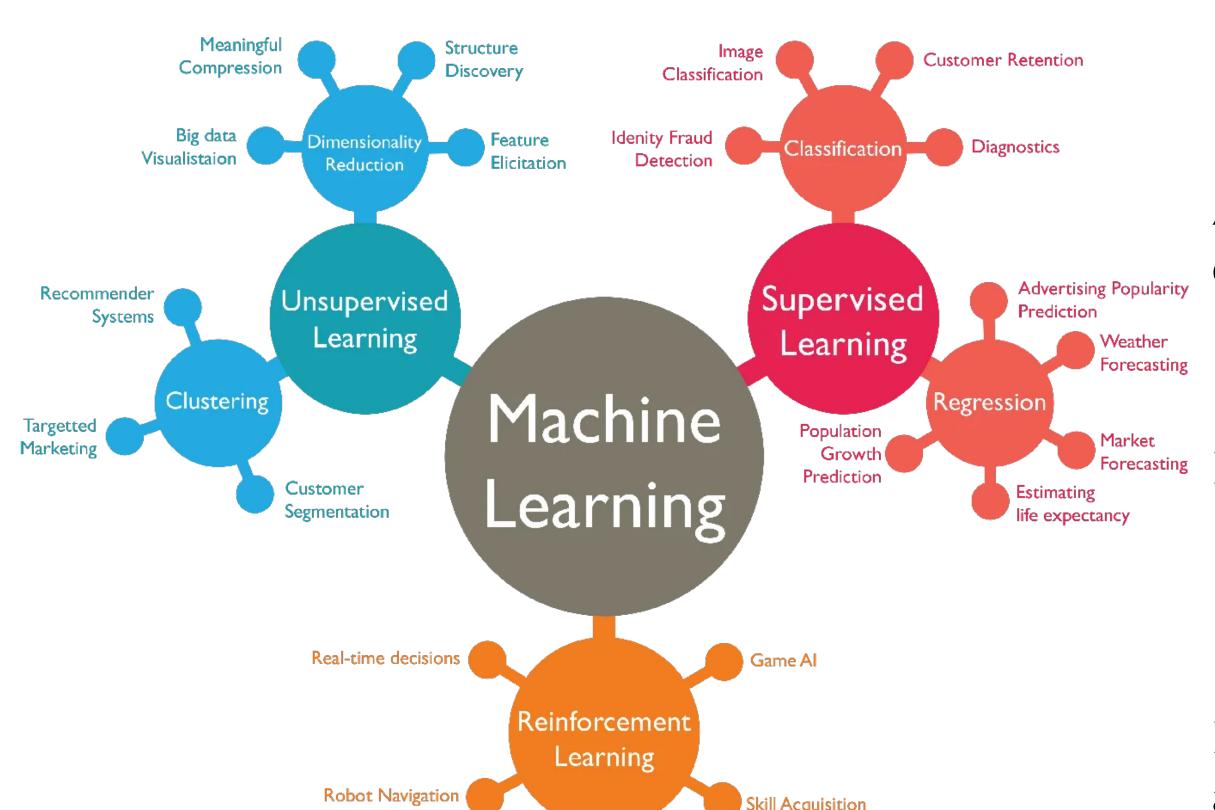


$$o_j^1(\bar{x}, \bar{W}^1) = a^1(\sum_i x_i W_{ij}^1 + b_j^1)$$



# Deep Learning 101: types of learning

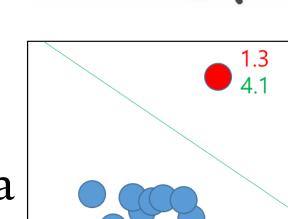




Learning Tasks

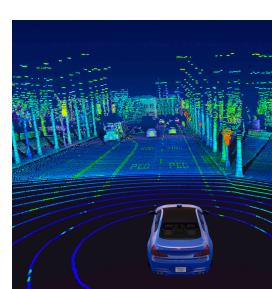
• Supervised learning (task specific model):

Assigned a task to predict an outcome from labelled data(classification or regression)



• Unsupervised learning (general model):

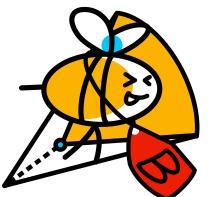
Discover patterns and properties from unlabeled data (LLMs, anomaly detection, etc)



• Reinforcement learning (acting model)

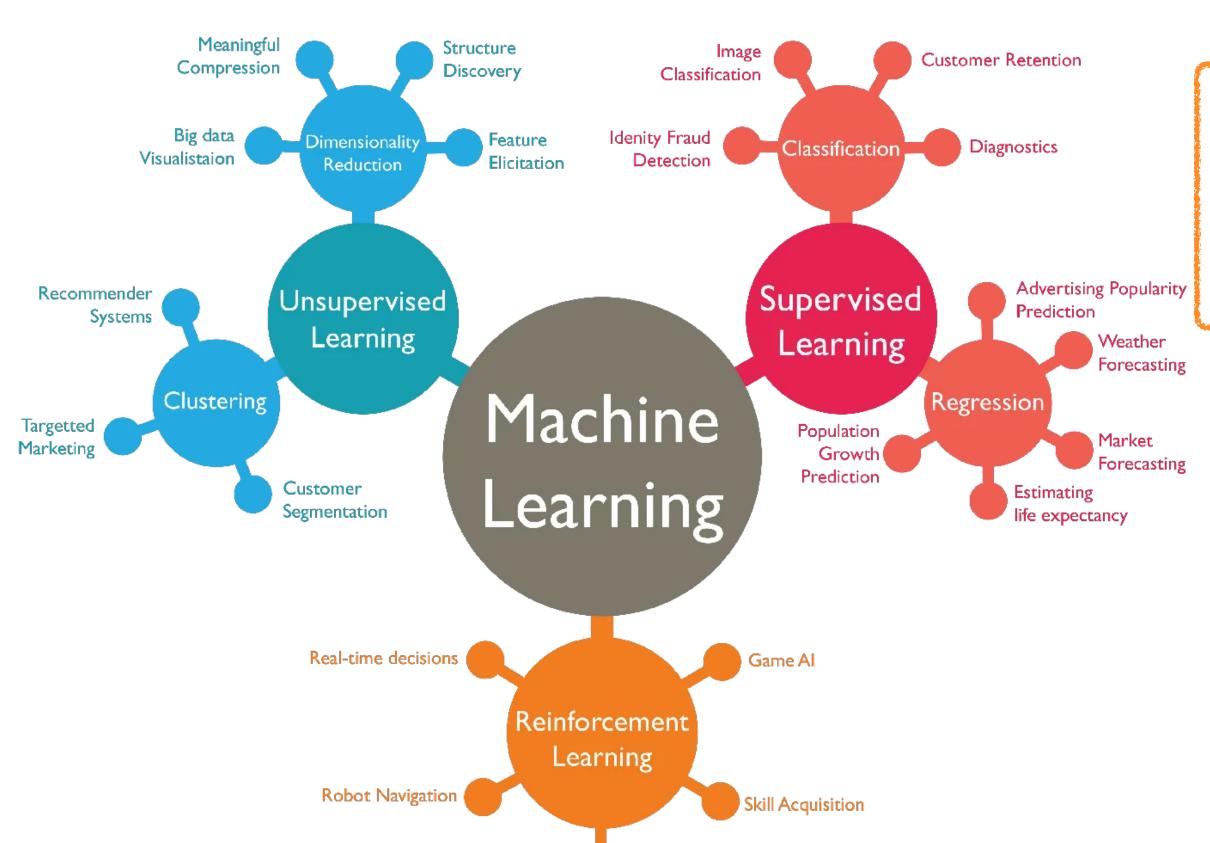
Decision making model, adjusting it's next move from a reward cost function (autonomous driving, Gaming, etc)

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# Deep Learning 101: types of learning





Learning Tasks

Today we stay in this area

• Supervised learning (task specific model):

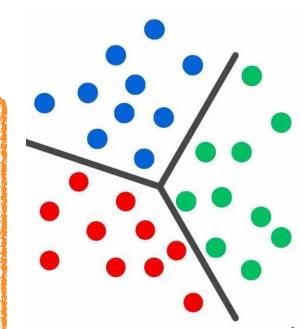
Assigned a task to predict an outcome from labelled data(classification or regression)

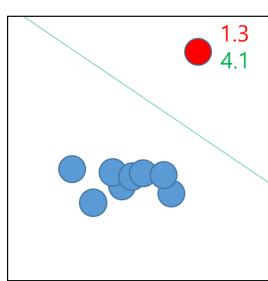
Unsupervised learning (general model):

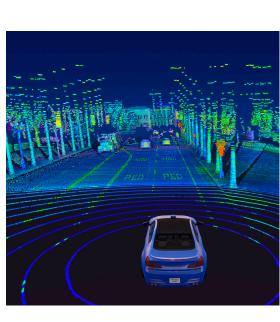
Discover patterns and properties from unlabeled data (LLMs, anomaly detection, etc)

• Reinforcement learning (acting model)

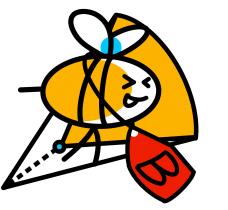
Decision making model, adjusting it's next move from a reward cost function (autonomous driving, Gaming, etc)



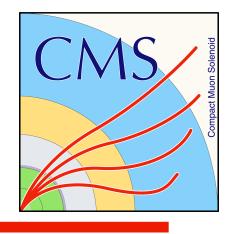




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# Deep Learning 101: Gradient descent



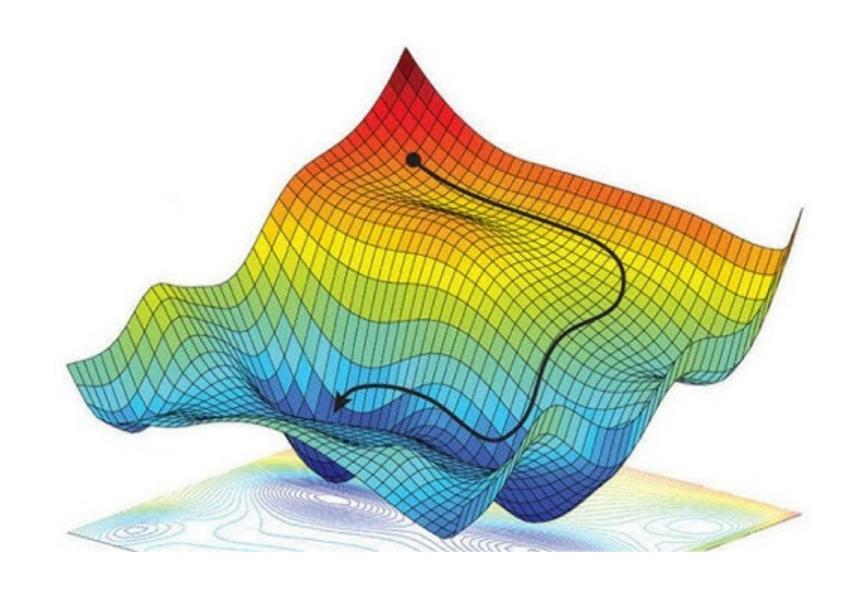
Core Concept: An iterative optimization algorithm for finding the minimum of a function by following the direction of steepest descent

**Physical Analogy:** Imagine releasing a ball on a mountainous landscape. The ball naturally rolls downhill, following the steepest slope at each point, until it reaches a valley—a local minimum

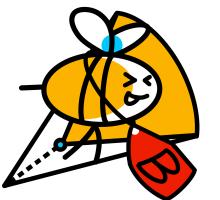
In gradient descent, the "landscape" is defined by a cost function L, and we iteratively update parameters by moving opposite to the gradient:

$$W_t = W_{t-1} - \lambda \cdot \frac{\partial \mathcal{L}}{\partial W_{t-1}}$$

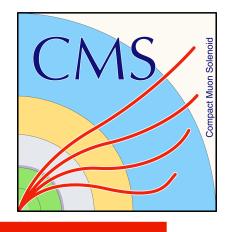
Key Insight: The learning rate  $\lambda$  controls step size—too large and we overshoot; too small and convergence is slow. The gradient provides local directional information, analogous to measuring the slope beneath the ball.



Foundation paper: <u>Nature 323, 533–536 (1986)</u>

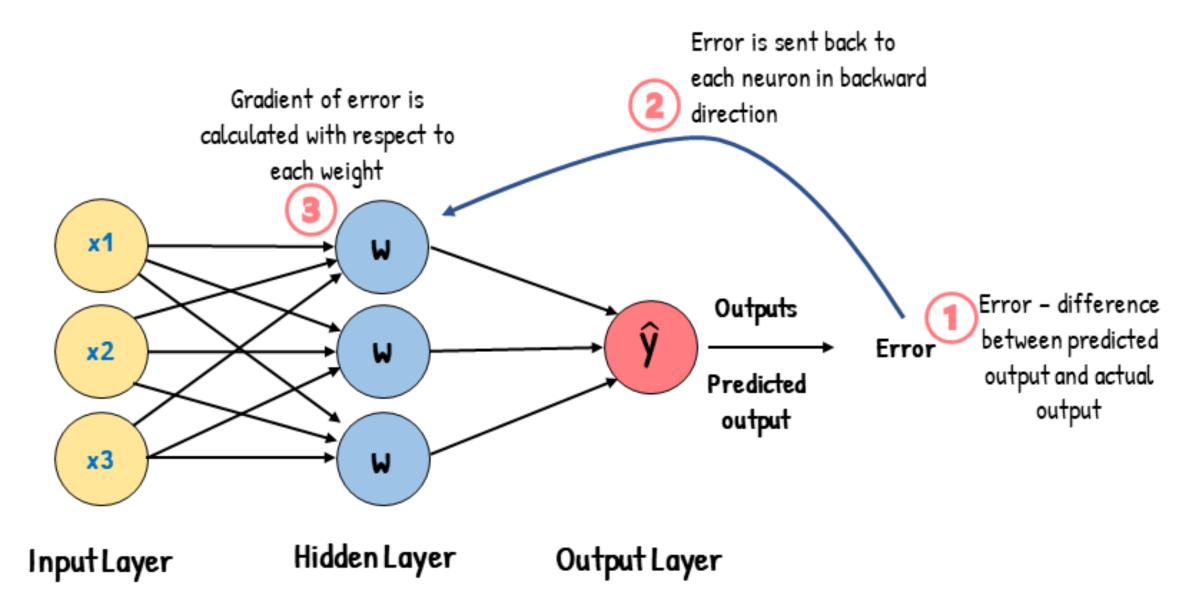


## Deep Learning 101: Gradient descent



Update of all the layers: Chain rules across the weights matrices and functions of the neural network structure - Backpropagation

#### Backpropagation



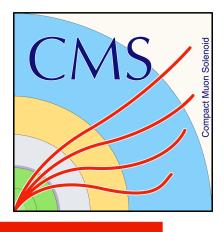


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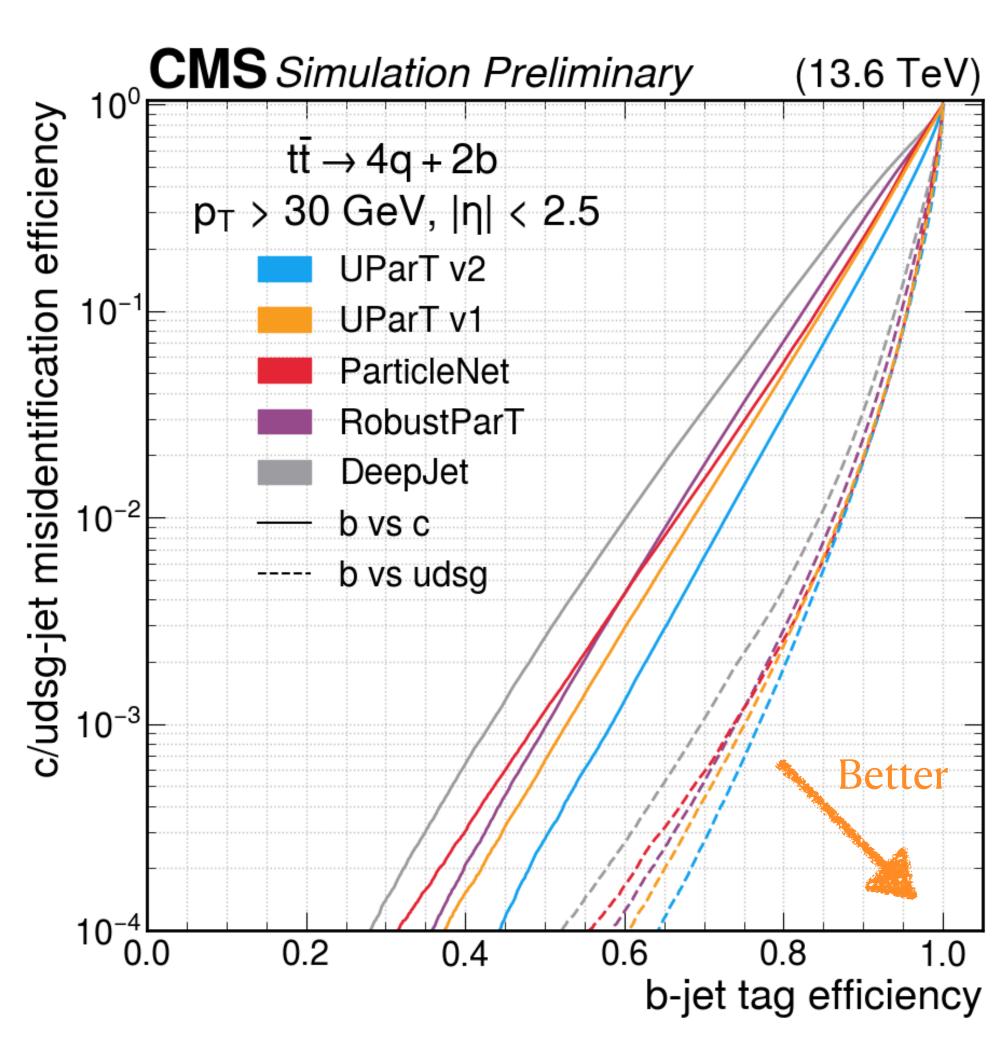




## The BTV rosetta stone



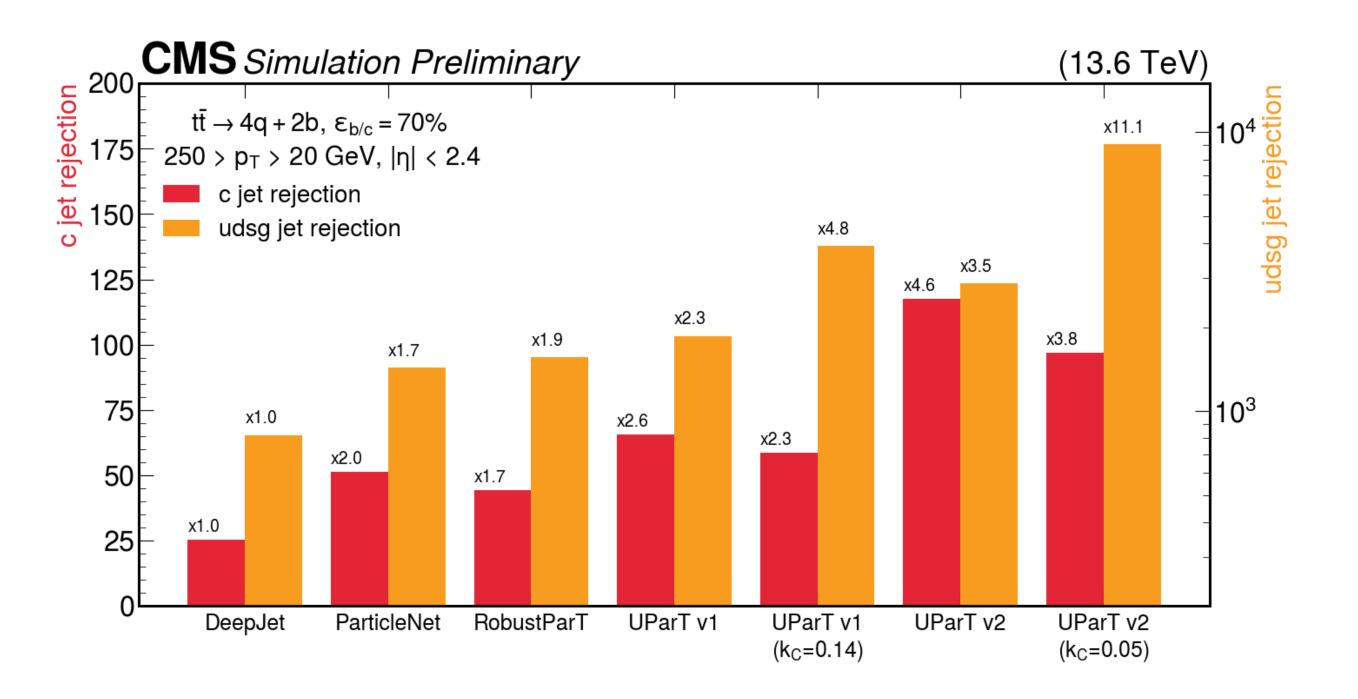




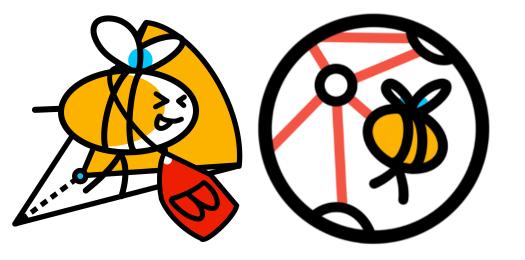
Two types of metrics:

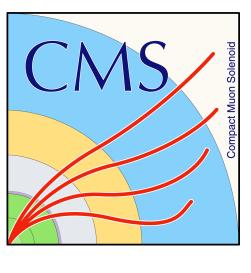
CMS-DP-2025-081

- Working points (WPs): signal efficiency at fixed background mis.id. rate
- Rejection rate: invert of the background mis.id. rate at a fixed signal efficiency



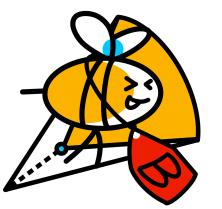
Sensitivity (1-Type II error)



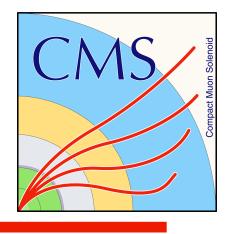


# Jet algorithm evolution: a matter of representation

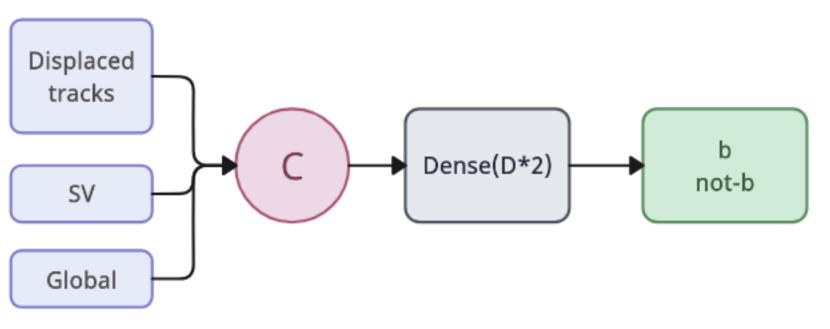
Low Complexity **High Complexity BDT MLP** DNN **RNN GNN Transformer Likelihood Ratio** P(x|S)P(x|B)~2010 ~2013 ~2014 ~2016 ~2017 ~2018 ~2020 Handcrafted Ensemble Shallow Deep learning Sequential Graph Attention features methods revolution data networks structures mechanism



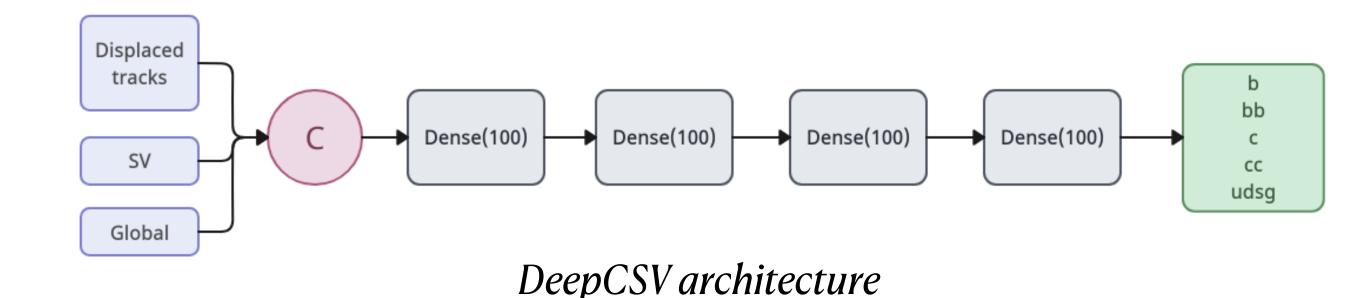
## Jet algorithms: a matter of representation



- The evolution of algorithms followed how we represented our jet inputs.
- First naïve approach use jet level inputs + handcrafted displaced tracks.
- ML methods used evolved from likelihood ratio (JetProbability algorithm) to Boosted Decision Tree/Shallow networks (Combined Secondary Vertex algorithms CSVs)
- First multi-layer DNN arrived at the end of this era: DeepCSV



CSVv2 architecture



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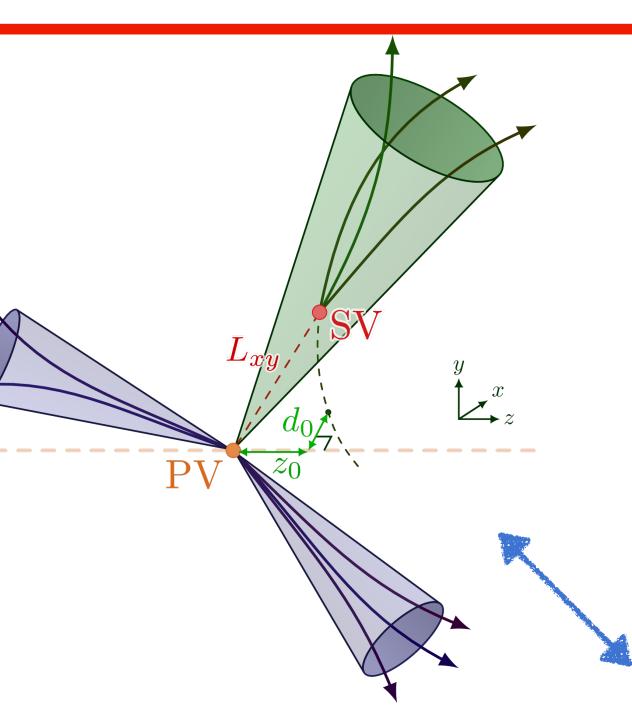
## Jet as an image



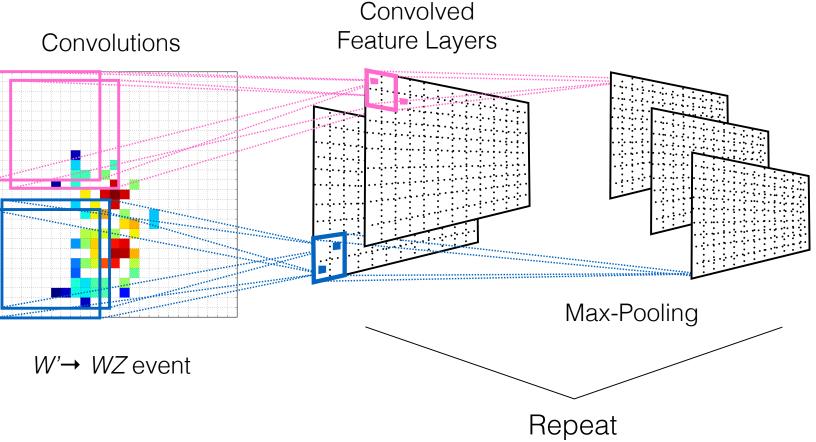
Jet seen as an image made of pixel hits:

- Jets are 'sparse' structures in an inhomogeneous medium
- Pixel representation unadapted to the physics meaning

Based on Convolutional neural networks (CNN)

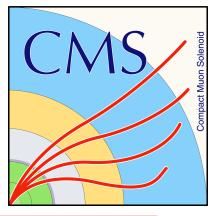


arXiv:1511.05190 arXiv:2012.09719



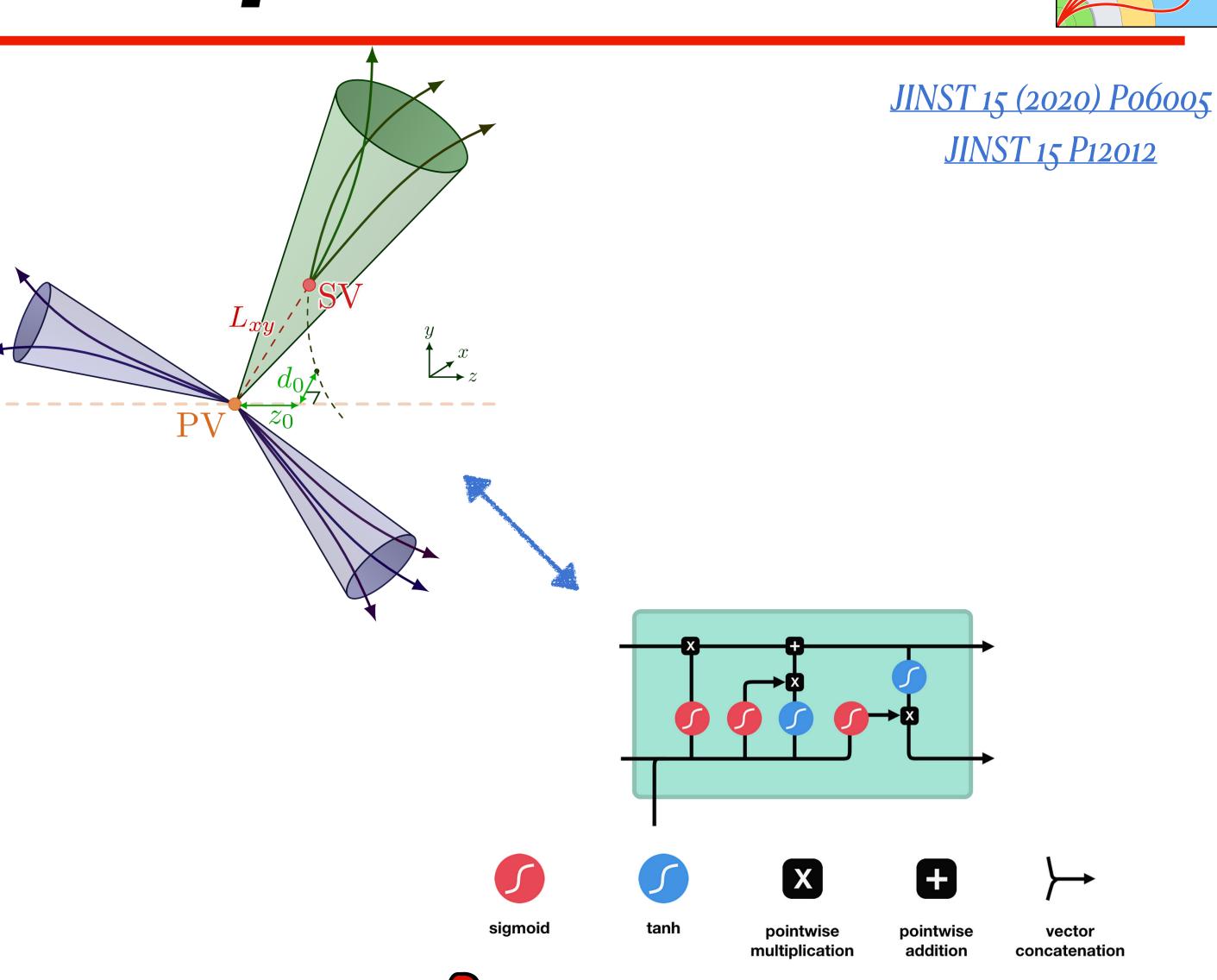


## Jet as a sequence



First turning point of jet algorithms:

- Exploits the substructure of the jets (constituent based approach)
- Processes constituents one by one in order to obtain a sequence-based latent space
- First 'Deep' neural networks
- Parametrization O(100) to O(10,000)
   and inputs O(10) to O(500)





A complex and hard to train architecture

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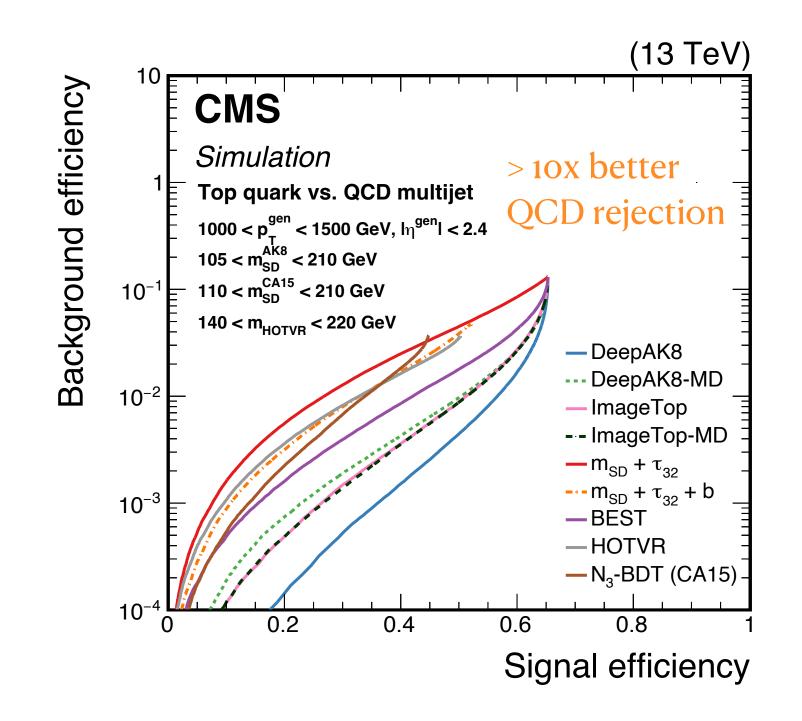


## Jet as a sequence: DeepAK8 and DeepJet

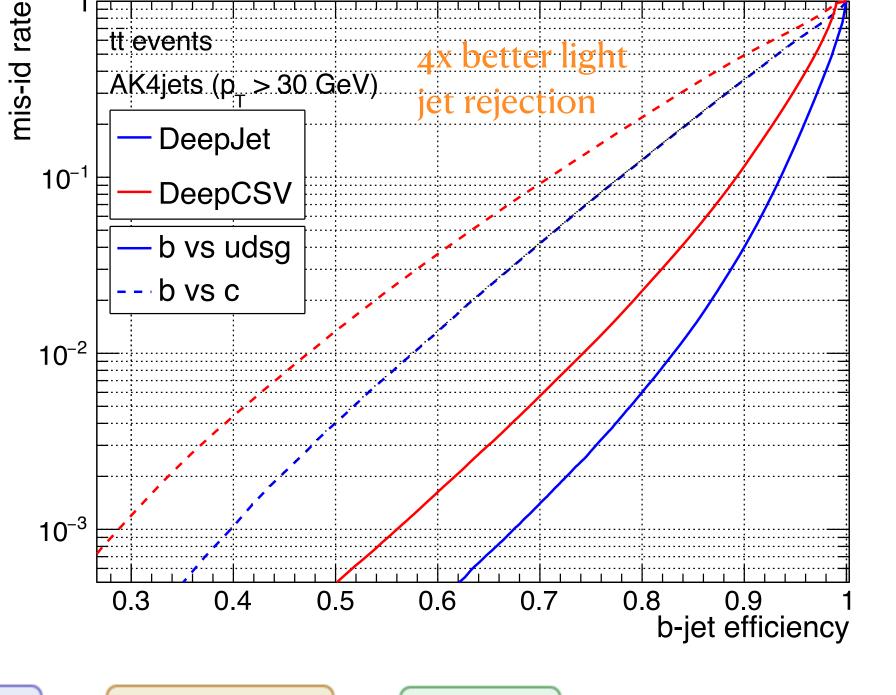


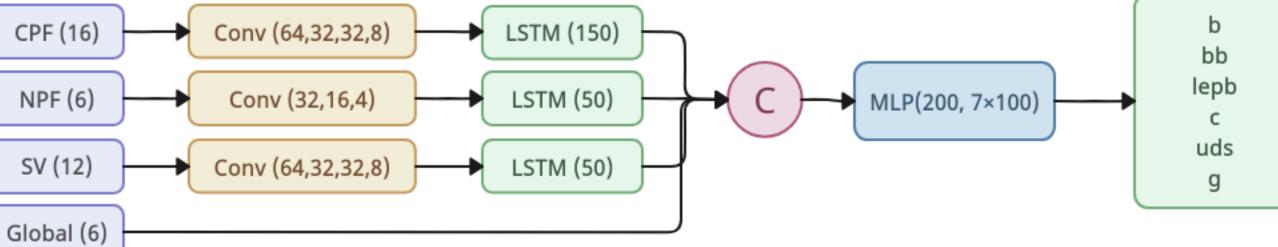
Widely adopted as the state-of-the-art at the end of Run2 at CMS.

Two models: DeepAK8 for large jet radius and DeepJet for small jet radius



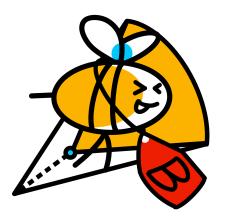
JINST 15 (2020) P06005 JINST 15 P12012





DeepJet architecture

25/11/2025



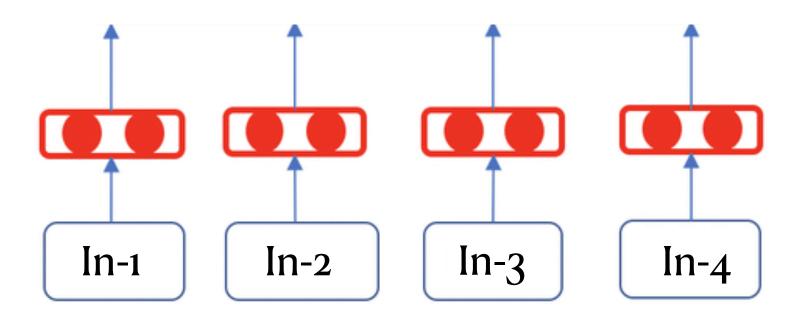
# Jet as a sequence: limit



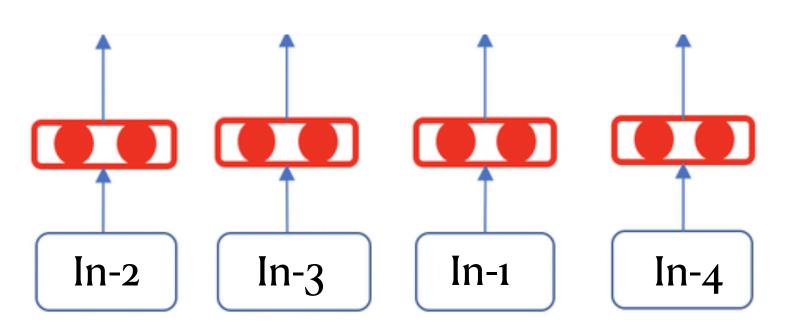
Sequence based model depends on the ordering:

- Shuffle your input list and the prediction changes
- Jets have no hierarchical ordering (not a sentence)

Need to impose a new representation that is permutation equivariant in the latent space

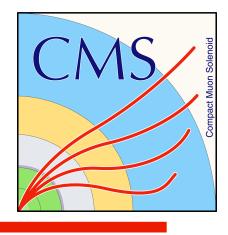






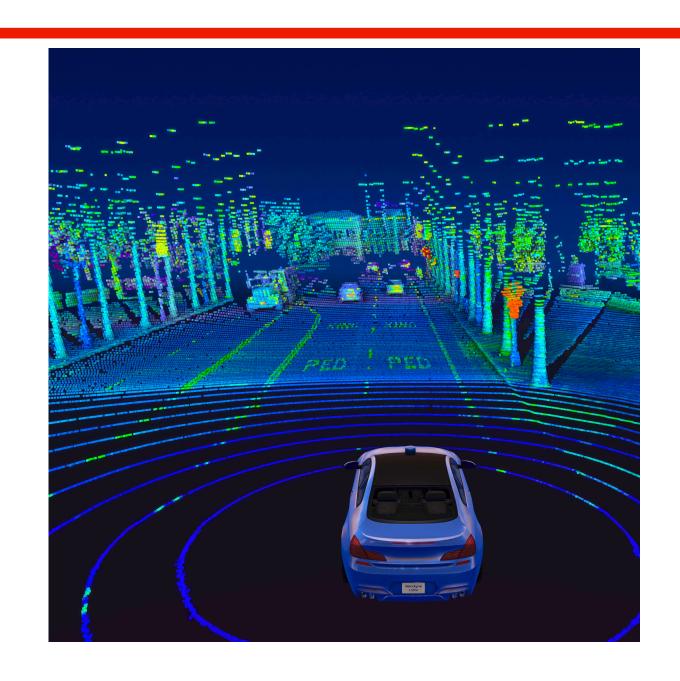


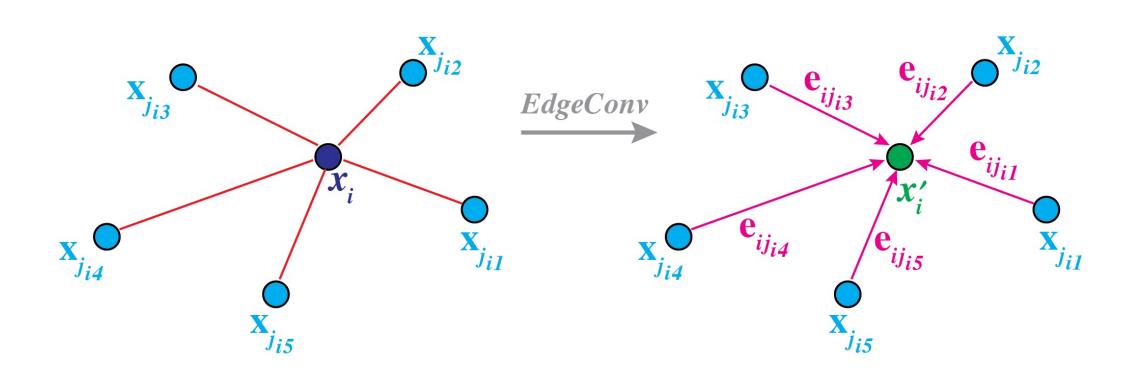
## Jet as a Particle Cloud



Analogous representation to the Point Cloud approach in 3D imaging (such as LIDAR):

- Each constituent is an element of a cloud in spatial coordinates
- Cloud is processed and represented as a graph
- Each constituent represent a nodes/'point' in the feature space, we can connect constituents via edges/'lines' representing features of a pair of nodes





arXiv:1801.07829

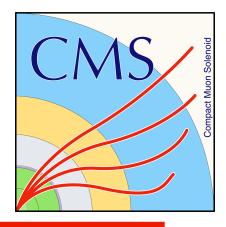
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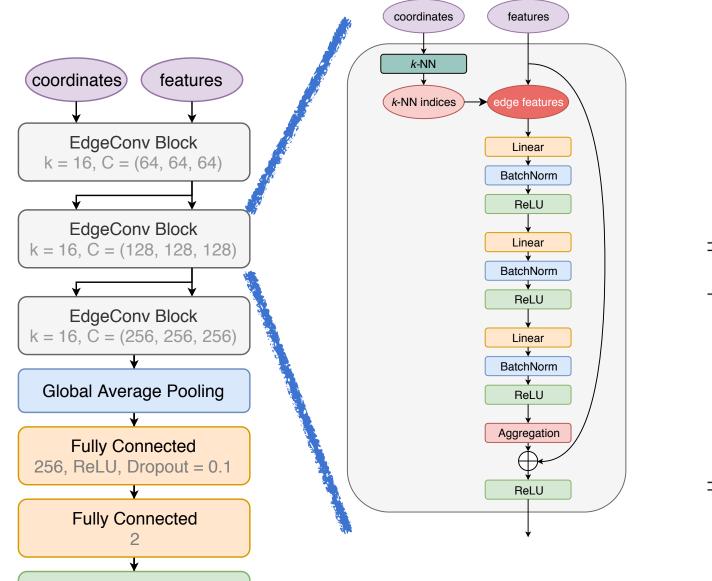
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### ParticleNet



ParticleNet: jet tagging via particle clouds

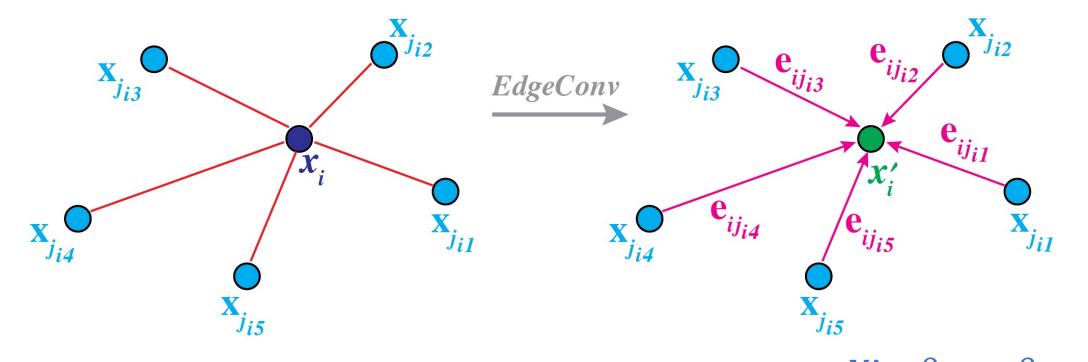
- Consider the jet from its set of constituents in the  $\eta - \phi$  coordinates
- Graph Network structure inherited from the Edge Convolution block
  - Build the edges from the k-nearest neighbors of each nodes
  - Uses permutation equivariant structure; convolutional layers and mean aggregation



Softmax

	$1/\varepsilon_b$ at $\varepsilon_s = 30\%$
ResNeXt-50	$1147 \pm 58$
P-CNN	$759 \pm 24$
PFN	$888 \pm 17$
ParticleNet-Lite	$1262 \pm 49$
ParticleNet	$\boldsymbol{1615 \pm 93}$

40% better bkg rejection

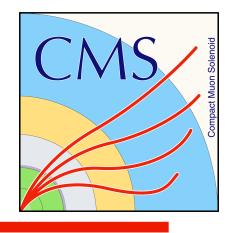


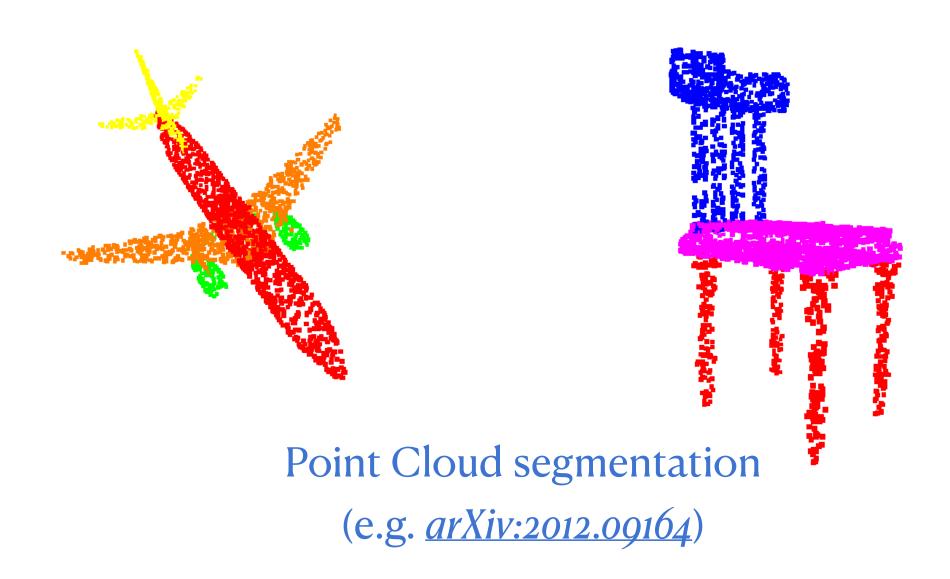
arXiv:1801.07829 Phys. Rev. D 101, 056019

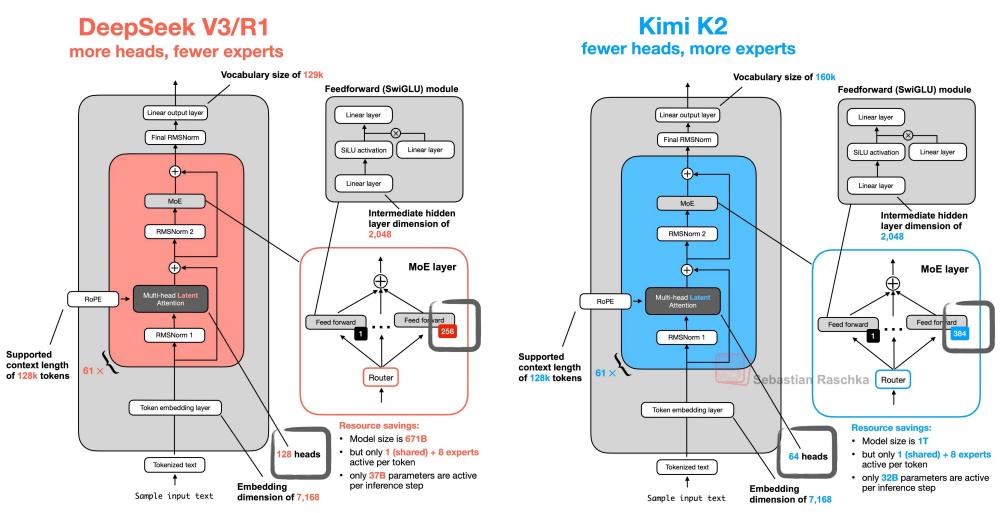
**EPPG** seminar

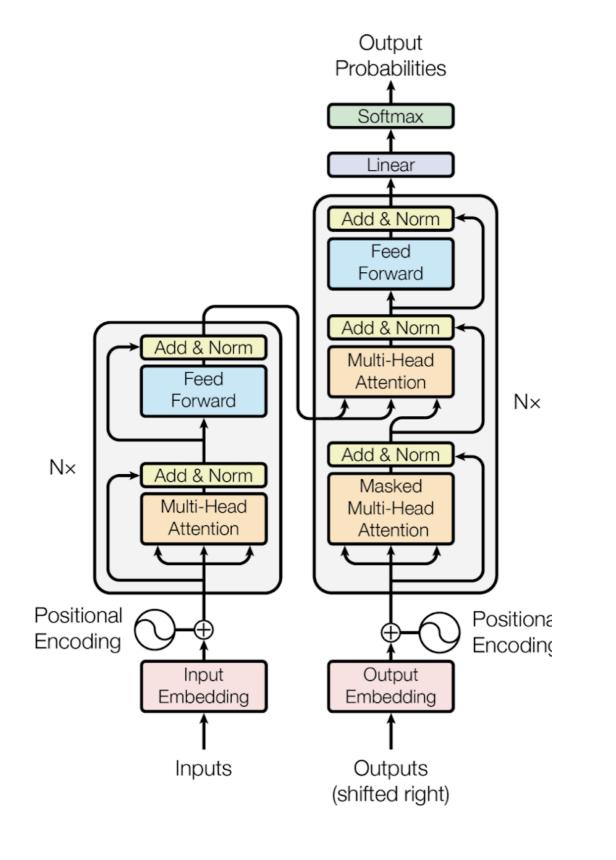


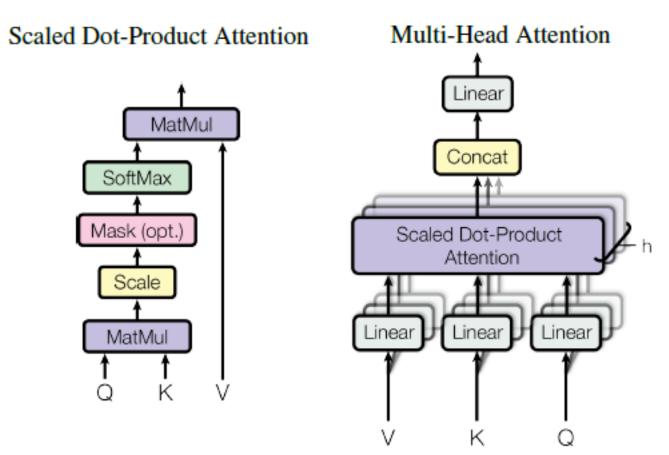
## Transformer models



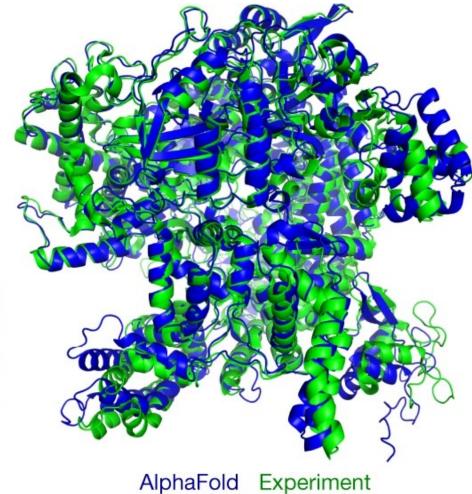








Protein Structure Prediction (e.g. *Nature* 596 (2021) 583)

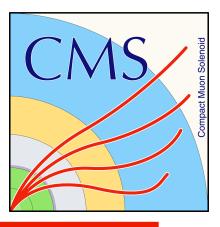


 $r.m.s.d._{95} = 2.2 \text{ Å}$ ; TM-score = 0.96

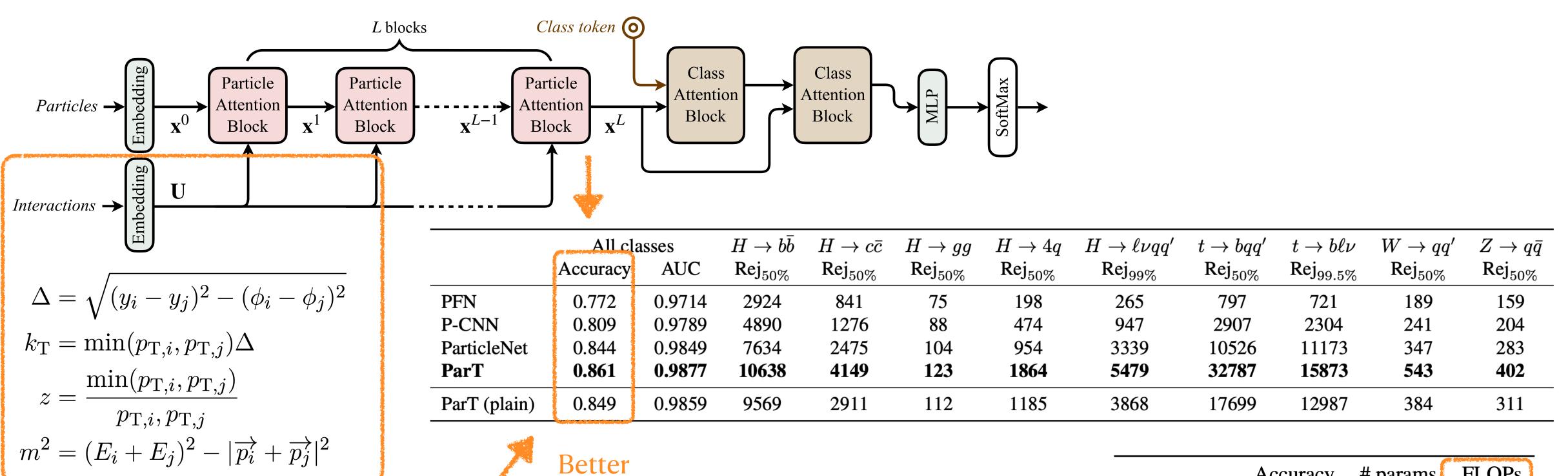
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## Particle Transformer



HQ, C. Li, S. Qian, ICML 2022



Physics inspired pairwise bias (ParT is a Graph Transformer model)

 $P\text{-}MHA(Q, K, V, U) = \text{SoftMax}\left(\frac{QK^T}{\sqrt{d_k}} + U\right)V$ 

Up to 3x in bkg rejection for an even faster architecture!

	Accuracy	# params	FLOPs
PFN	0.772	86.1 k	4.62 M
P-CNN	0.809	354 k	15.5 M
<b>ParticleNet</b>	0.844	370 k	540 M
ParT	0.861	2.14 M	340 M
ParT (plain)	0.849	2.13 M	260 M

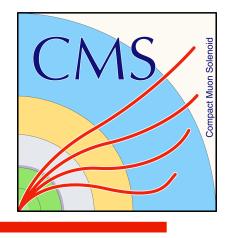
Faster



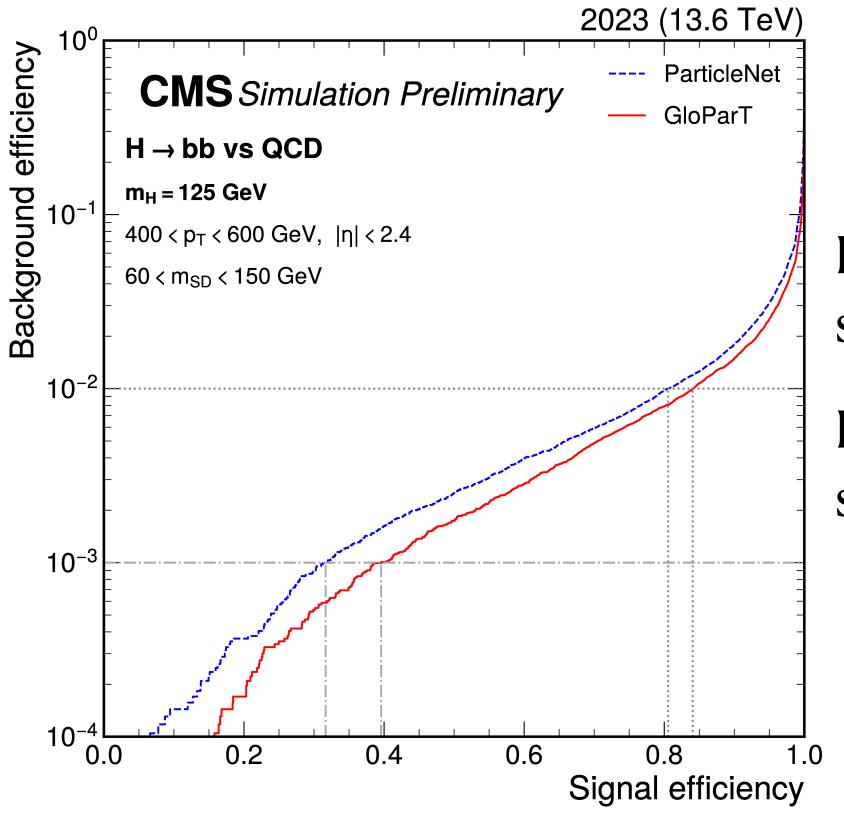
EPPG seminar



## In CMS: the new state-of-the-art



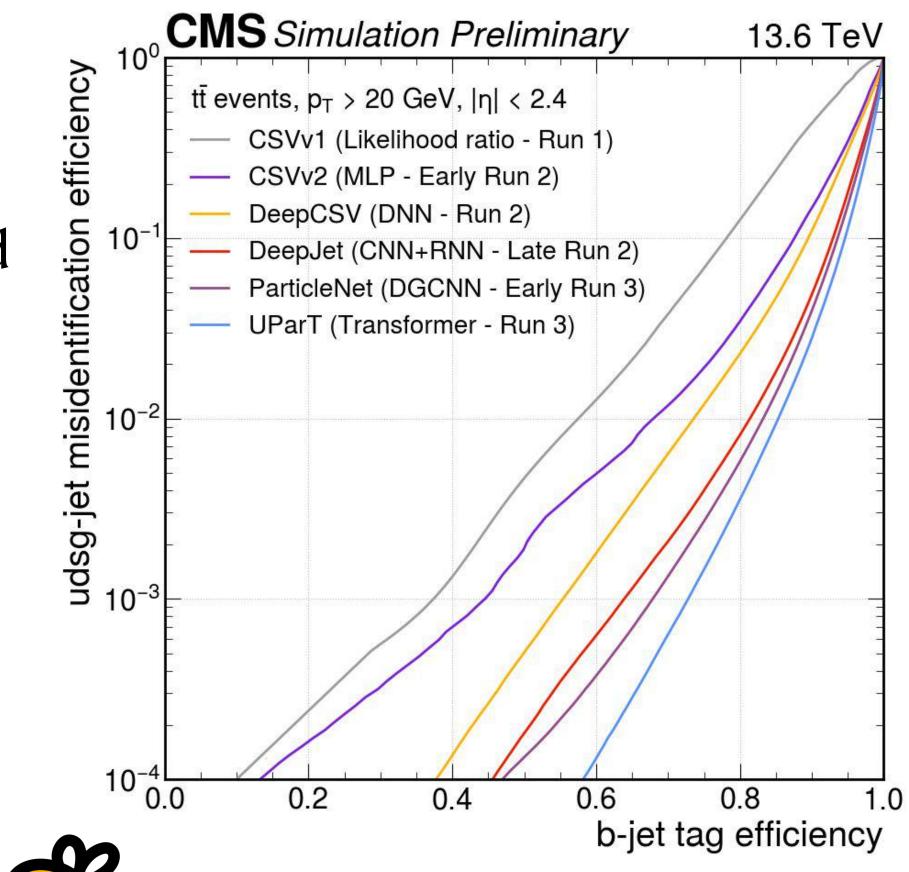
#### Large radius tagging



Particle Transformer demonstrated state-of-the-art performance.

It is now widely adopted as the standard algorithm for jet tasks

#### Small radius tagging

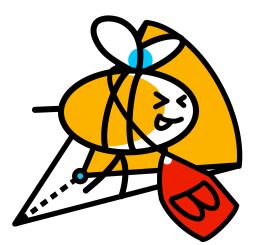


**CMS-PAS-HIG-24-010** 

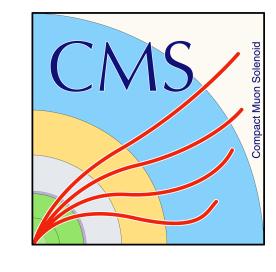
Question: can we beat Transformers?

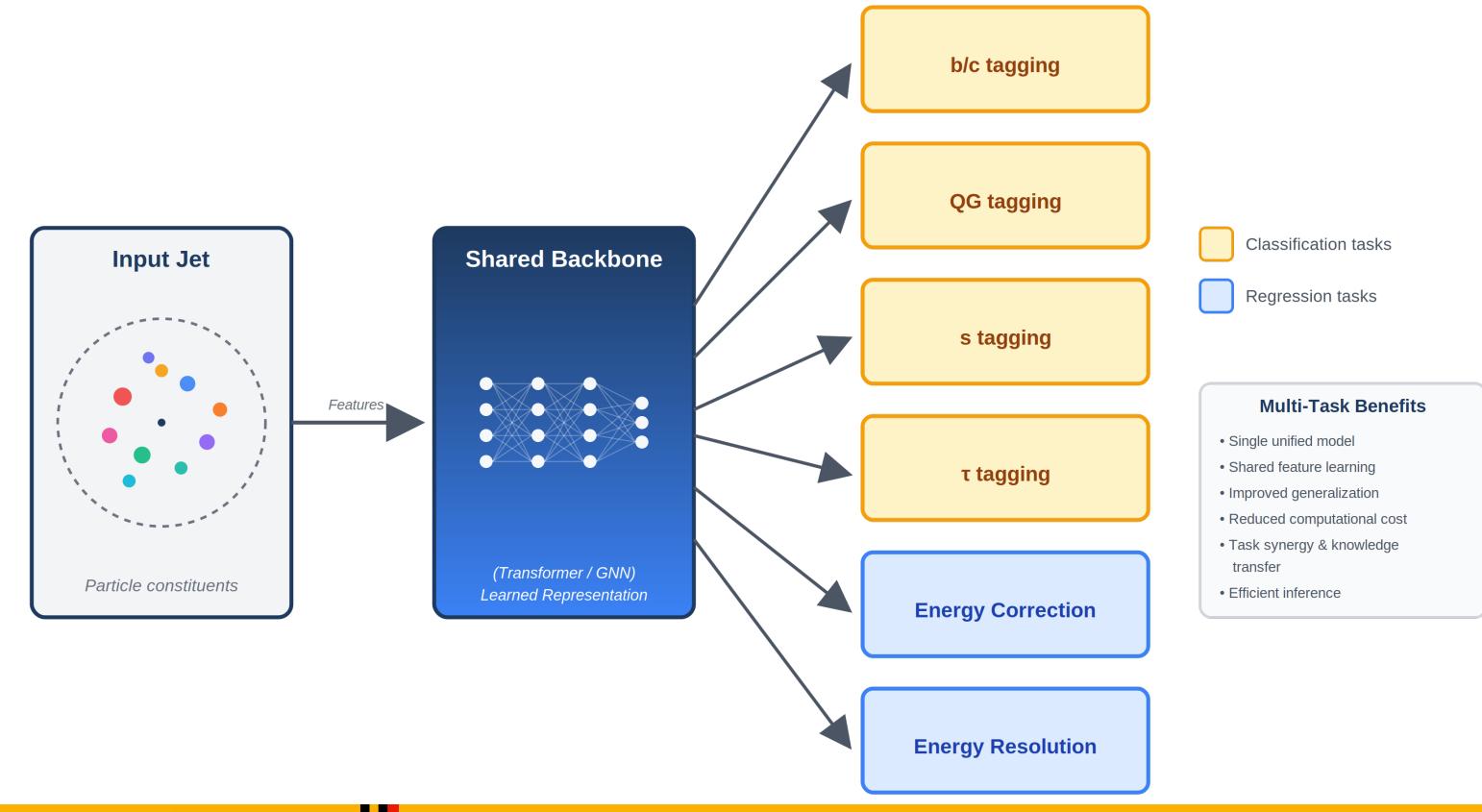


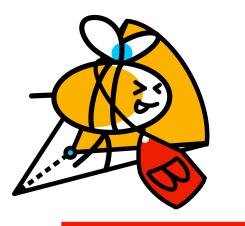
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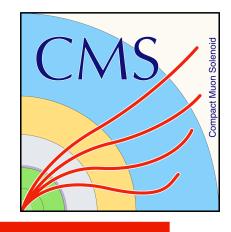






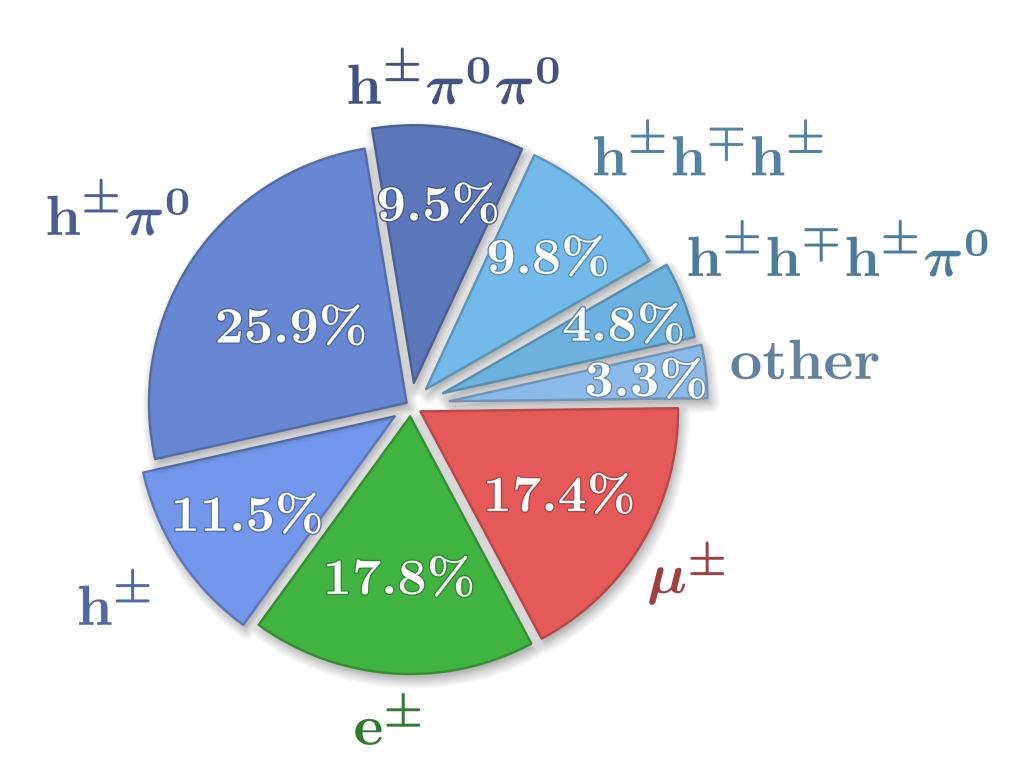


# Towards a unified jet approach



Goal: combine the latest efforts for developing a unified jet algorithm

- First attempt with ParticleNet
- Extended classification for s-tagging and hadronic tau tagging
- Include a flavor-aware jet energy regression and resolution
- SOTA architecture: Particle Transformer
- New inclusive loss function for this purpose



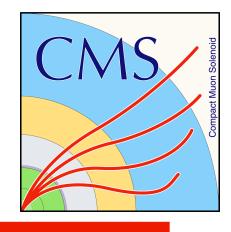
Tau lepton decay modes

New model: Unified Particle Transformer (UParT)

25/11/2025



# Towards a unified jet approach



Goal: combine the latest efforts for developing a unified jet algorithm

- First attempt with ParticleNet
- Extended classification for s-tagging and hadronic tau tagging
- Include a flavor-aware jet energy regression and resolution
- SOTA architecture: Particle Transformer
- New inclusive loss function for this purpose

$$L_{cat} = \text{CrossEntropy}(\mathbf{x}, \mathbf{x}_{\text{truth}})$$

+

$$L_{reg} = \lambda \times [\log(\cosh(y^{vis} - y_{target}^{vis}) + \log(\cosh(y^{\nu} - y_{target}^{\nu}))]$$

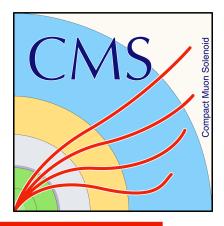
+

$$L_{res} = \gamma \times [\rho_{0.16}(z^{vis} - y_{target}^{vis}) + \rho_{0.84}(k^{vis} - y_{target}^{vis})]$$

New model: Unified Particle Transformer (UParT)



## New adversarial training

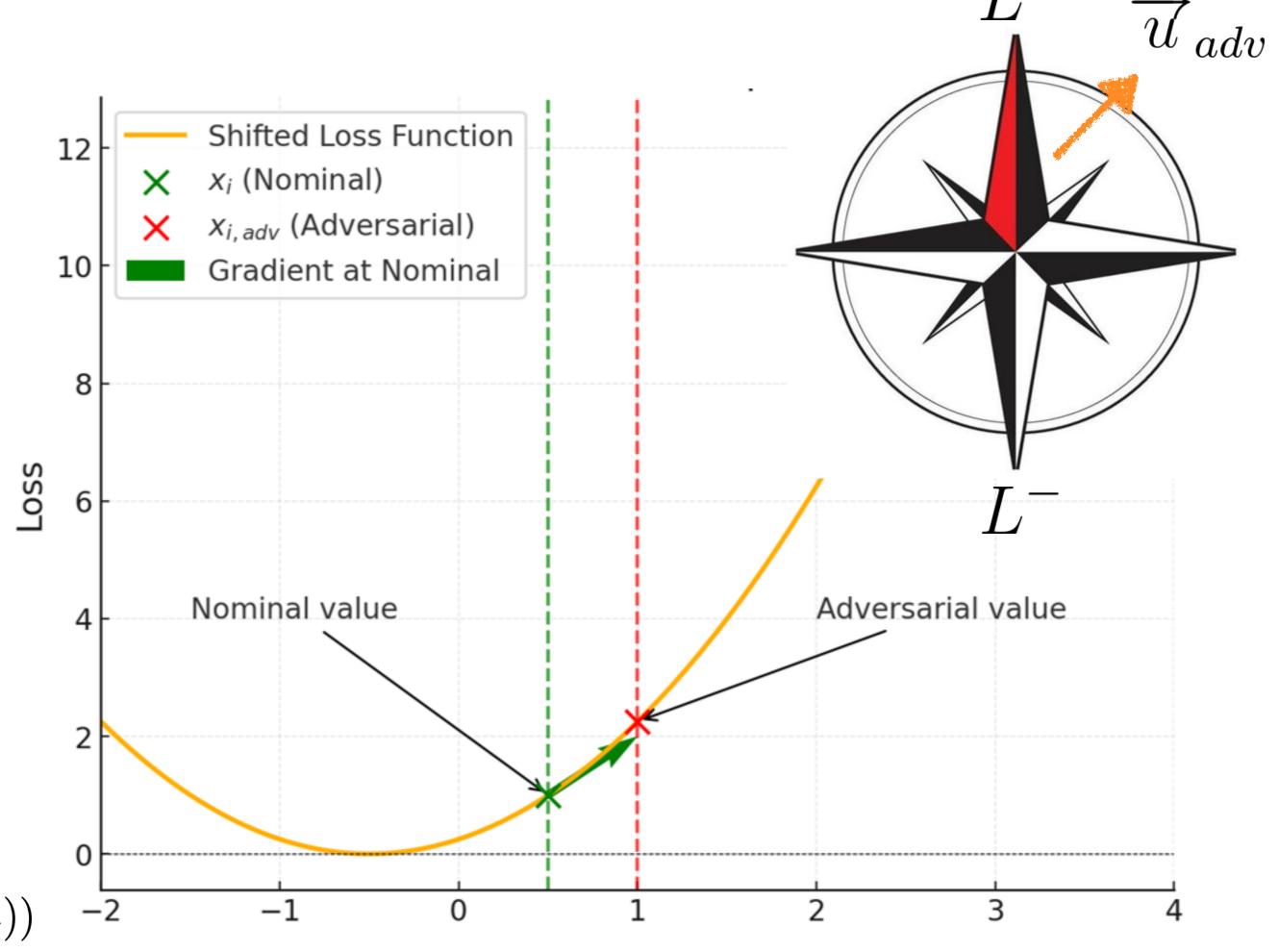


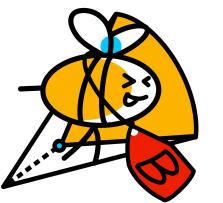
Targeted perturbations to jet input features to fool the network:

- Standard attacks (FGSM & co) are not ideal for heterogeneous jet features.
- Design jet-specific attacks and training.
- Adversarial training: improve robustness to mismodelling in an agnostic way while keeping nominal performance.

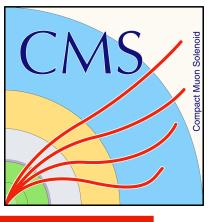
$$L_{\text{adv}}(x, x_{\text{adv}}, y, \theta) = \begin{cases} CE(\theta(x), y) \text{ if nominal mode} \\ CE(\theta(x_{\text{adv}}), y) + \lambda \cdot KL(\theta(x), \theta(x_{\text{adv}})) \end{cases}$$

$$\text{otherwise}$$





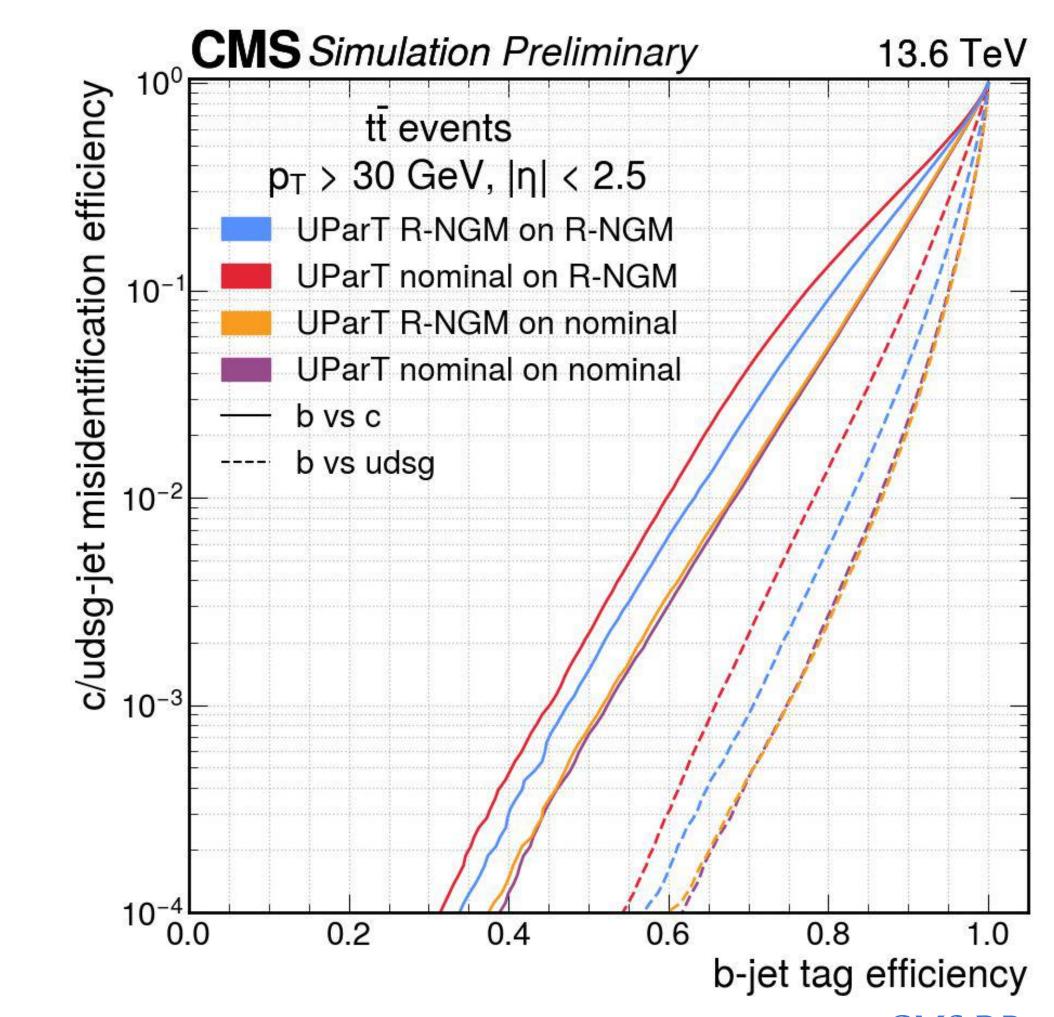
# Rectified Normed Gradient Method



R-NGM: uses full input gradient normalized

- Adversarial training with these attacks preserves nominal performance
- R-NGM achieves the best robustness
- Result: best MC performance with minimization of the sensitivity to data/MC disagreement

$$x_{\text{adv}} = x + \epsilon \cdot \frac{\nabla_x L(\theta, x, y)}{||\nabla_x L(\theta, x, y)||_{L_2}}$$

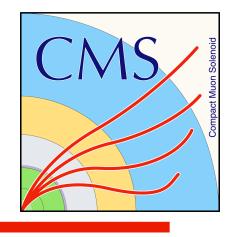


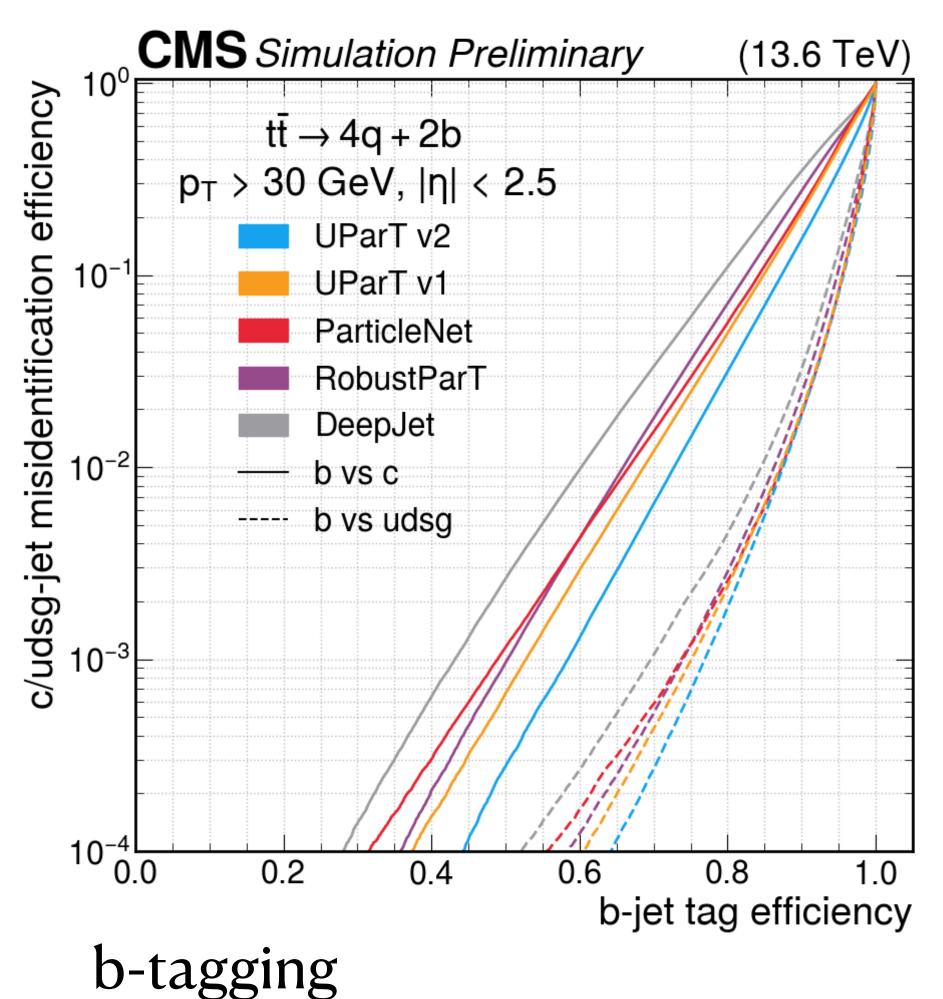
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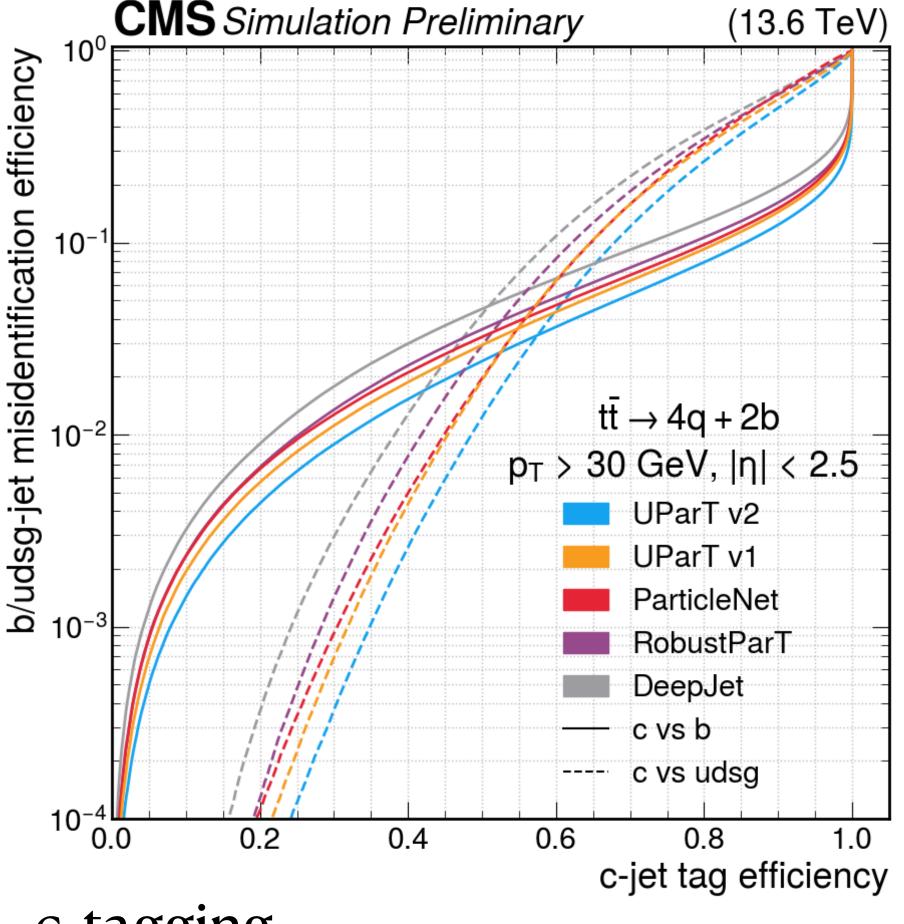


# UParT: flavor tagging result





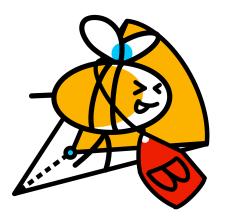
About 20-60% improvement in bkg rejection for b/c tagging compared to the ParticleNet models



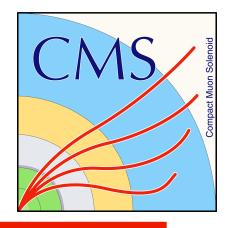
c-tagging

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CMS DP -



# UParT: flavor tagging result



Very first s-tagging model at LHC. We can achieve a low efficiency s-tagger.

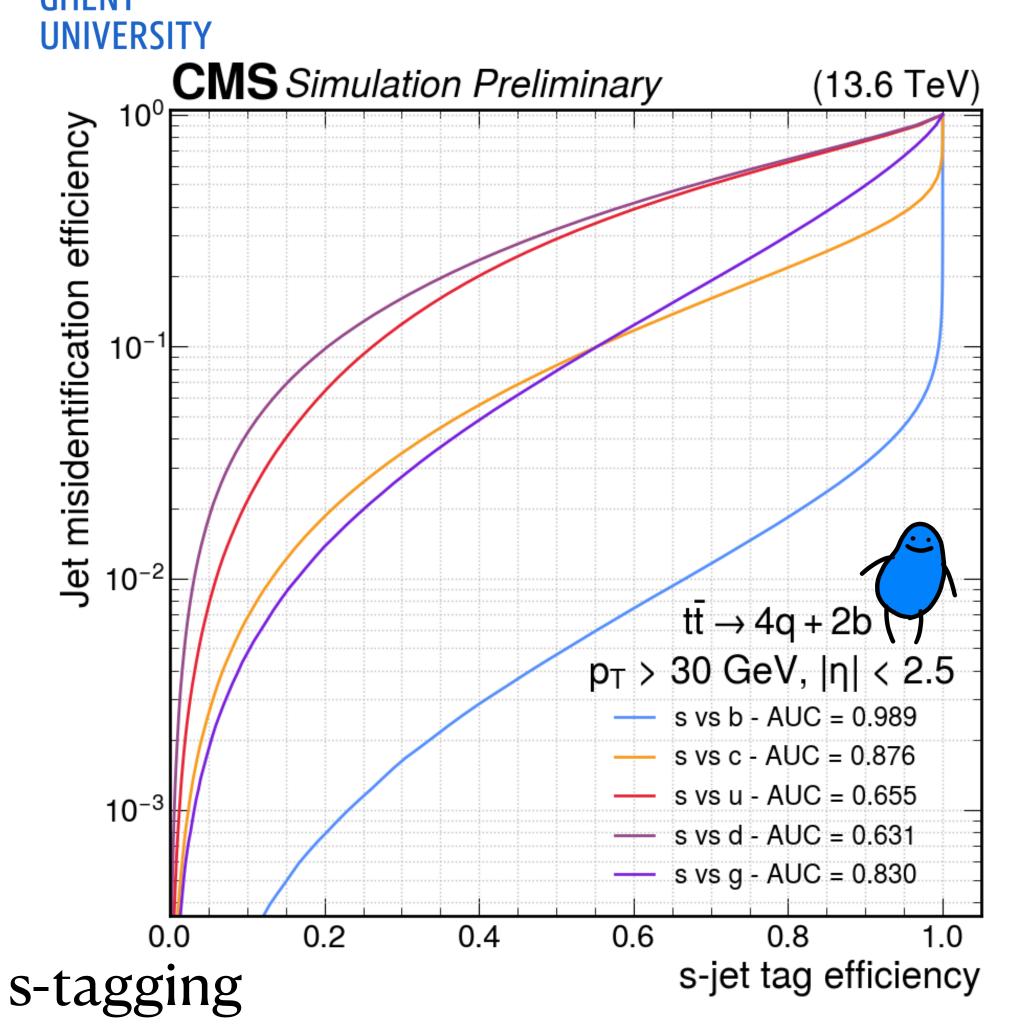
Future: work on the calibration of the s-tagging node

Question: Can you do u vs d tagging?



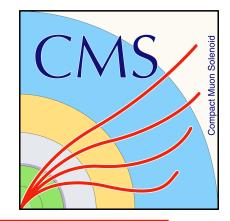


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# UParT: flavor tagging result

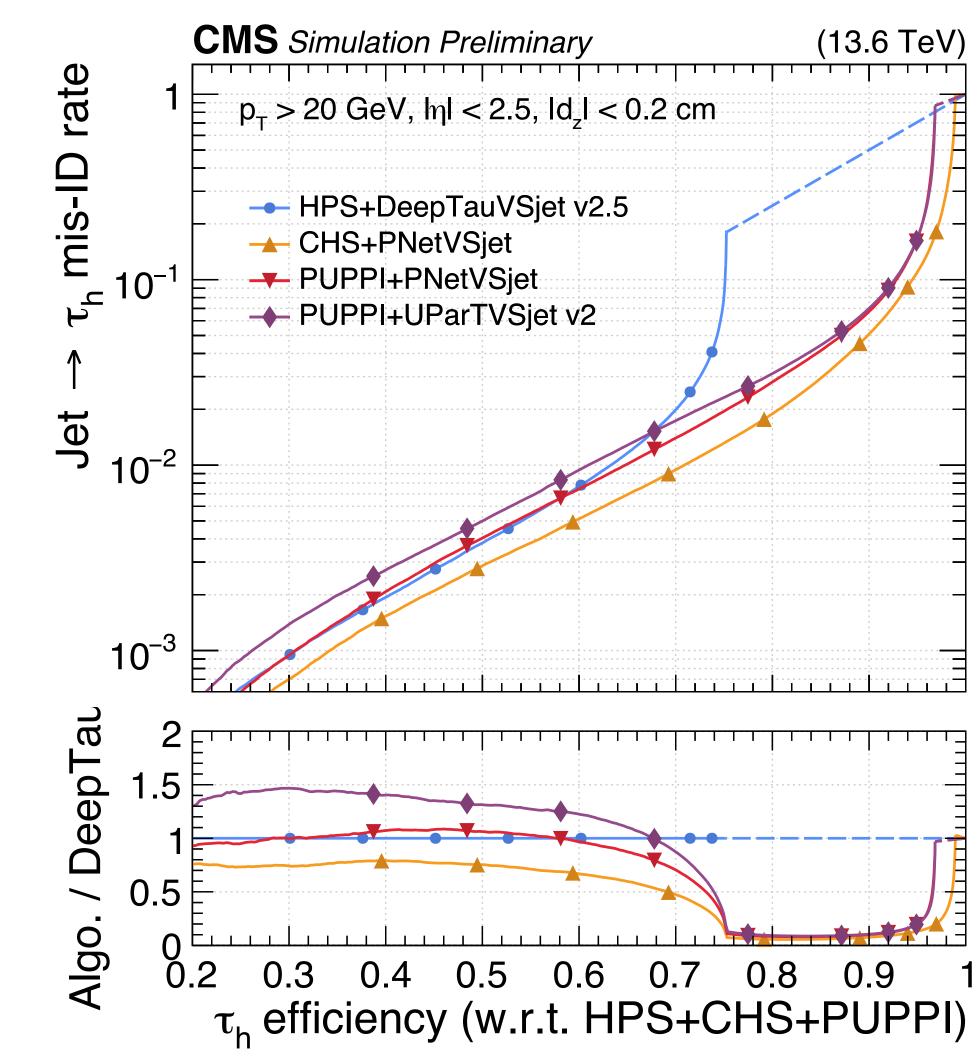


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Tau performance not fully under control

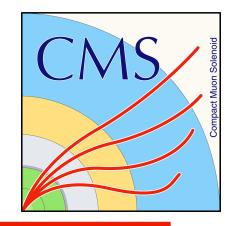
High dependence of the pile-up mitigation algorithm plus the reconstruction of the tau

Future: include reconstruction task in the jet algorithm



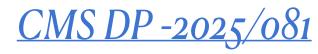


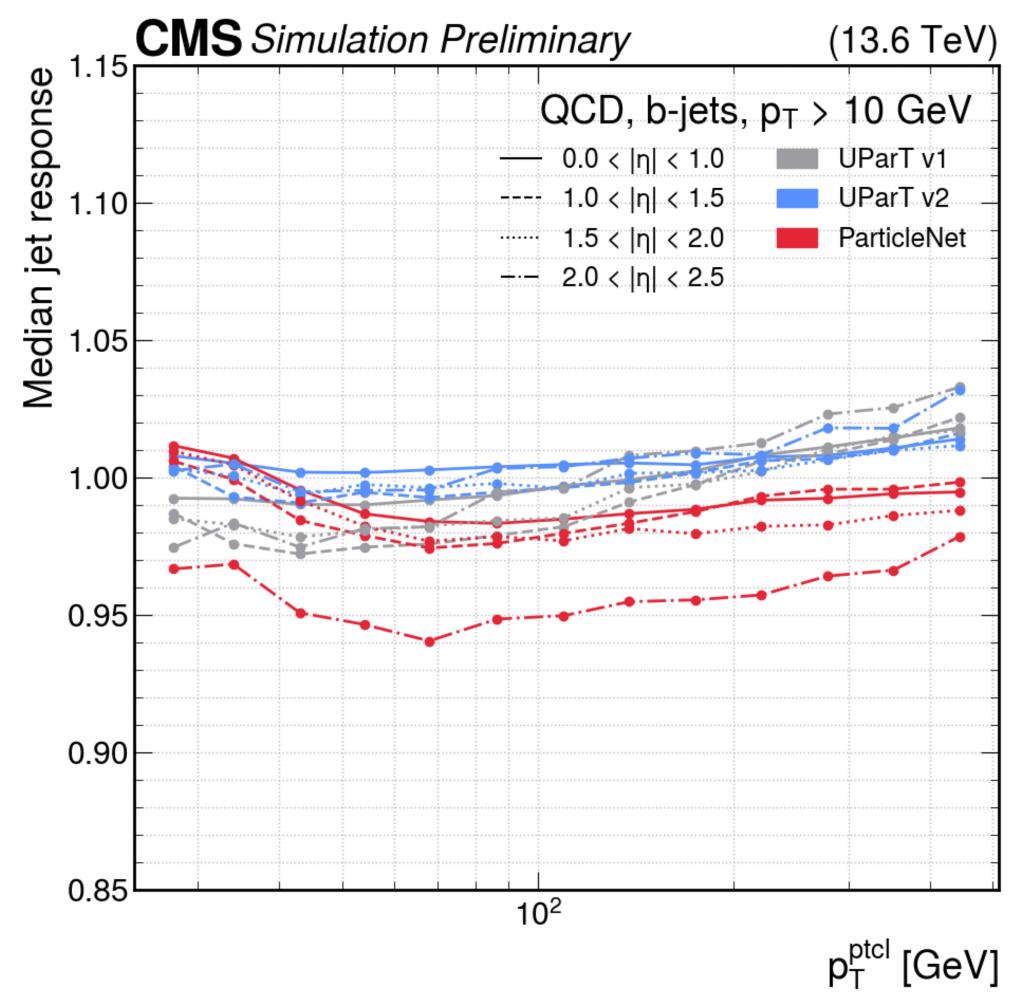
# UParT: jet regression result



Improved median jet response across model versions.

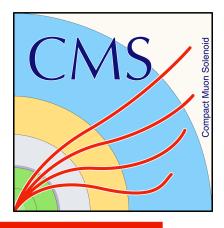
Observed per year overall sensitivity (small HCAL response changes can dramatically impact the models)







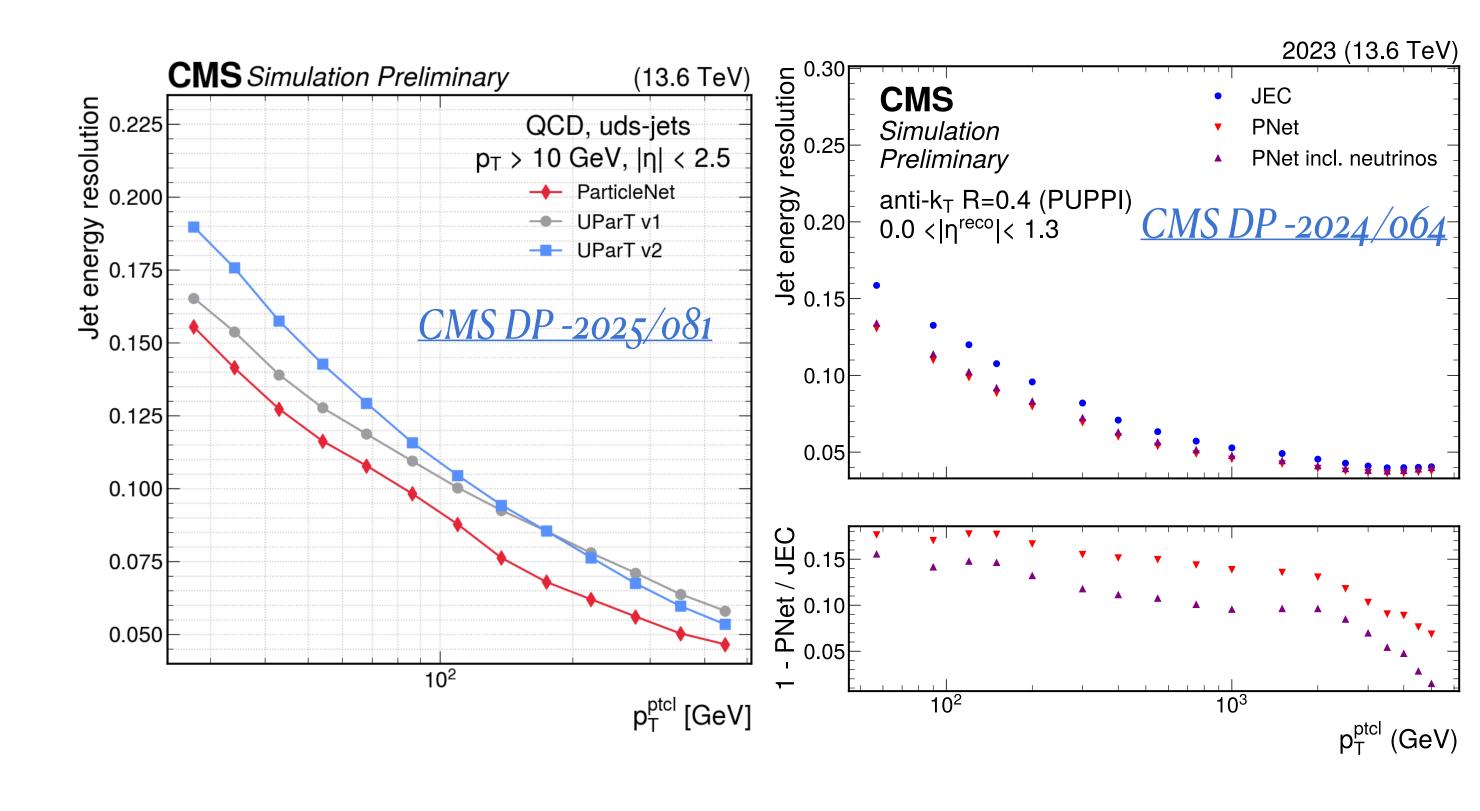
# UParT: jet resolution result

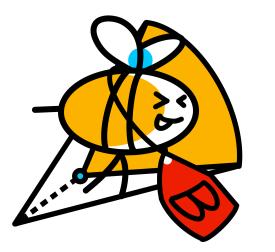


Resolution improved compared to the usual JEC by O(10-15%)

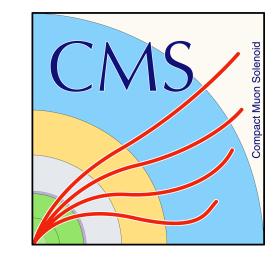
Degradation in UPArT models: problem seems to be now fully understood

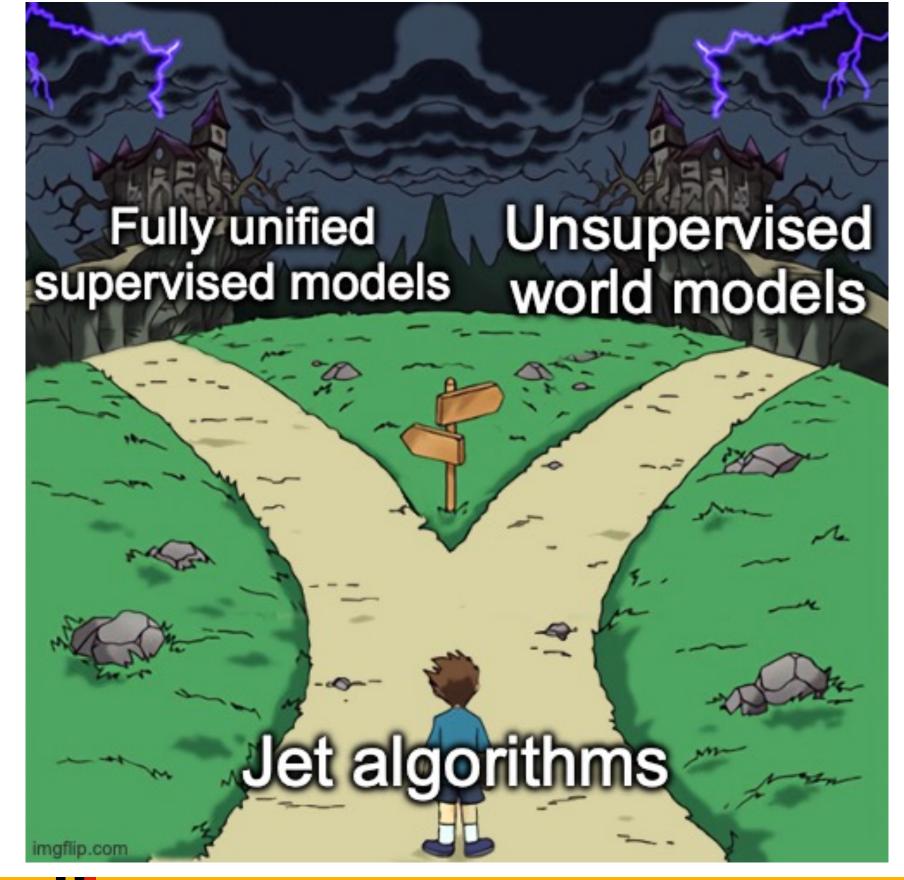
• Simulation and training tuning issue





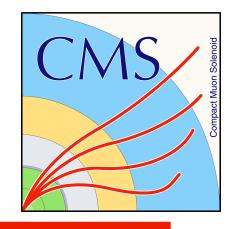








# Prelude: scaling laws

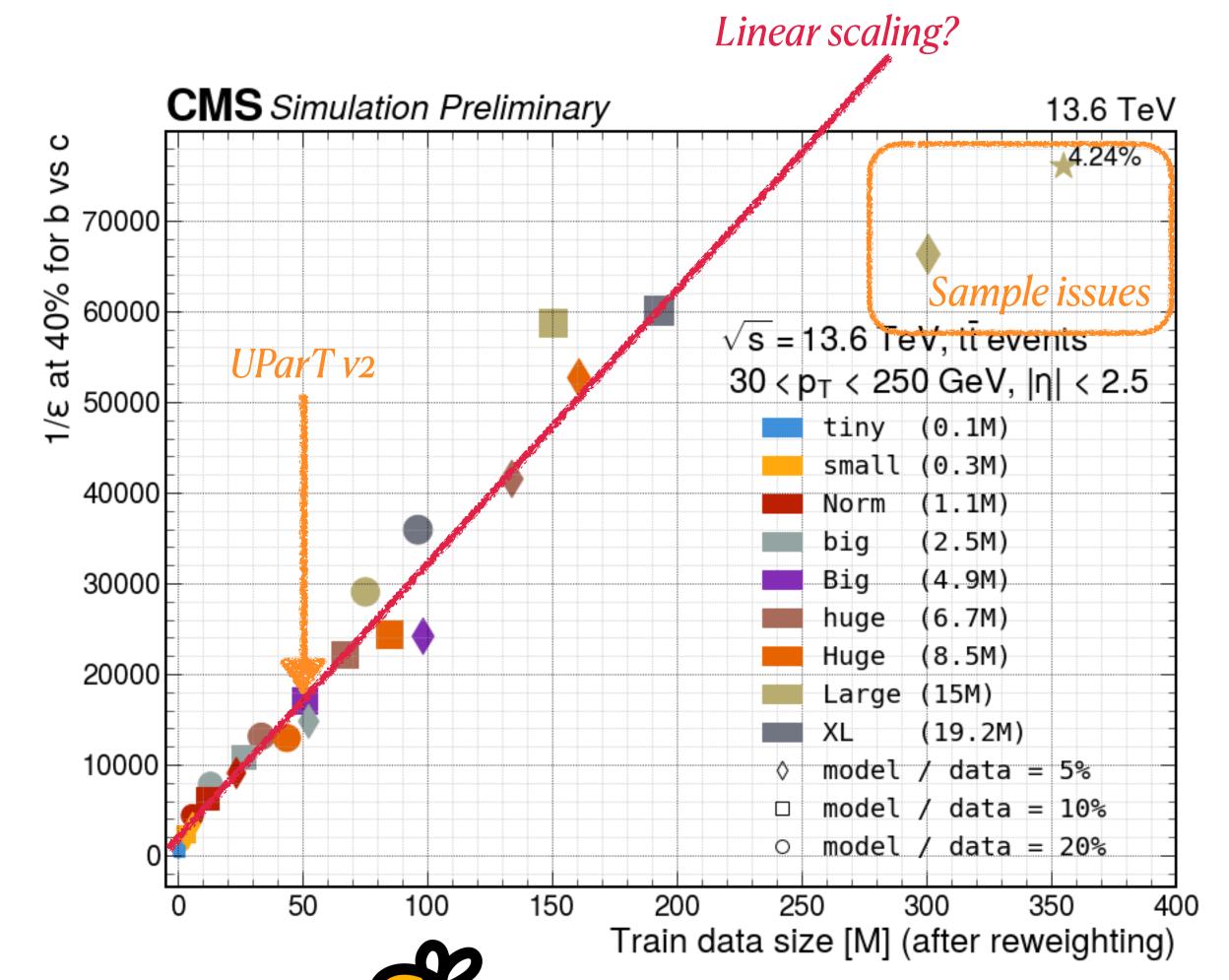


Pavlo Kashko's talk

Scaling laws: the laws extrapolating the performance of neural networks at larger size (model/datasets)

We have found scaling laws of flavor tagging:

- Huge room of improvement
- Challenges: fit the inference in our software and stabilize the training
- To come: even better scaling laws



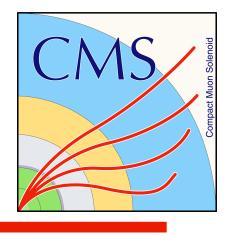
Question: Does it hold at 1B+ jets?



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# Prelude: scaling law

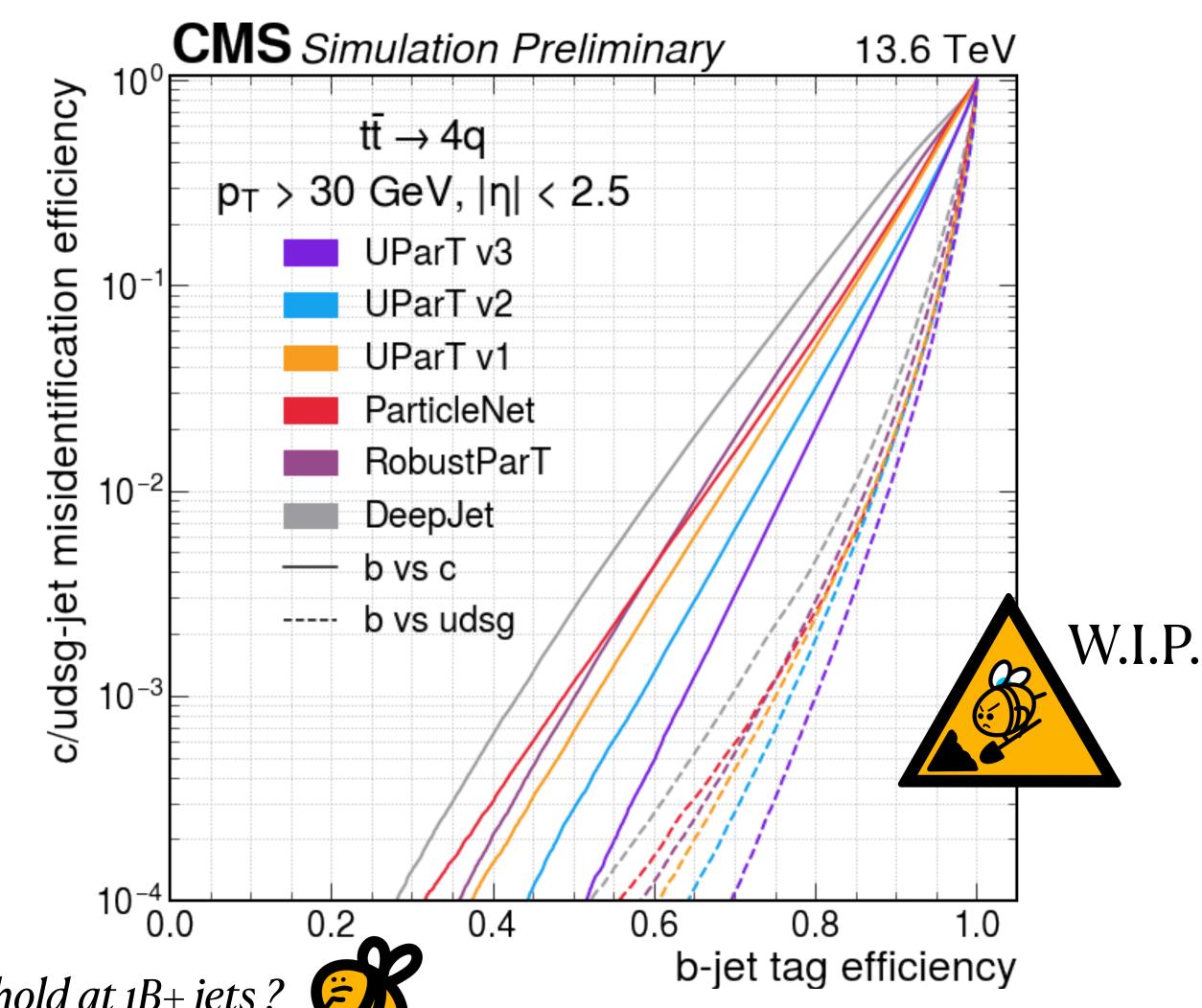


We have extrapolated the scaling laws of flavor tagging:

- Huge room of improvement
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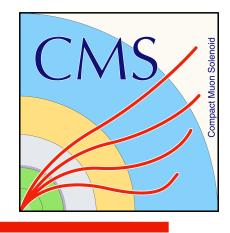
Warning: this is a first attempt!

hollup...Let him cook





# Full supervised unification



We could extend the unification towards more tasks:

- Full object reconstructions such as hadronic tau or b/c hadrons
- Jet charge tagging
- In-training ML based calibration

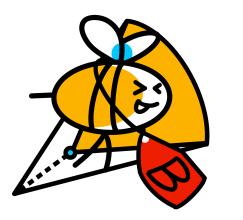
#### gen τ<sub>h</sub> - HPS matching efficiency

Reco/Gen	TAU1H0P (16.6%)	TAU1H1P (40.9%)	TAU1H2P (15.9%)	TAU3H0P (17.7%)	TAU3H1P (8.5%) TA	Wother (0.3%)
0h_0p	14.54	22.53	21.23	9.65	11.24	20.54
0h_1p	0.00	0.30	0.32	0.00	0.02	0.33
0h_2p	0.00	0.00	0.26	0.00	0.00	0.50
0h_3p	0.00	0.00	0.00	0.00	0.00	0.41
1h_0p	85.46	13.07	7.65	4.40	1.15	5.69
1h_1p		64.10	28.85	0.00	4.60	12.46
1h_2p			41.68	0.00	0.00	15.68
1h_3p				0.00	0.00	18.07
2h_0p				19.62	9.16	1.73
2h_1p				0.00	7.95	1.24
2h_2p				0.00	0.00	1.24
2h_3p				0.00	0.00	0.00
3h_0p				66.33	25.49	8.58
3h_1p					40.40	4.21
3h_2p	011 1	1 / 1	1 1 000	. 11	. 1 6 1	8.33
3h_3p	Old metho	d (cut base	d - Iow ettic	ciency and h	nigh fake rate	S) 0.00
other						0.99

#### gen $\tau_h$ - jet matching efficiency

$\mathbf{O}$	••	O				
Reco/Gen	TAU1H0P (16.6%)	TAU1H1P (40.9%)	TAU1H2P (15.9%)	TAU3H0P (17.7%)	TAU3H1P (8.5%) TAUo	ther (0.3%)
0h_0p	1.33	0.04	0.03	0.07	0.01	0.08
0h_1p	0.00	8.49	0.40	0.00	0.29	0.08
0h_2p	0.00	0.00	7.64	0.00	0.00	0.41
0h_3p	0.00	0.00	0.00	0.00	0.00	3.88
1h_0p	98.67	8.14	2.01	1.28	0.10	0.66
1h_1p		83.33	12.62	0.00	1.61	4.13
1h_2p			77.30	0.00	0.00	8.83
1h_3p				0.00	0.00	45.30
2h_0p				12.58	1.41	0.33
2h_1p				0.00	11.07	0.58
2h_2p				0.00	0.00	3.05
2h_3p				0.00	0.00	0.00
3h_0p				86.07	13.82	1.40
3h_1p					71.68	3.63
3h_2p						18.23
3h_3p	New study	(huge room	of improv	ement - ger	n matching onl	0.00
other	ricw Study	(Huge 100III		cincin - gci	i matering Om	y / 9.41

Recent VUB+Vanderbilt effort



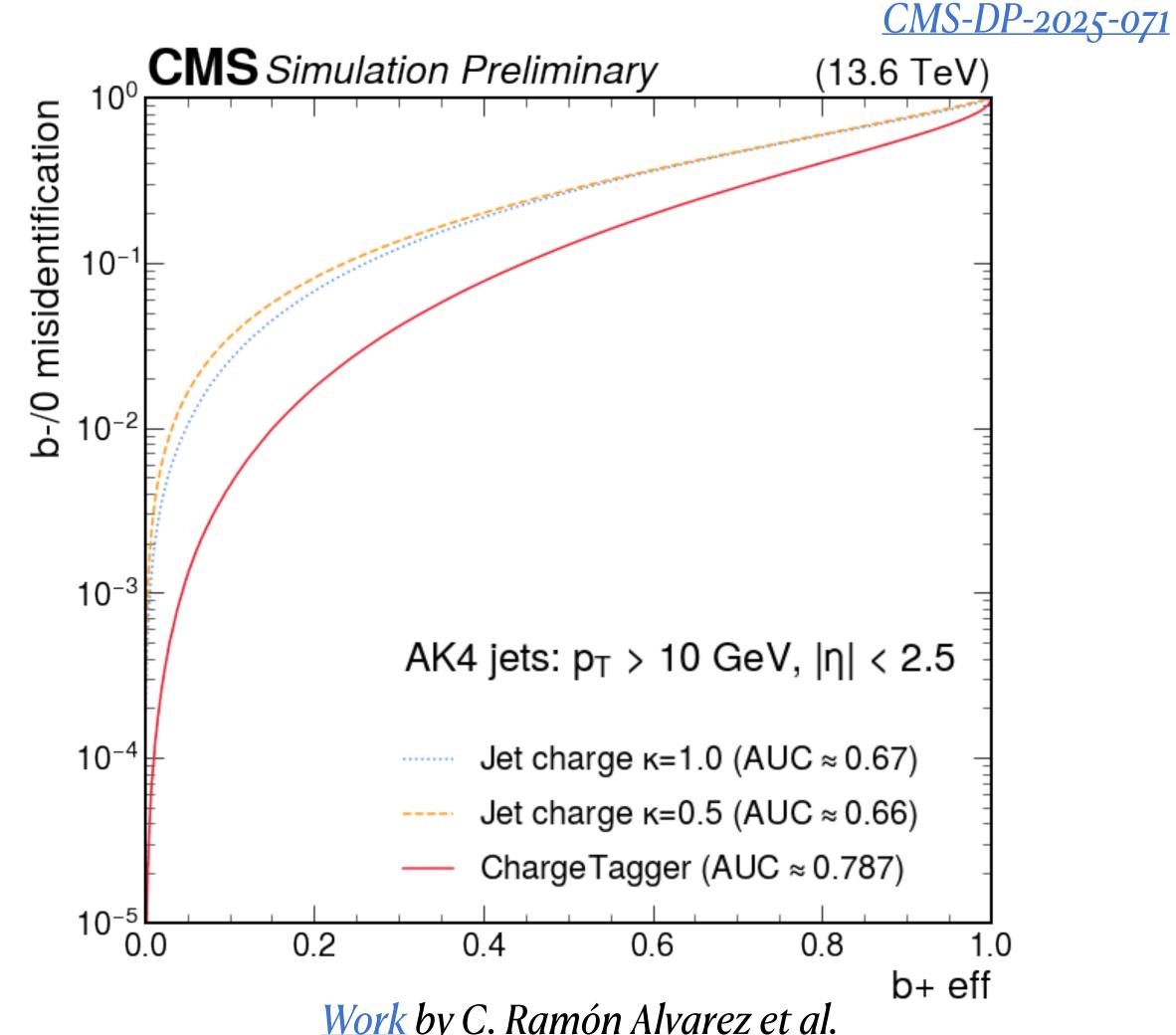
# Full supervised unification



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We could extend the unification towards more tasks:

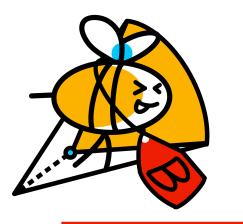
- Full object reconstructions such as hadronic tau or b/c hadrons
- Jet charge tagging
- In-training ML based calibration



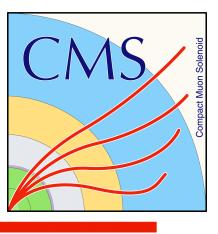
Work by C. Ramón Alvarez et al.

Now working on calibration method for b and c jet charge tagging

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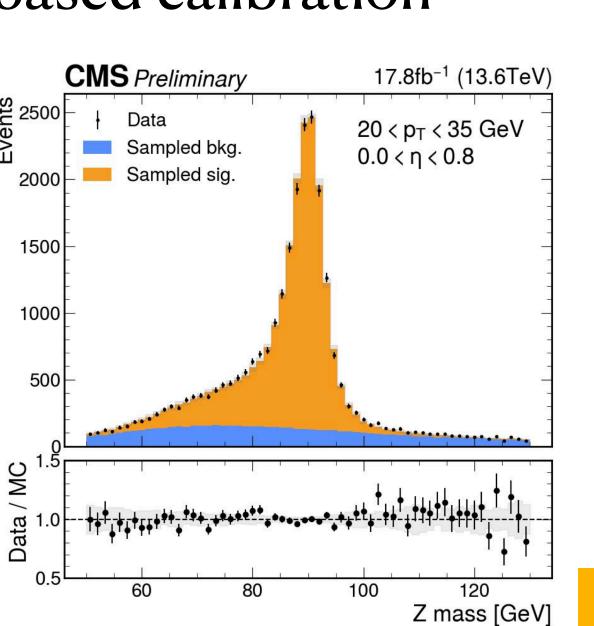
# Full supervised unification

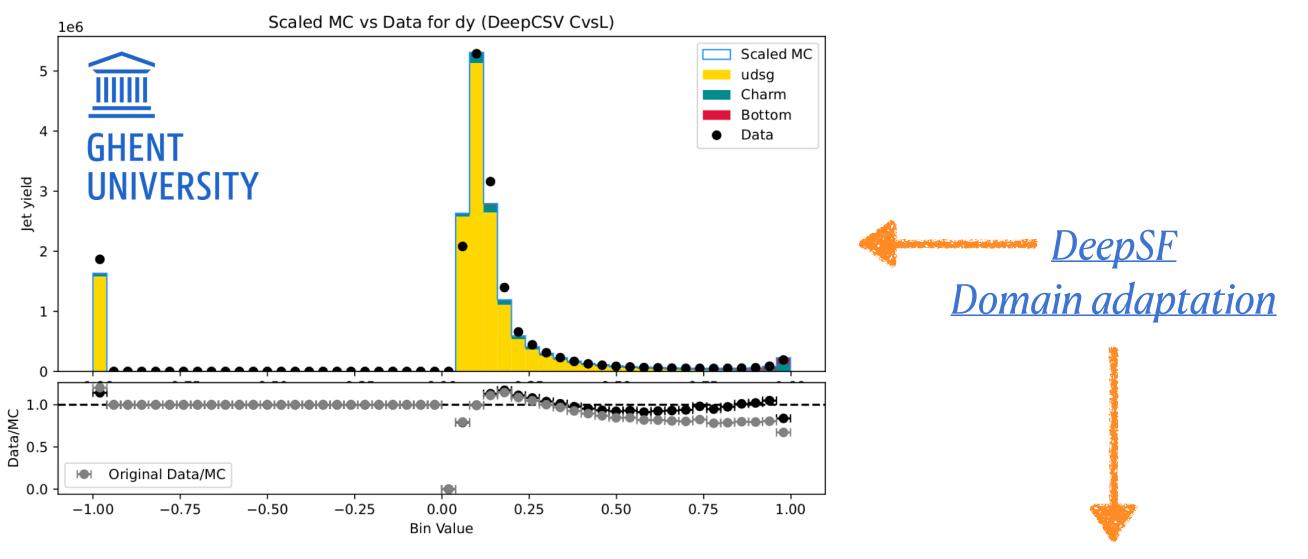


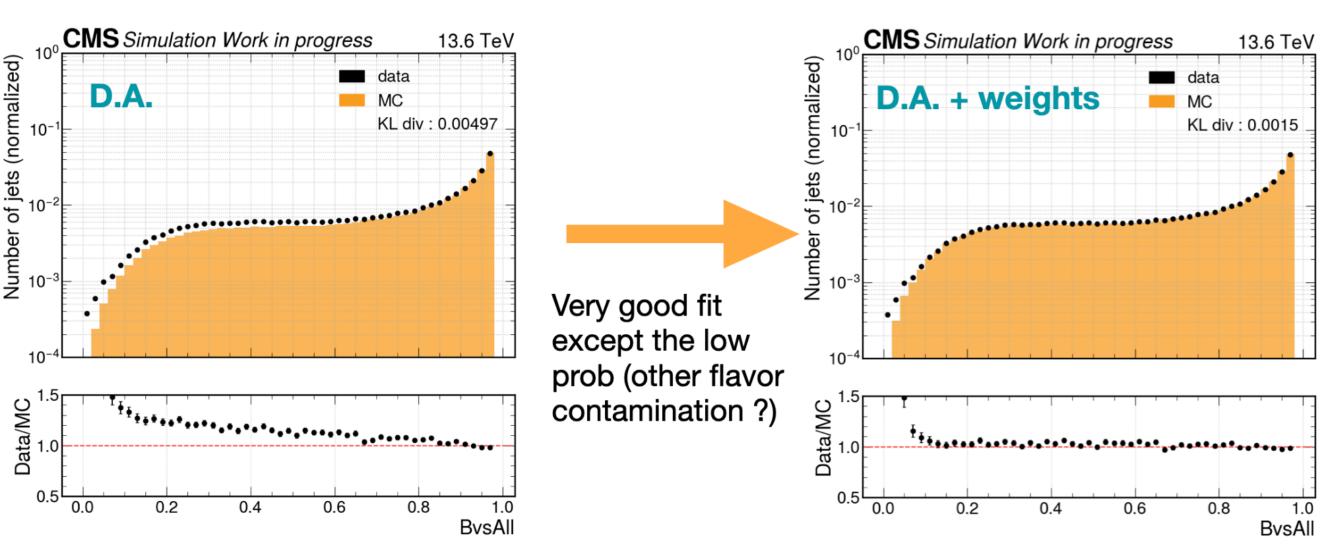
We could extend the unification towards more tasks:

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- Jet charge tagging
- In-training ML based calibration

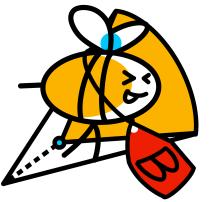
1500 1000 Also <u>CMS-DP-2025-053</u>: public result on lepton id. calib. but will be tested on b-MC tagging soon





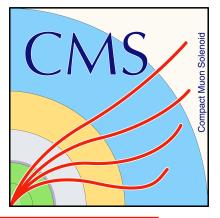


**EPPG** seminar



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### Towards the unsupervised world model

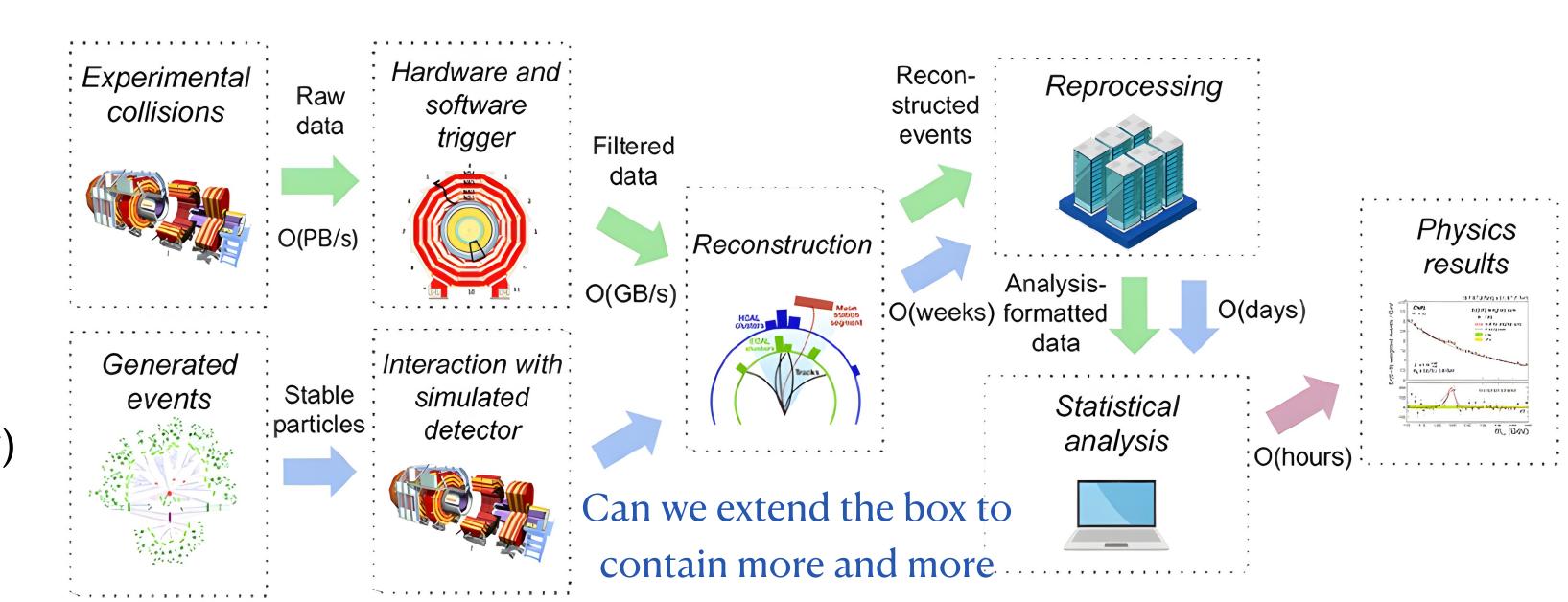


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Fully supervised model will always be focused only on the loss function tasks

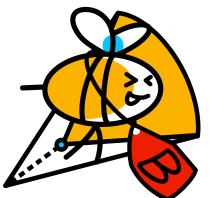
Need to go to unsupervised for self discover:

- Fully understand and discover underlying properties
- One single large model (Jet/CMS GPT) you can fine-tune for any downstream tasks
- Probe on data: get rid of most of the mismodeling?

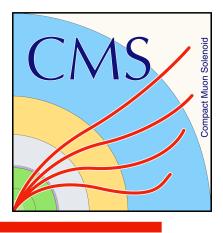


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### Towards the unsupervised world model



Joint-Embedding Predictive Architecture (JEPA):

Learn by predicting representations, not raw features

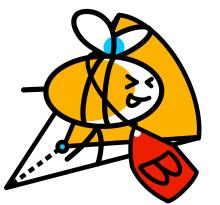
- Mask jet subregions: predict their latent embeddings from remaining context
- Train with MSE loss in embedding space

#### Advantages for HEP:

- Learns physics-informed representations automatically
- More robust than constituent-level prediction

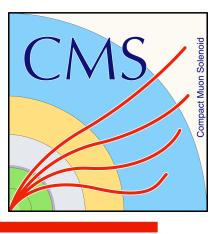
Cons: rely on a predictor bias

- How can you make this reliable for HEP?
- Can you get rid of the bias and avoid human-level knowledge intervention



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### Towards the unsupervised world model

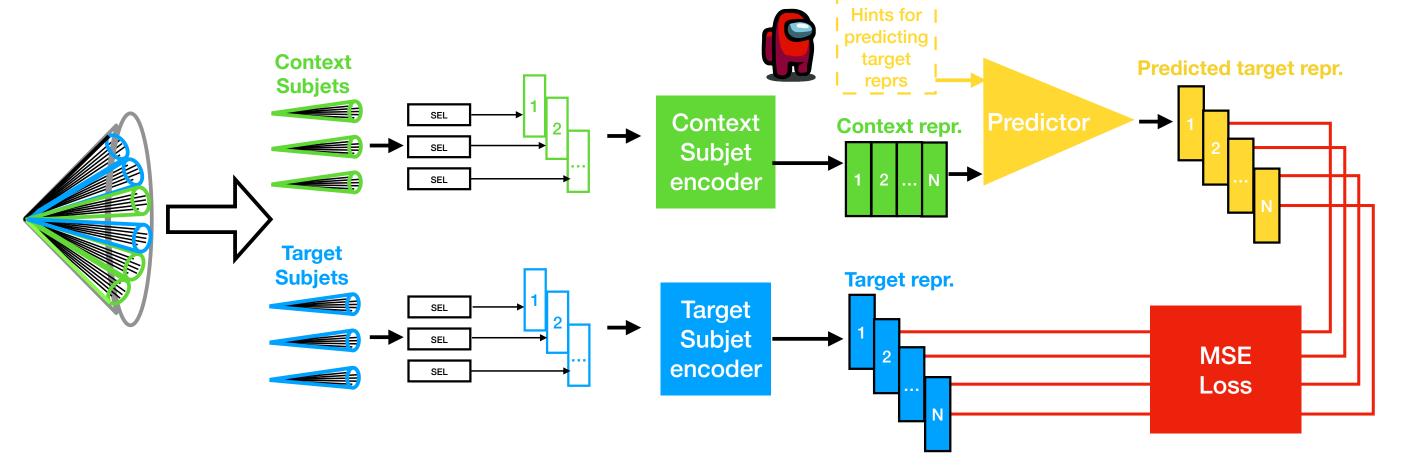


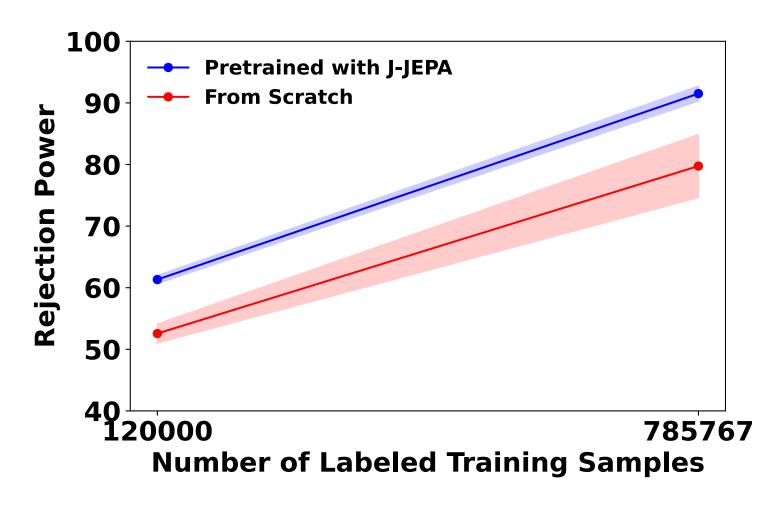
**50** 

#### Advantages for HEP:

- Learns physics-informed representations automatically
- No labelling needed: can we achieve a training on data?
- Single pre-trained model: fine-tune for multiple tasks
- More robust than constituent-level prediction

First JEPA attempts in HEP: <u>2412.05333</u> and <u>2502.03933</u>







# Summary



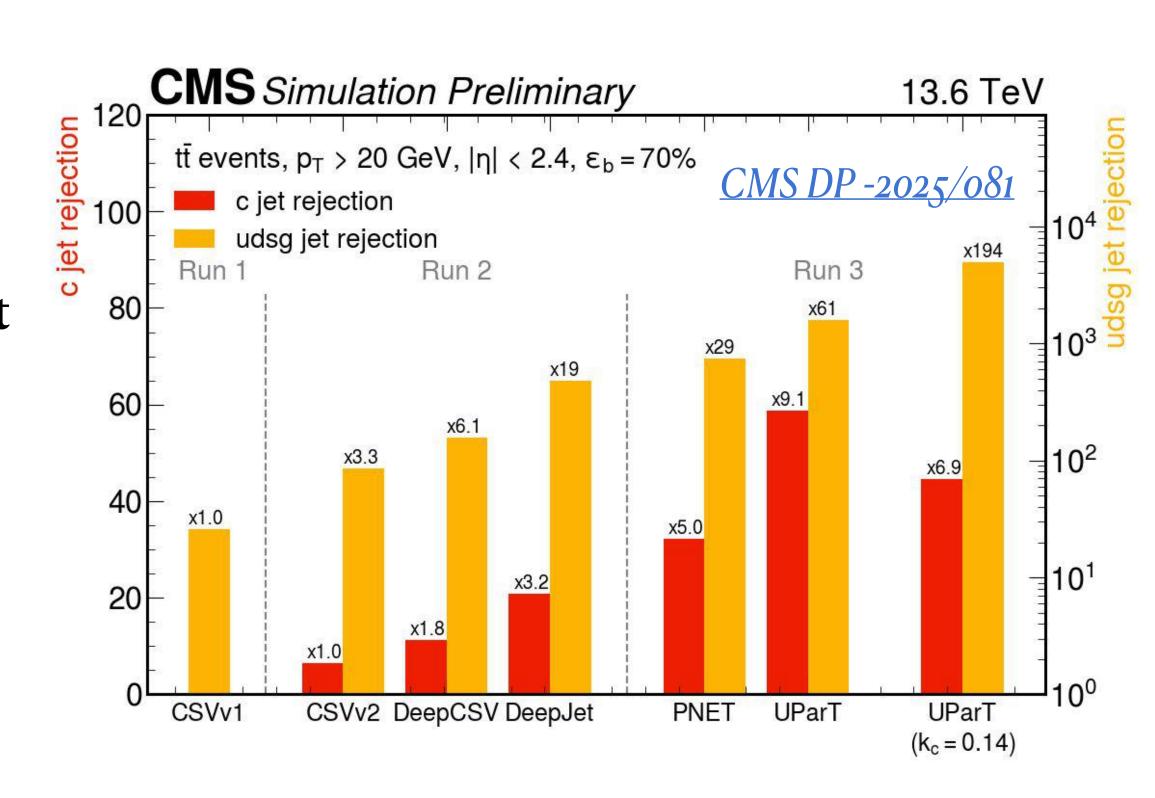
Deep learning has revolutionized jet algorithms in HEP:

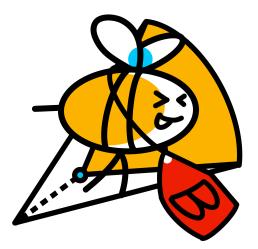
- Evolved from handcrafted features to sophisticated DNN architectures.
- Growing field with still a lot to do

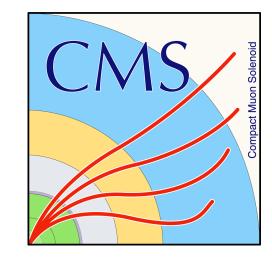
The Unified Particle Transformer (UParT) represents a significant milestone, achieving up to a factor 194 improvement in background rejection compared to Run 1 taggers

#### Key achievements:

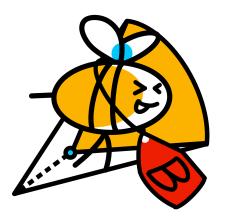
- First s-tagging capability at the LHC
- Robust adversarial training (R-NGM) attempting to minimized data/MC disagreement
- State-of-the-art performance across most tagging tasks
- Demonstrated scaling laws with potential for further improvement



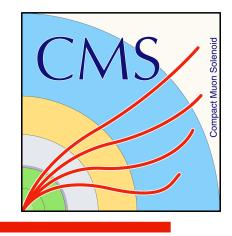




# Encyclo-dia

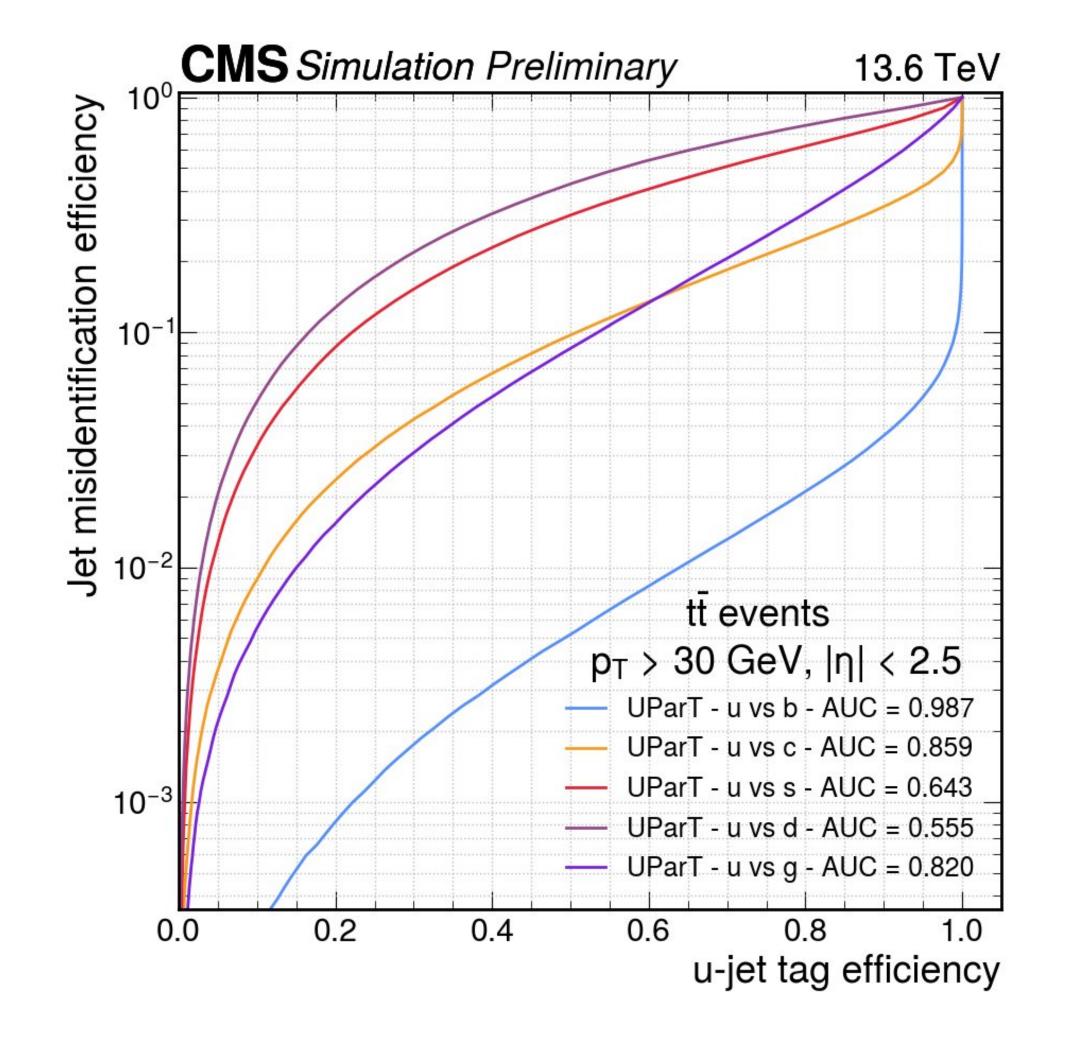


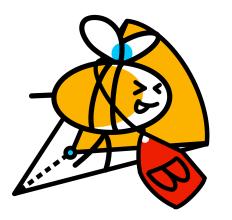
# UvsD tagging



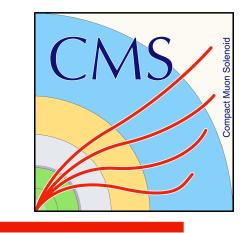
**53** 

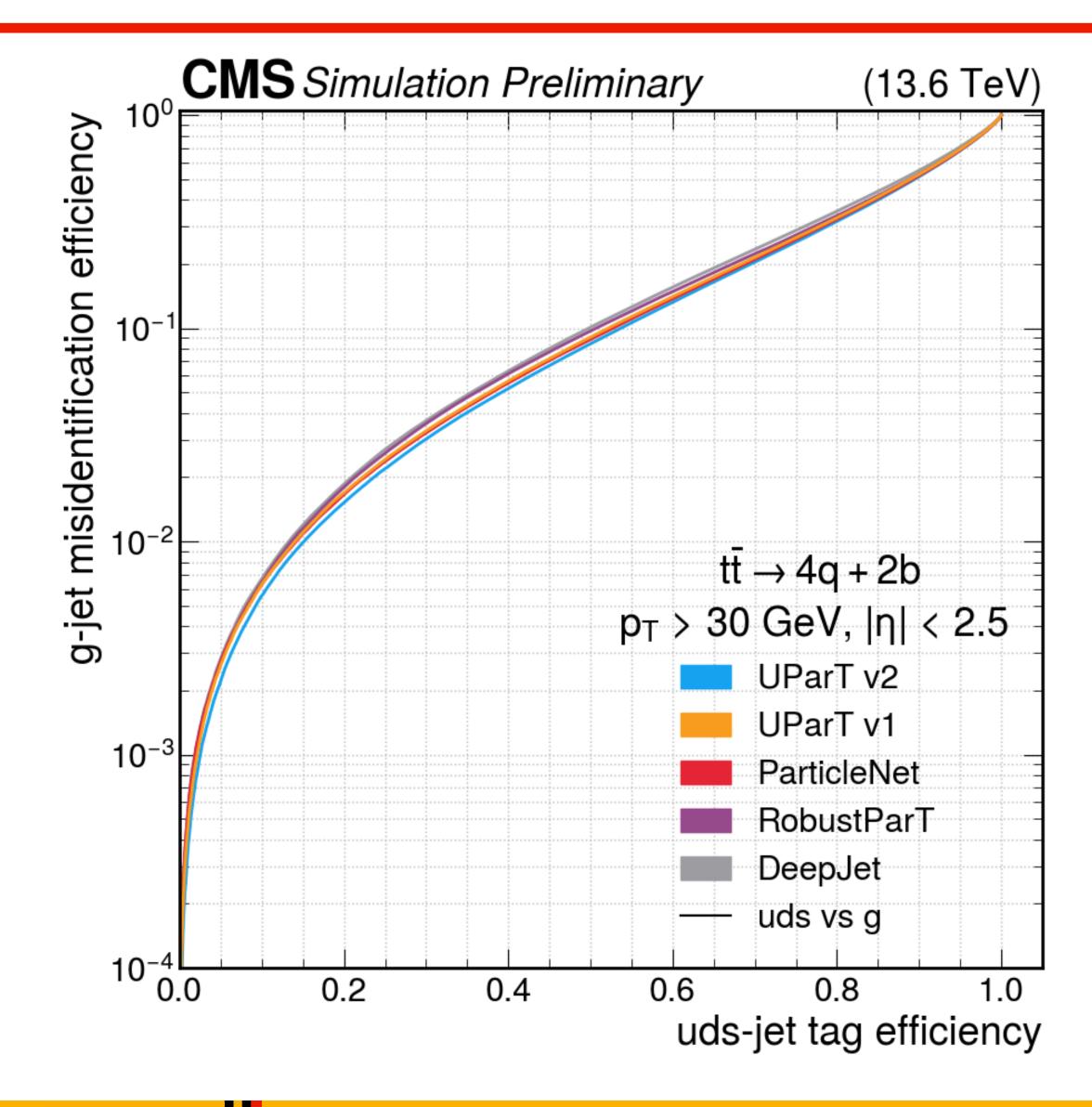






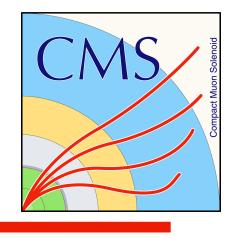
# QG tagging

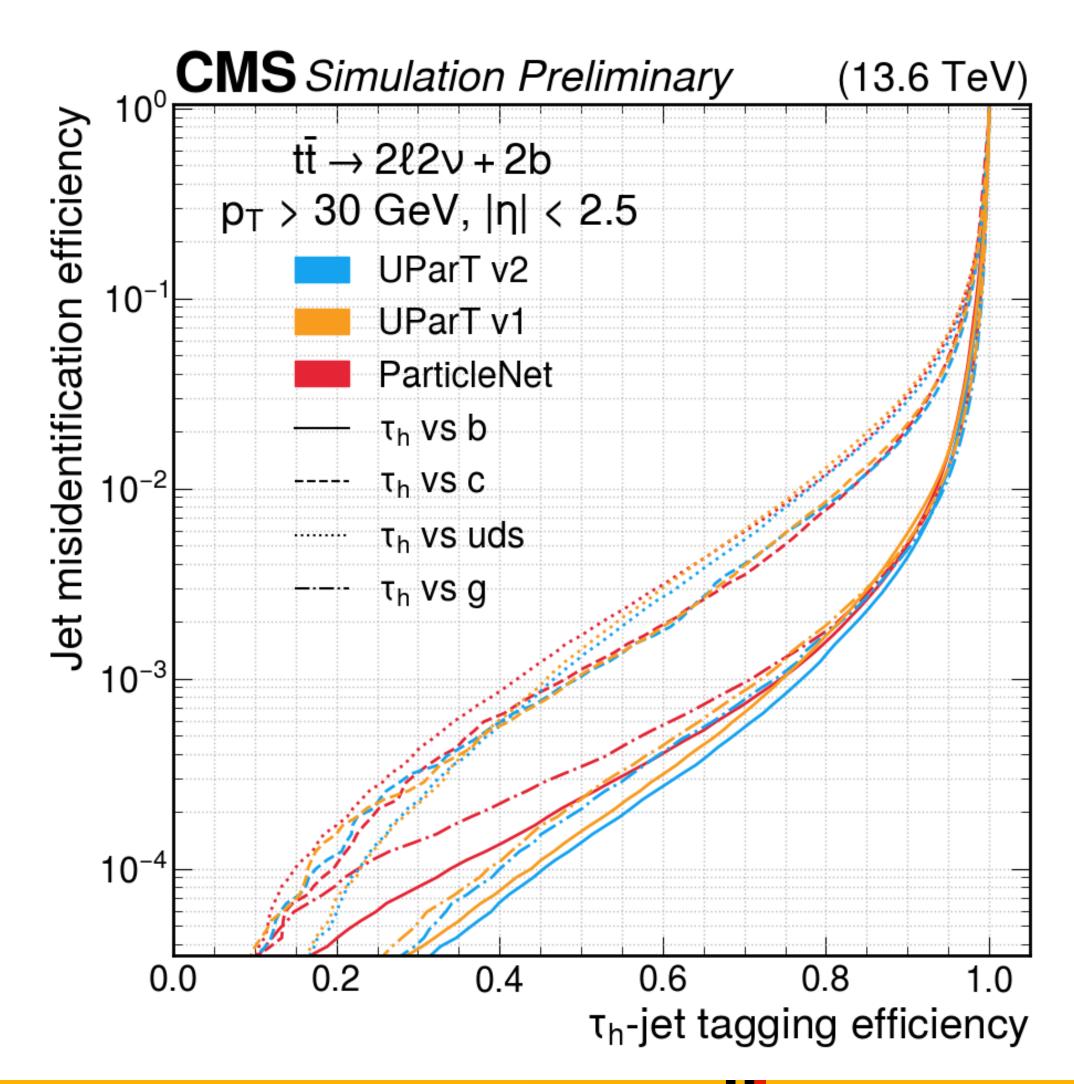


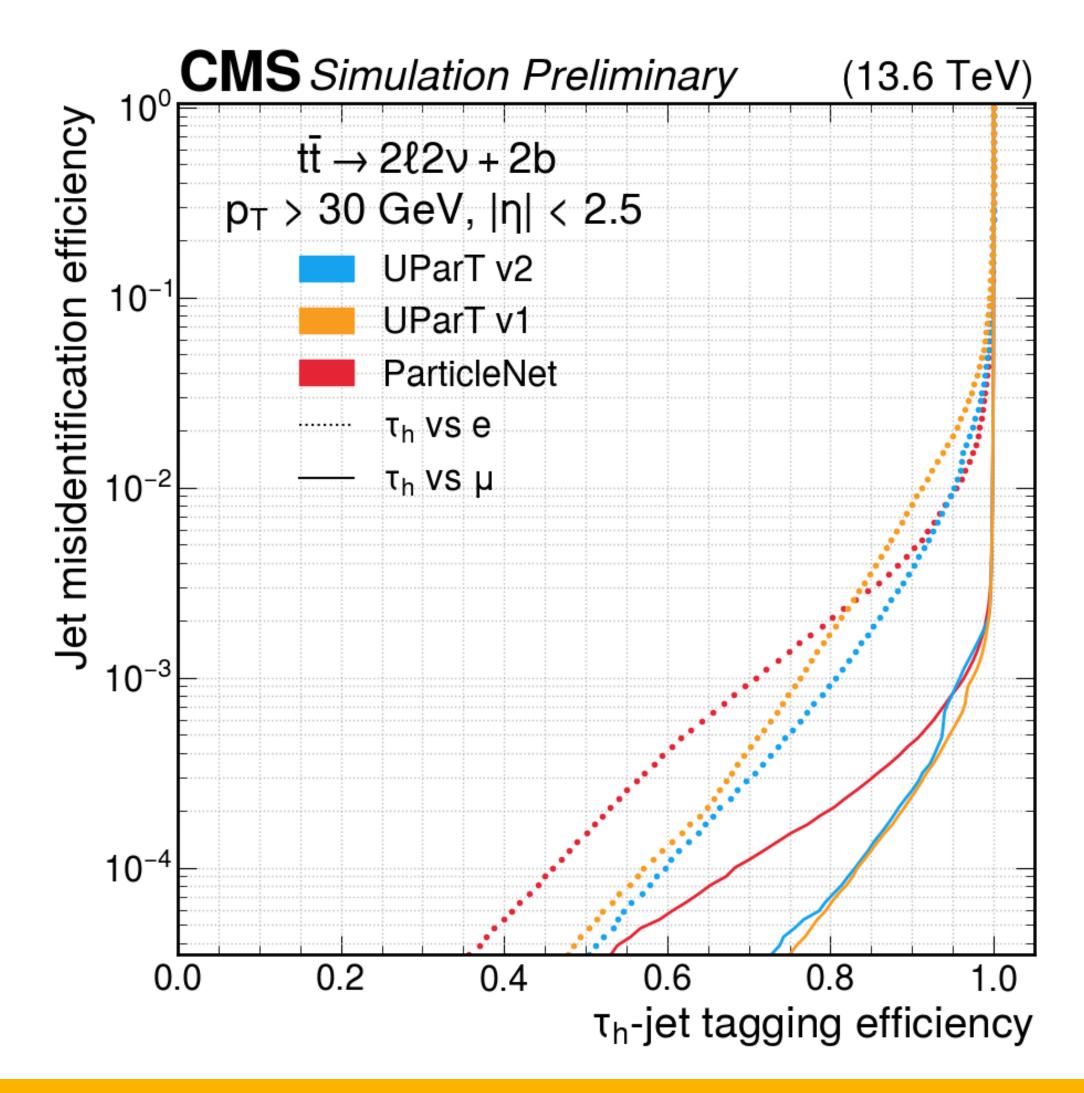




## Ttagging

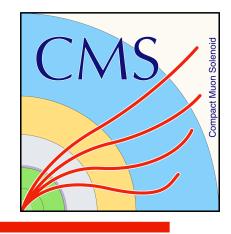


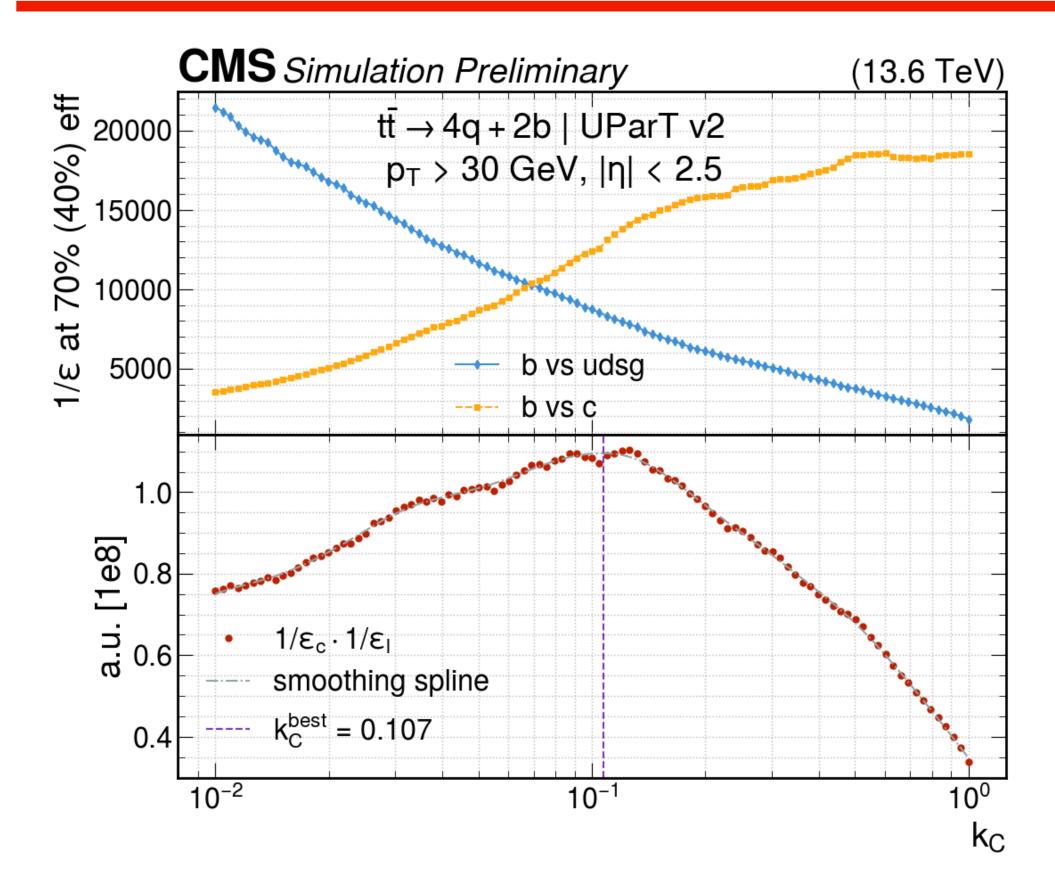




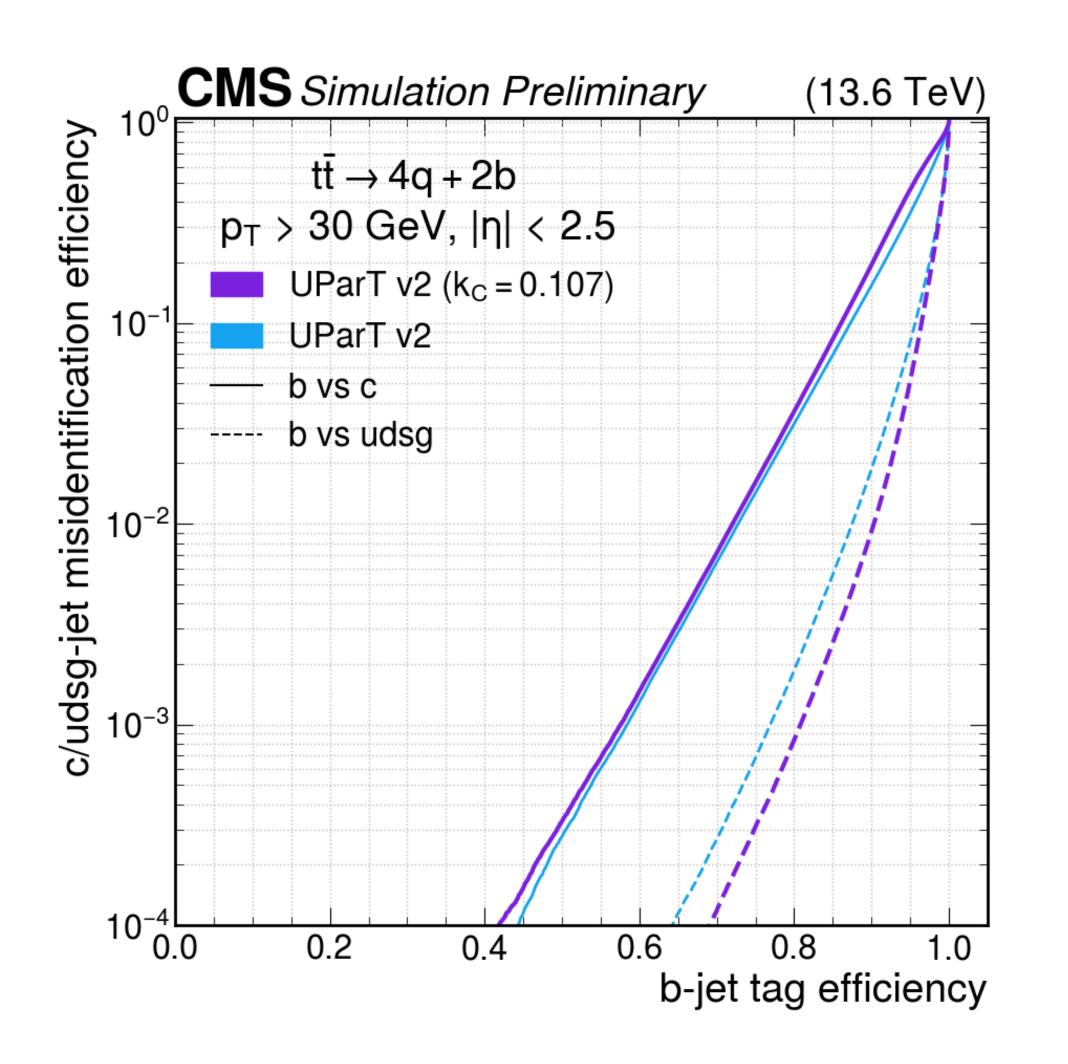


# Weighted b-tagging





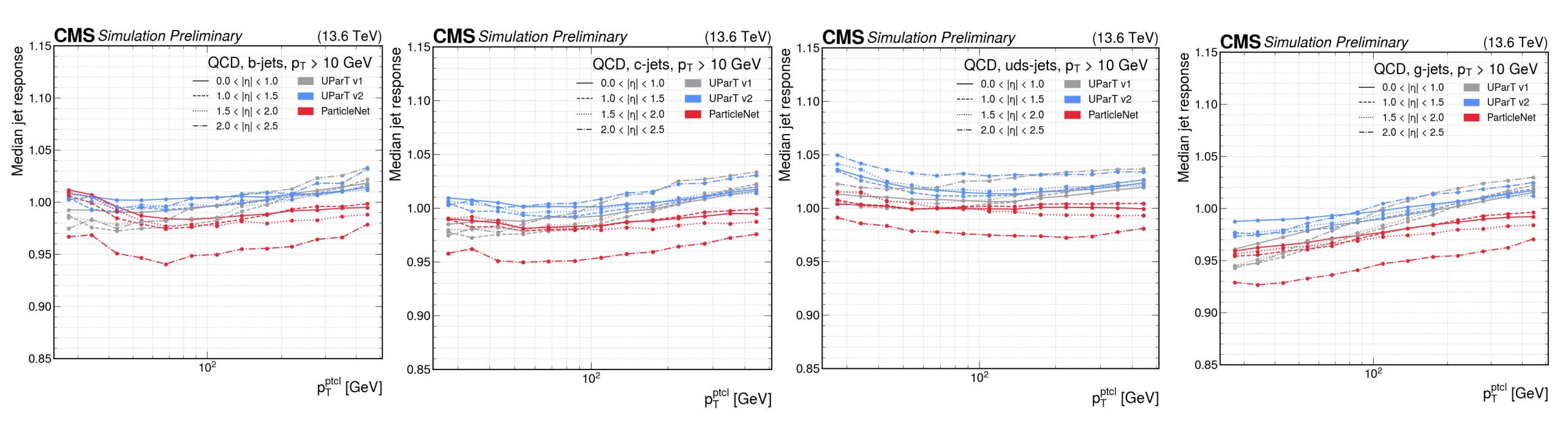
$$BvsAll weighted = \frac{prob(b)}{k_c \cdot prob(c) + (1 - k_c) \cdot prob(udsg)}$$





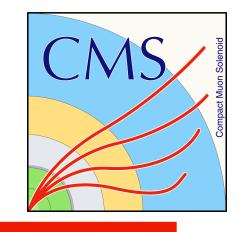
# Jet regression



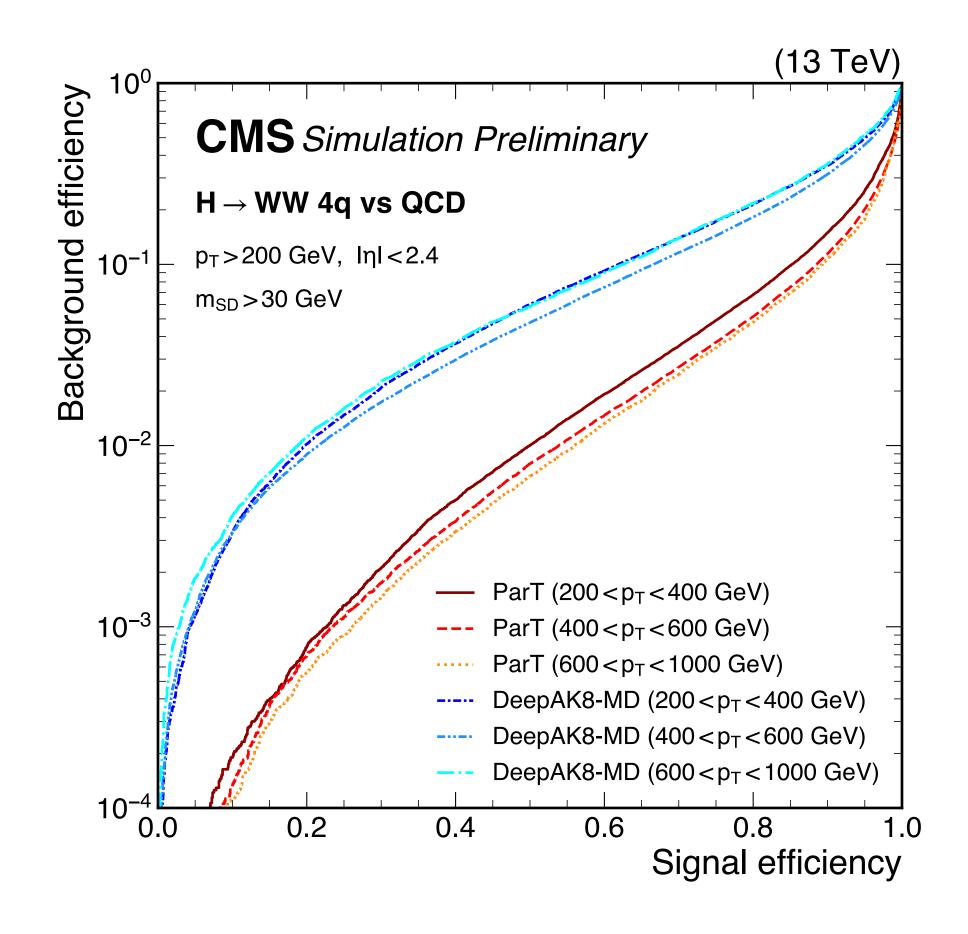




### GloParT v1



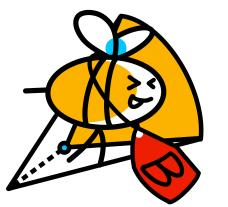
Process	Final state		Flavor	# of classes	a
H→WW (full-hadronic)	qqqq qqq	$\otimes$	0c / 1c / 2c	3 3	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
H→WW (semi-leptonic)	$rac{e  u qq}{\mu  u qq}$ $ au_e  u qq$ $ au_\mu  u qq$ $ au_\mu  u qq$ $ au_h  u qq$	$\otimes$	$0\mathrm{c}\ /\ 1\mathrm{c}$	2 2 2 2 2	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
Н→qq		$\otimes$	$\begin{array}{c} \mathrm{bb} \\ \mathrm{cc} \\ \mathrm{ss} \\ \mathrm{qq} \ (\mathrm{q}{=}\mathrm{u}/\mathrm{d}) \end{array}$	1 1 1 1	$H \longrightarrow q \over \bar{q}$
Η→ττ	$ au_{ m e}  au_{ m h}$ $ au_{ m \mu}  au_{ m h}$ $ au_{ m h}  au_{ m h}$			1 1 1	$H$ $( au_\ell)$ $ au_h$
t→bW (hadronic)	bqq bq	$\otimes$	$1\mathrm{b}+0\mathrm{c}\ /\ 1\mathrm{c}$	2 2	$t \longrightarrow q \qquad \qquad \bar{q} \qquad \bar{q}$
t→bW (leptonic)	bev $b\mu u$ $b au_e u$ $b au_\mu u$ $b au_h u$	$\otimes$	1b	1 1 1 1 1	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
$\operatorname{QCD}$			b bb c c cc others (light)	1 1 1 1 1	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$



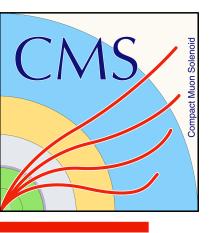
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### Unsupervised world model: autoregression

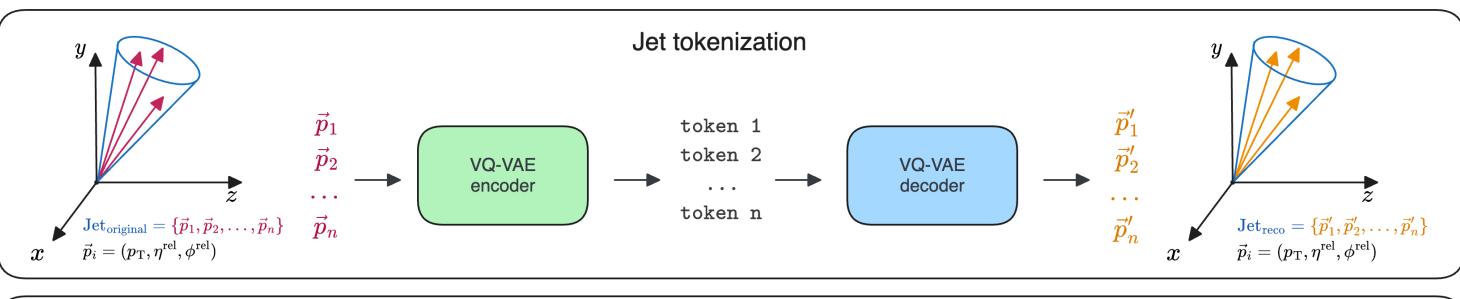


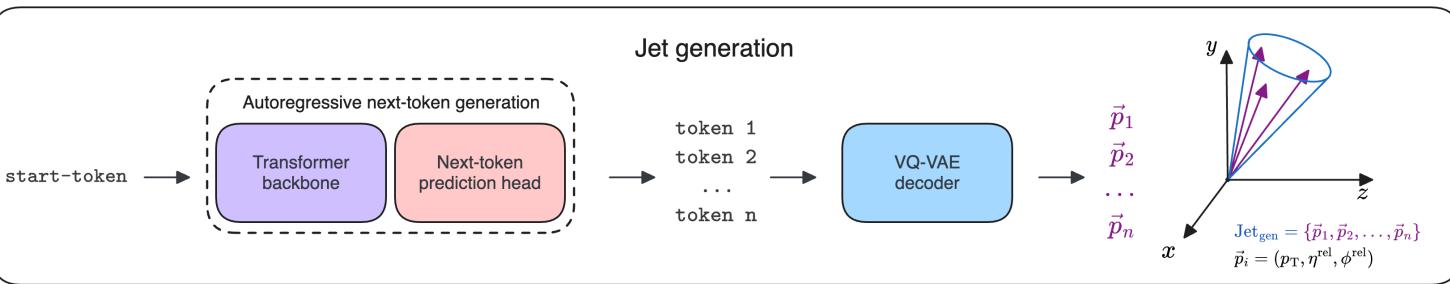
**59** 

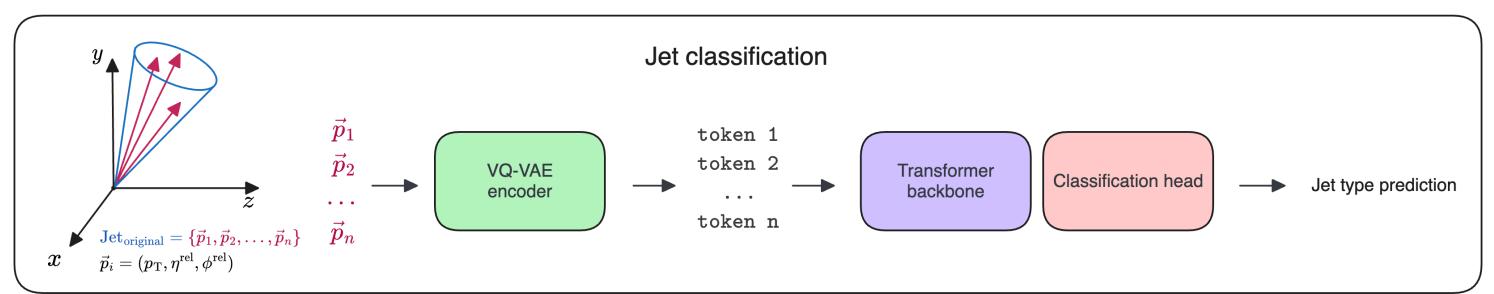
Consider the jet as a sequence:

- Create a tokenizer (constituent to latent space compression)
- Try to predict the next token (constituent)

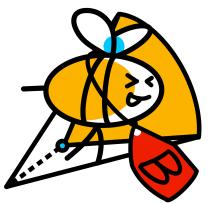
Example: <u>OmniJet-α</u>



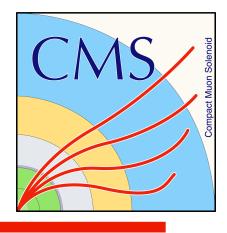




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### Unsupervised world model: masked modeling

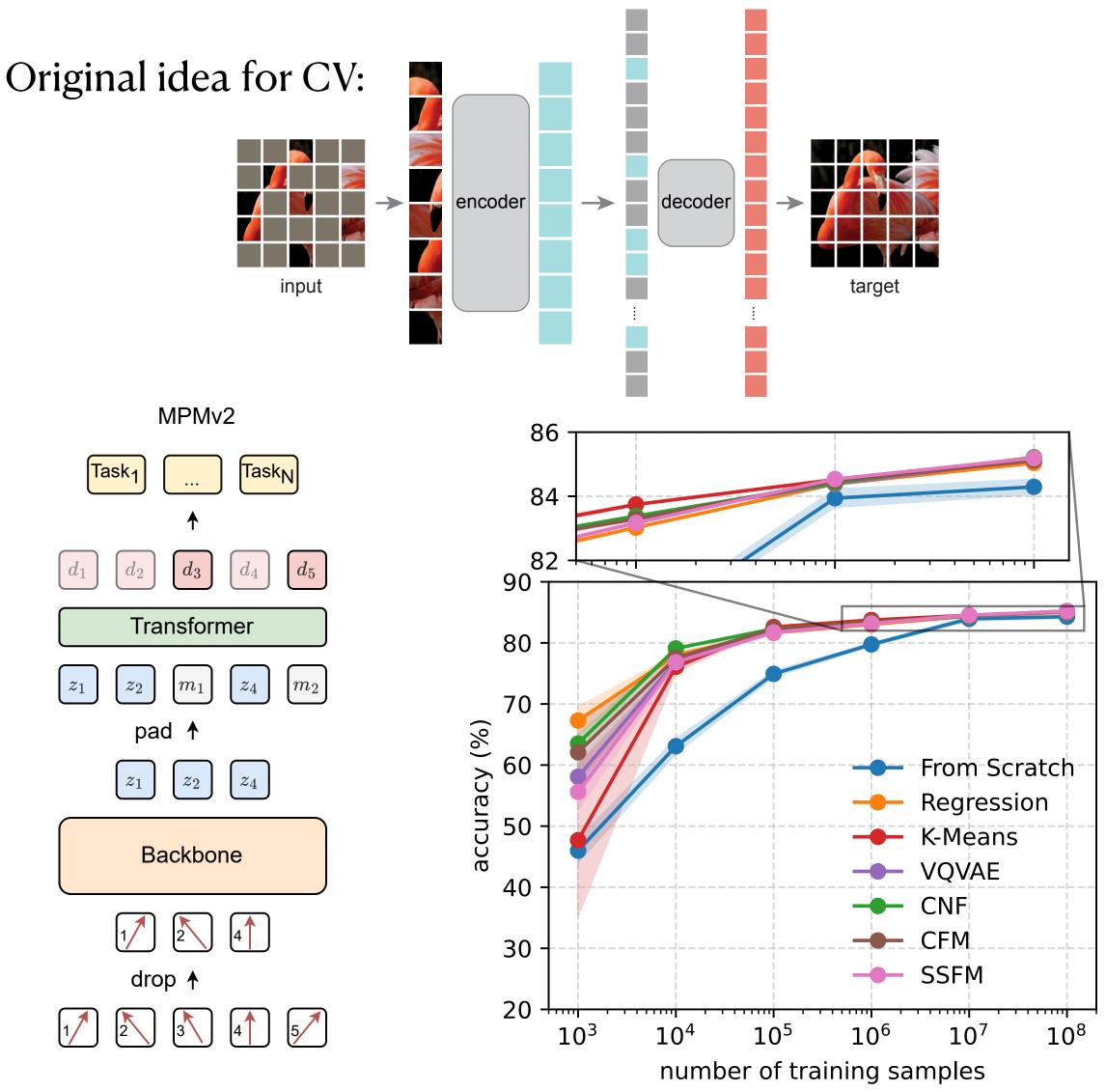


60

Masked Particle Modeling is similar to Masked Autoencoder:

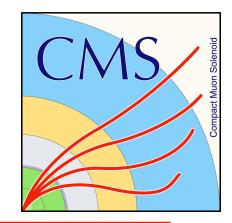
- No discrete tokenization
- Assumed Masking and Reconstructing the missing patches is possible for a jet

Example: MPMv1 and MPMv2

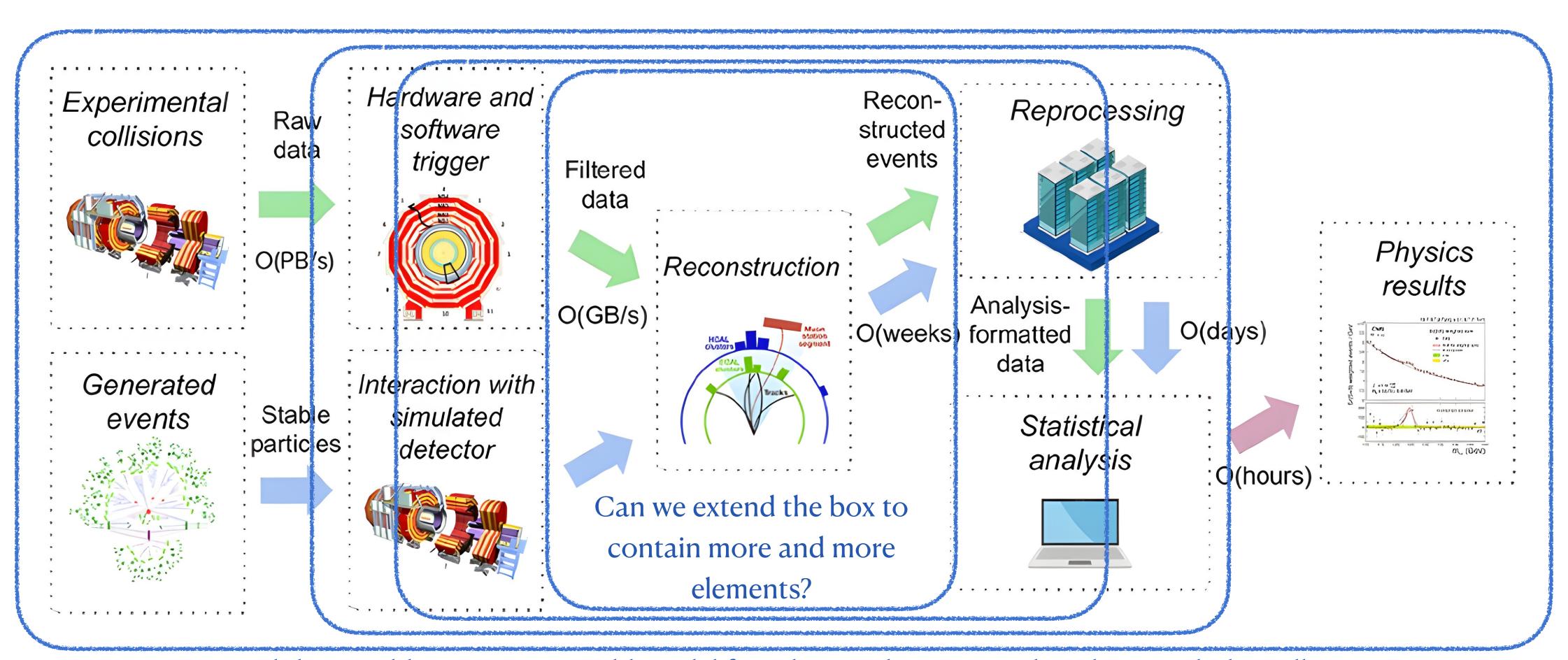




# Beyond the jet itself



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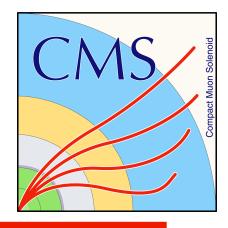


Beyond this: could we create a world model from hits to the statistical analysis (including all the tracking, calorimetry, PF, vertexing, etc)? On data and/or simulations?

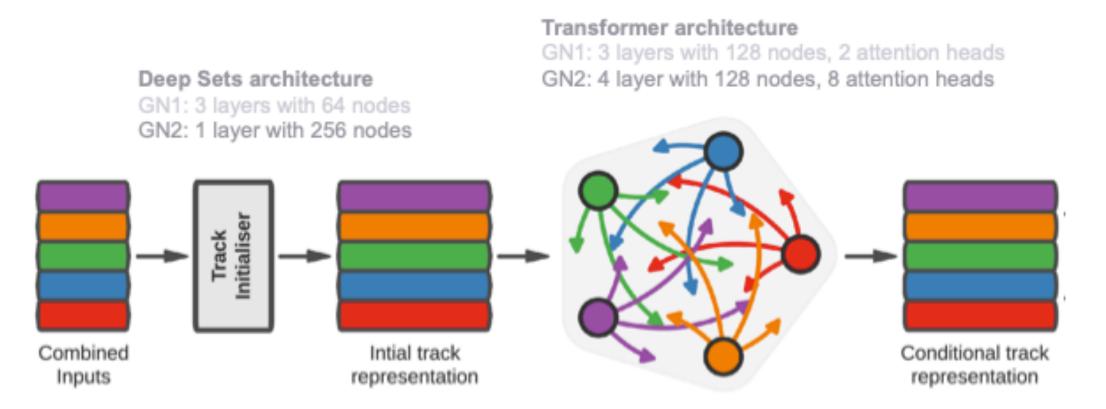
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# Training time



#### **GN2** algorithm structure



**GN2** is a multi-modal and multi-task algorithm based on transformer architecture ("Pre-LN Transformer") w/ about 2.6M parameters trained on mixture of ttbar and Z' jets.

Auxiliary tasks improve training convergence and enhance overall performance. Training with <a href="OneCycleLR">OneCycleLR</a>.

Trainings run for 300M jets with 1 NVIDIA A100 GPU

→ 4.8 hours / epoch. Software for training is "salt".

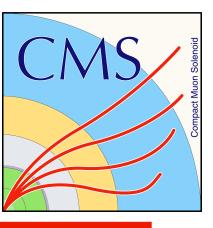
	Size of model	Training time	Dataset size	# of GPUs
ATLAS GN2	2.6 M	~ week	300 M	4
CMS UParT	2 M	1.5 days	30 M	1
ATLAS GN3	12 M	~ 2 weeks	410 M	4
CMS UParTv2	5.7 M	3 days	70 M	1

FTAG algorithms in ATLAS

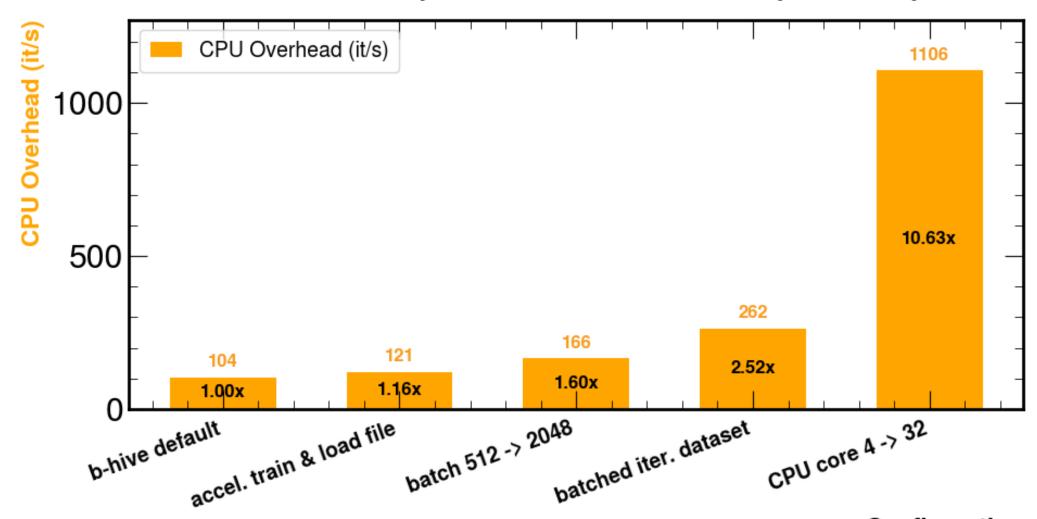
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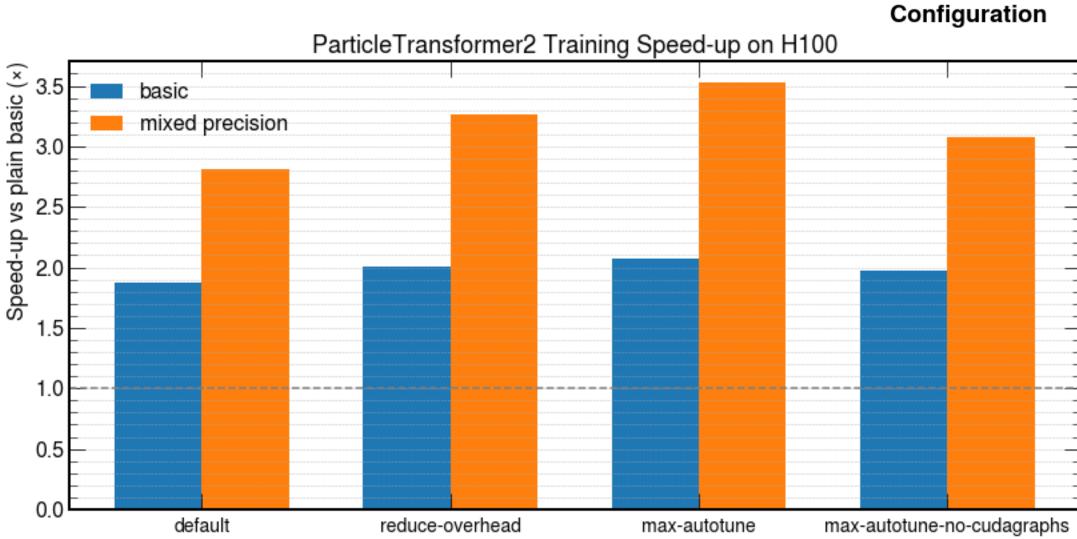


# Training time: b-hive benchmark

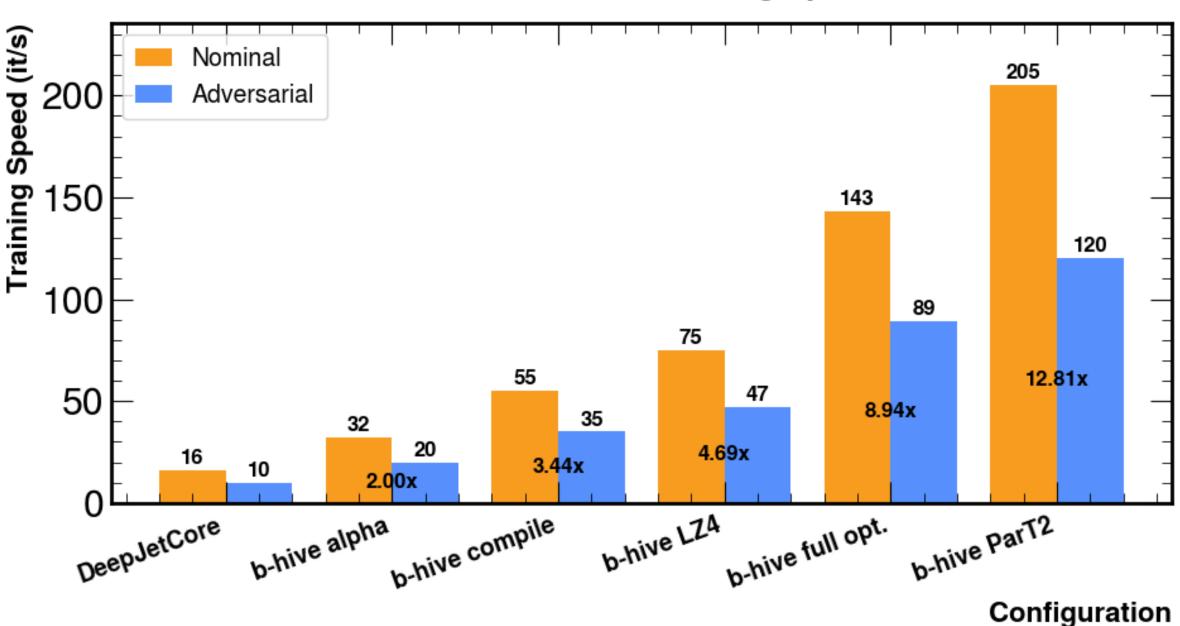


#### Performance Comparison: CPU Overhead & Speed Multiplier





#### **Evolution of the Training Speed**



Training speed of a default ParT model (3+1 attention

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