

Gravitational Wave Project

“Matched filtering”

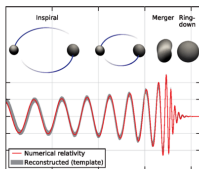
Archisman Ghosh

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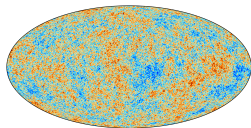
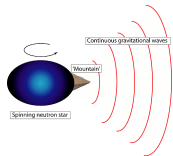
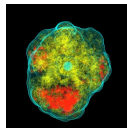
BND Graduate School 2024

Blankenberge, 2024 Sep 02-12

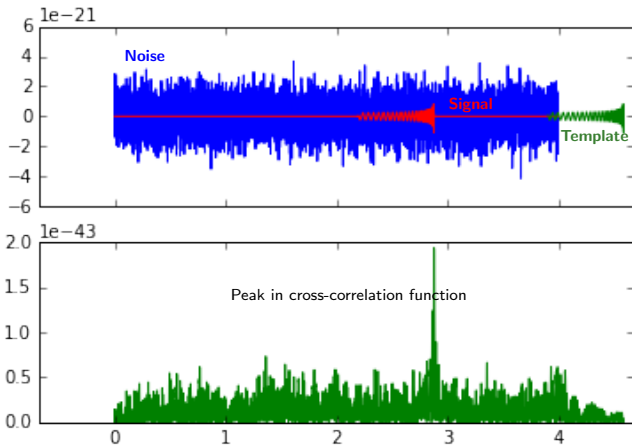
Gravitational-wave sources



	Modelled	Unmodelled
Transient	<p>Compact binary coalescences</p> <p>NS-NS, NS-BH, BBH</p>	<p>Bursts</p> <p>Supernova explosions</p>
Persistent	<p>Continuous waves</p> <p>Spinning deformed NS</p>	<p>Stochastic background</p> <p>Astrophysical + Cosmological</p>



Matched filtering



In this project ...

- Code up a simple matched filtering algorithm
 - Newtonian chirp** waveform
 - Gaussian **white** noise
- Search for a “fake” signal (with above assumptions)
 - When?? [time] How heavy?? [mass]
- Look at stretches of LIGO-Virgo-KAGRA data (gwpv)
 - Determine its noise properties
- Try to generalize above algorithm for real data analysis
 - Discuss complications

Pros and cons ...

Project likely on the easier side :)

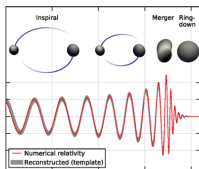
In line with the GW lectures by Elena Cuoco :)

Limited help available until until the very end :(

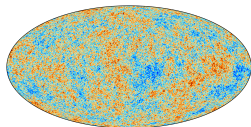
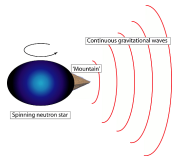
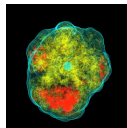
Python, SciPy, conda (gwpv) ... | cluster / laptop

Reference slides

Gravitational-wave sources



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Gravitational-wave data analysis

Typically signal buried in noise significantly louder than itself.

In order to search for / study any signal,
one needs a thorough understanding of the detector noise.

Stationary Gaussian noise

Detector noise is **random**: detector output in absence of signal is a random number at every instant of time.

Stationary?

Its **statistical properties** do not change over time!

Caveat: they do!

Stationary Gaussian noise

Correlation of noise with itself at an earlier (or later) time

$$\langle n(t)n(t+\tau) \rangle \equiv \frac{1}{T} \int_{-T/2}^{T/2} dt n(t) n(t-\tau) = \kappa(\tau)$$

is a such a statistical property | “ergodicity”

In Fourier space

power spectral density

$$\langle \tilde{n}(f)\tilde{n}^*(f') \rangle = S_n(f)\delta(f-f'), \quad \text{where} \quad S_n(f) \equiv \int_{-\infty}^{\infty} dt \kappa(t) e^{i2\pi ft}$$

$\kappa(\tau) = \kappa(-\tau) \Rightarrow S_n(f)$ is real

dimensions of **time**

unit: Hz^{-1}

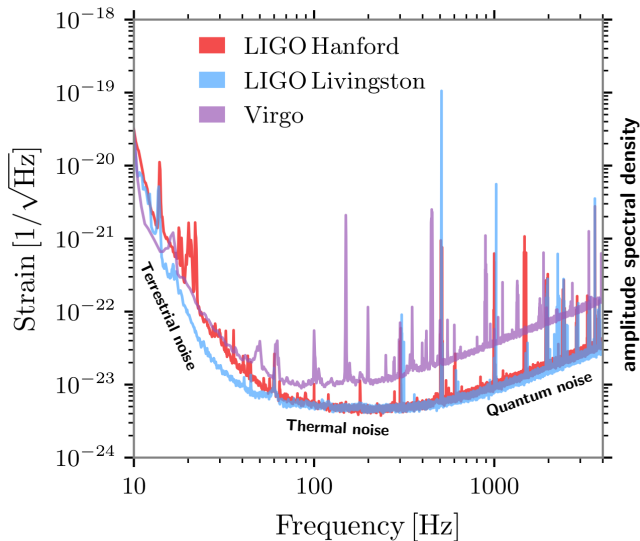
Stationary Gaussian noise

$S_n(f) = \text{constant}$: white noise

$S_n(f) \propto \frac{1}{f}$: flicker noise

$S_n(f) \propto \frac{1}{f^2}$: random walk

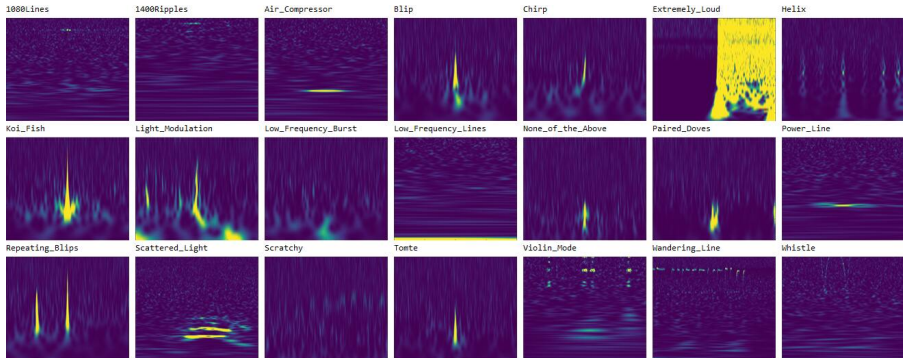
Gravitational-wave detector noise



Non-stationary effects

PSD slowly changing with time

transient “glitches”



Searching for modelled signal in detector data

detector data = possible signal + noise: $x(t) = h(t - t_{arr}) + n(t)$

Correlation of template $q(t)$ with detector output.

$$c(\tau) \equiv \int_{-\infty}^{\infty} dt x(t) q(t + \tau)$$

lag τ : effectively concentrates all information in signal in one place

optimal filter $q(t)$ maximizes $c(\tau)$ when $h(t)$ in detector output

In frequency domain

$$c(\tau) = \int_{-\infty}^{\infty} df \tilde{x}(f) \tilde{q}^*(f) e^{-i2\pi f\tau}$$

Searching for modelled signal in detector data

$$S \equiv \langle c(\tau) \rangle = \int_{-\infty}^{\infty} df \tilde{h}(f) \tilde{q}^*(f) e^{-i2\pi f(\tau - t_{\text{arr}})}$$

$$N^2 \equiv \langle |c - \langle c \rangle|^2 \rangle = \int_{-\infty}^{\infty} df S_n(f) |\tilde{q}(f)|^2$$

Noise-weighted inner product

given $a(t)$, $b(t)$

$$\langle a|b \rangle \equiv 2 \int_0^{\infty} \frac{df}{S_n(f)} \left[\tilde{a}(f) \tilde{b}^*(f) + \tilde{a}^*(f) \tilde{b}(f) \right]$$

Signal-to-noise ratio (SNR):

$$\rho \equiv \frac{S}{N} = \frac{\langle h e^{i2\pi f t} | S_n q \rangle}{\langle S_n q | S_n q \rangle^{\frac{1}{2}}}$$

Searching for modelled signal in detector data

Signal-to-noise ratio (SNR):

$$\rho \equiv \frac{S}{N} = \frac{\langle h e^{i2\pi f t} | S_n q \rangle}{\langle S_n q | S_n q \rangle^{\frac{1}{2}}}$$

Optimal template that maximizes ρ is

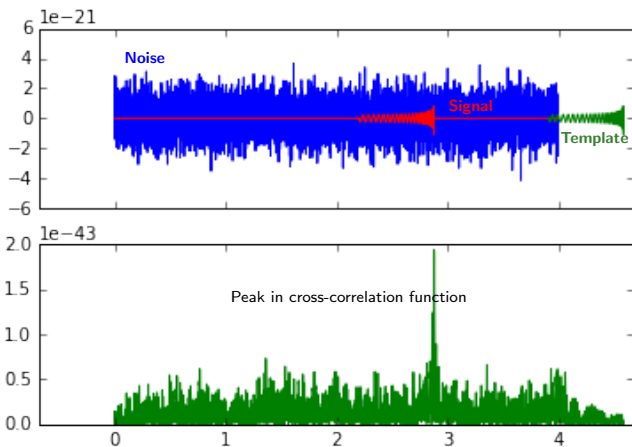
$$\tilde{q}(f) \sim \frac{\tilde{h}(f) e^{i2\pi f(t-t_{\text{arr}})}}{S_n(f)}$$

- SNR maximized when $\tau = t_{\text{arr}}$
- Optimal filter = signal weighted down by PSD (not just copy of signal)

Optimal SNR

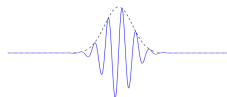
$$\rho_{\text{opt}} = \frac{\langle h|h \rangle}{\langle h|h \rangle^{\frac{1}{2}}} = \langle h|h \rangle^{\frac{1}{2}} = 2 \left[\int_0^{\infty} df \frac{|h(f)|^2}{S_n(f)} \right]^{\frac{1}{2}}$$

Matched filtering

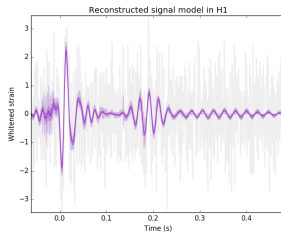
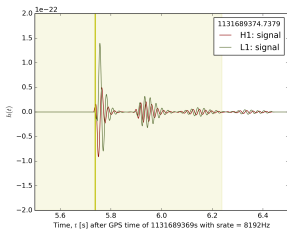


Searching for unmodelled signal in detector data

- Wavelet reconstruction: look for coherent excess power



Morlet-Gabor



Detector strain from an astrophysical signal

- Location of source w.r.t (arms of) the detector: (θ, ϕ)
- Polarization angle: ψ

$$F_+(\theta, \phi, \psi) = -\frac{1}{2}(1 + \cos^2 \theta) \cos 2\phi \cos 2\psi - \cos \theta \sin 2\phi \sin 2\psi \quad (\text{A.10})$$

$$F_\times(\theta, \phi, \psi) = +\frac{1}{2}(1 + \cos^2 \theta) \cos 2\phi \sin 2\psi - \cos \theta \sin 2\phi \cos 2\psi \quad (\text{A.11})$$

These beam pattern functions are shown in Figure A.1.

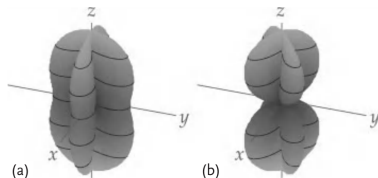


Figure A.1 The beam pattern functions $F_+^2(\theta, \phi, \psi = 0)$ (a) and $F_\times^2(\theta, \phi, \psi = 0)$ (b) for an interferometric gravitational-wave detector with orthogonal arms along the x - and y -axes.

detector strain $h = F_+(\theta, \phi, \psi)h_+(t - t_{\text{arr}}) + F_\times(\theta, \phi, \psi)h_\times(t - t_{\text{arr}})$

Searching for unmodelled signal in detector data

Multiple reconstructions: which reconstruction to choose?

Bayesian Occam's razor: simpler reconstruction; fewer params

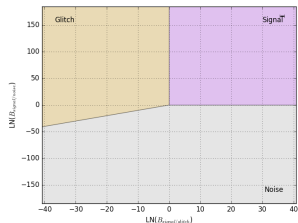
detector strain = signal + glitch + gaussian noise

signal model: $F_{\text{detector}}^+(\theta, \phi, \psi)h_+(t - t_{\text{arr}}) + F_{\text{detector}}^\times(\theta, \phi, \psi)h_\times(t - t_{\text{arr}})$

glitch model: independent sum of wavelets in each detector

noise model: gaussian noise of given (or measured) PSD

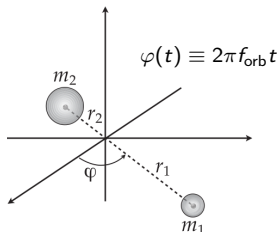
Bonus: **model selection & glitch removal!**



Compact binary coalescences

Two-body problem in GR

$$l_{ij} = \frac{1}{2} \mu r_{12}^2 \begin{bmatrix} 1 + \cos 2\varphi & \sin 2\varphi \\ \sin 2\varphi & 1 - \cos 2\varphi \\ & & 0 \end{bmatrix}$$



reduced mass $\mu \equiv \frac{m_1 m_2}{m_1 + m_2}$

$$h_{ij}^{\text{TT}} \equiv \frac{2G}{c^4 d_L} \ddot{l}_{ij} \Rightarrow \begin{cases} h_+(t) = \frac{2GM\eta}{c^4 d_L} (\pi M f_{\text{GW}})^2 (1 + \cos^2 \iota) \cos 2\varphi(t) \\ h_\times(t) = \frac{4GM\eta}{c^4 d_L} (\pi M f_{\text{GW}})^2 \cos \iota \sin 2\varphi(t) \end{cases}$$

$$M \equiv m_1 + m_2$$

total mass

$$\eta \equiv \frac{m_1 m_2}{M^2}$$

symmetric mass ratio

Note: $f_{\text{GW}} = 2f_{\text{orb}}$

Two-body problem in GR

$$L_{\text{GW}} = \frac{1}{5} \frac{G}{c^5} \langle \ddot{I}_{ij} \ddot{I}^{ij} \rangle = \frac{32}{5} \frac{c^5}{G} \eta^2 \left(\frac{\pi G M f_{\text{GW}}}{c^3} \right)^{10/3}$$

Larmor formula

$$E = \frac{1}{2} \mu (\pi G M f_{\text{GW}})^{2/3}$$

$$L_{\text{GW}} = -\frac{dE}{dt}$$

Newtonian energy

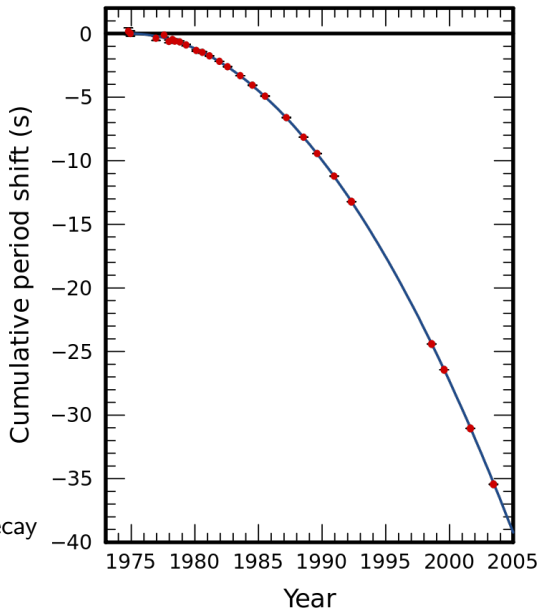
energy conservation

$$\Rightarrow \frac{df_{\text{GW}}}{dt} = \frac{96}{5} \pi^{8/3} \left(\frac{G \mathcal{M}_c}{c^3} \right)^{5/3} f_{\text{GW}}^{11/3}$$

$$\text{with chirp mass } \mathcal{M}_c \equiv \frac{(m_1 m_2)^{3/5}}{(m_1 + m_2)^{1/5}}$$

Leading order of the **post-Newtonian expansion**.

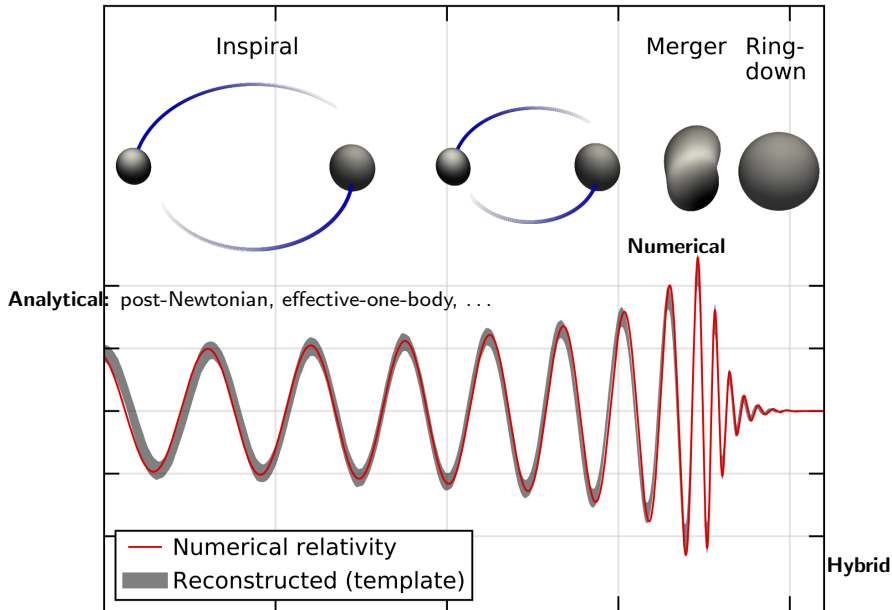
PSR B1913+16 orbital decay
Hulse-Taylor (1975)



Post-Newtonian expansion

Expansion in powers of $\left(\frac{v}{c}\right)^2$

$$\begin{aligned} P_{\text{gw}} = & \frac{32c^5}{5G} \nu^2 x^5 \left\{ 1 + \left(-\frac{1247}{336} - \frac{35}{12} \nu \right) x + 4\pi x^{3/2} \right. \\ & + \left(-\frac{44711}{9072} + \frac{9271}{504} \nu + \frac{65}{18} \nu^2 \right) x^2 \\ & + \left(-\frac{8191}{672} - \frac{583}{24} \nu \right) \pi x^{5/2} \\ & + \left[\frac{6643739519}{69854400} + \frac{16}{3} \pi^2 - \frac{1712}{105} C - \frac{856}{105} \log(16x) \right. \\ & + \left. \left(-\frac{134543}{7776} + \frac{41}{48} \pi^2 \right) \nu - \frac{94403}{3024} \nu^2 - \frac{775}{324} \nu^3 \right] x^3 \\ & \left. + \left(-\frac{16285}{504} + \frac{214745}{1728} \nu + \frac{193385}{3024} \nu^2 \right) \pi x^{7/2} + \mathcal{O}\left(\frac{1}{c^8}\right) \right\} \end{aligned} \quad (5.)$$



Waveform approximants

Post-Newtonian

TaylorT, TaylorF

Hybrid, phenomenological

IMRPhenom, IMRPhenomP, IMRPhenomX

Effective one-body

SEOBNR

reduced-order-model

ROM

Intrinsic parameters

- Component masses, $m_{1,2}$
- Component dimensionless spin angular momenta, $\vec{s}_{1,2}$ $\vec{s} \equiv \frac{\vec{J}}{m^2}$
- Tidal deformability parameters for neutron stars, $\lambda_{1,2}$

NS in binaries deform in gravitational field of companion
deformation depends on NS composition (equation-of-state)
leaves imprint on GW signal (waveform)

- Any residual eccentricity? radiated away Peters & Matthews (1963)

Two polarizations

Dominant (2, 2)-mode to leading order:

$$h_{+}(t) = \frac{2M\eta}{d_L} (\pi M f_{\text{GW}})^2 (1 + \cos^2 \iota) \cos 2\varphi(t)$$

$$h_{\times}(t) = \frac{4M\eta}{d_L} (\pi M f_{\text{GW}})^2 \cos \iota \sin 2\varphi(t)$$

$$M \equiv m_1 + m_2$$

$$\eta \equiv \frac{m_1 m_2}{M^2}$$

- Distance, d_L
- Inclination angle, ι
- Phase at coalescence, ϕ_c
- Time of coalescence, t_c

Antenna beam pattern functions

- Two angles in the sky $(\theta, \phi) \longrightarrow (\alpha, \delta)$, right ascension and declination
- Polarization angle, ψ

$$F_+(\theta, \phi, \psi) = -\frac{1}{2}(1 + \cos^2 \theta) \cos 2\phi \cos 2\psi - \cos \theta \sin 2\phi \sin 2\psi \quad (\text{A.10})$$

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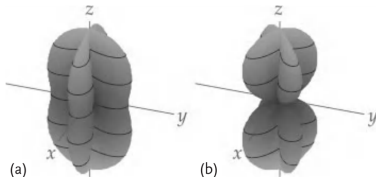


Figure A.1 The beam pattern functions $F_+^2(\theta, \phi, \psi = 0)$ (a) and $F_\times^2(\theta, \phi, \psi = 0)$ (b) for an interferometric gravitational-wave detector with orthogonal arms along the x - and y -axes.

CBC parameters

Intrinsic parameters: $\{m_1, m_2, \vec{s}_1, \vec{s}_2, \lambda_1, \lambda_2, \dots\}$

Extrinsic parameters: $\{\alpha, \delta, d_L, \iota, \psi, \varphi_c, t_c\}$

$$F_{\text{detector}}^+(\theta, \phi, \psi) h_+(t - t_{\text{arr}}) + F_{\text{detector}}^\times(\theta, \phi, \psi) h_\times(t - t_{\text{arr}})$$

masses of the components

spin angular momenta

tidal deformability for neutron stars

eccentricity

distance d_L

sky position α, δ

euler angles $\{\theta, \phi, \psi\} = \text{fn.}(\{\iota, \psi, \varphi_c\})$

time of arrival

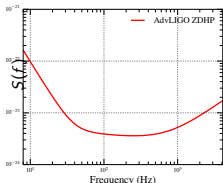
Bayesian parameter estimation

Obtain the **posterior** probability distribution on the parameter space given the data and a **prior** probability distribution.

$$\text{Posterior}(\vec{\Omega}|\text{data}, I) = \frac{\text{Prior}(\vec{\Omega}|I) \mathcal{L}(\text{data}|\vec{\Omega}, I)}{\text{Evidence}(\text{data}, I)}$$

$$\vec{\Omega} = \{ \mathcal{M}, q, \vec{s}_1, \vec{s}_2, \lambda_1, \lambda_2, \alpha, \sin \delta, d_L, \cos \iota, \psi, \varphi_c, t_c \}$$

$$\begin{aligned} \mathcal{L}(\text{data}|\vec{\Omega}, I) &= P(\text{data}|\text{signal}(\vec{\Omega}), I) && \text{data} = \text{signal}(\vec{\Omega}) + \text{noise}, n \\ &= \exp \left(-\frac{1}{2} \left\langle \text{data} - \text{signal}(\vec{\Omega}) | \text{data} - \text{signal}(\vec{\Omega}) \right\rangle \right) \end{aligned}$$



$$\langle n|n \rangle \equiv \int df \frac{\|n(f)\|^2}{S^2(f)}$$

Gaussian noise

Bayesian parameter inference algorithms

Markov Chain Monte Carlo (MCMC)

Metropolis-Hastings

Parallel tempering (MCMC)

Nested sampling

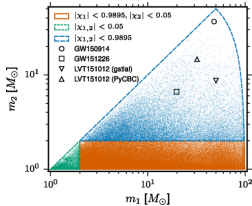
1024 live points

Data analysis workflow of CBCs

Searches

generate (real-time) triggers

LVC: Abbott+, PRX 6, 041015 (2016)



Implications

fundamental physics, astrophysics, cosmology

Parameter estimation

rigorous analysis of data around trigger

Low latency

quick

BayesSTAR

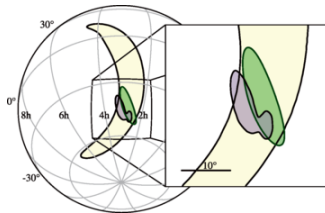
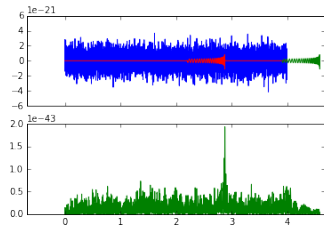
RapidPE

High latency

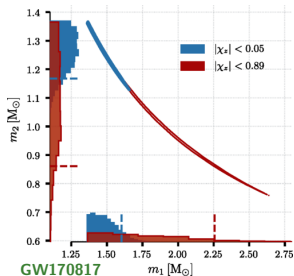
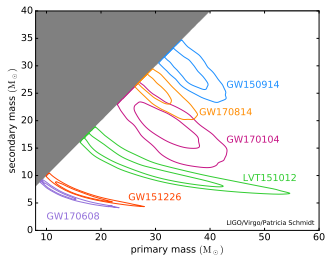
accurate

LALINFERENCE

BILBY



Parameter estimation results



LVC: Abbott+, PRL 119, 161101 (2017)

